

13.1 Vector Functions and Space Curves

If a particle is moving through space during a given time interval, say $t \in I = [t_0, t_1]$, then the position of the particle at time $t \in I$ is

$$\begin{aligned} P &= P(x, y, z) \\ &= P(f(t), g(t), h(t)) \end{aligned}$$

That is,

$$(1) \quad x = f(t), \quad y = g(t), \quad z = h(t), \quad t \in I$$

Then for each $t \in I$, the points make up the **curve** in space called the particle's **path**. The equations in (1) **parameterize** the curve.

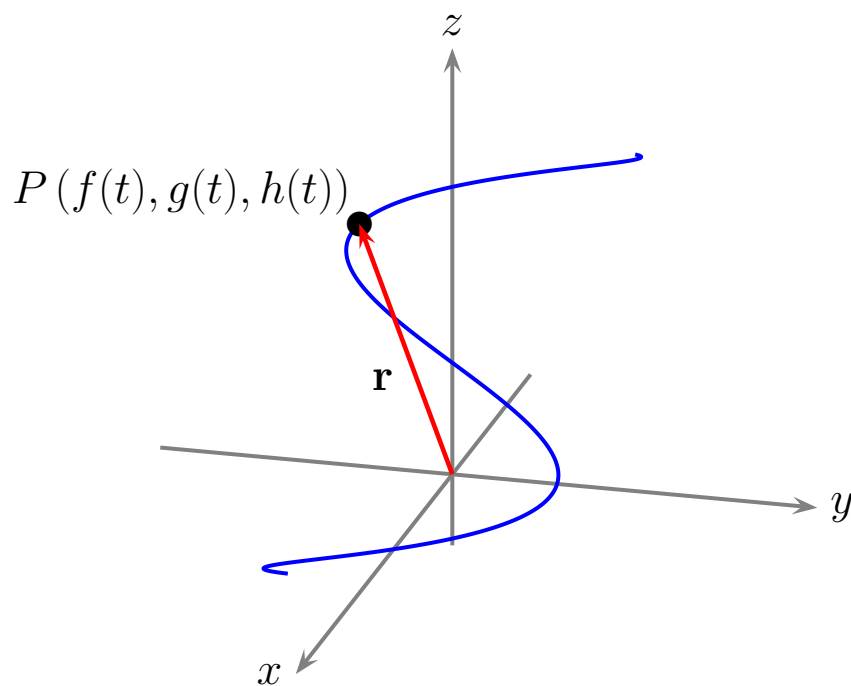
The vector

$$(2) \quad \mathbf{r}(t) = f(t) \mathbf{i} + g(t) \mathbf{j} + h(t) \mathbf{k}$$

is a **position** vector of the particle at time t . And the functions f , g , and h are the **component functions** of \mathbf{r} .

We often refer to the function in (2) as (an example of) a **vector-valued** function. On the other hand, the component functions are examples of **scalar-valued** functions.

Example 1. A Space Curve



We often like to think of $\mathbf{r}(t)$ as the *position vector* of a particle P , traveling along the curve, at time t .

Example 2. At which point(s) does the space curve $\mathbf{r}(t) = 2t \mathbf{i} - (t + t^2) \mathbf{k}$ intersect the paraboloid $z = x^2 + 4y^2$?

Solution:

It might be easier to attack this problem by rewriting the space curve in parametric form. That is,

$$(3) \quad x(t) = 2t, \quad y(t) = 0, \quad z(t) = -t - t^2$$

It is then a bit easier to see that the curve will intersect the surface precisely when $P = P(x(t), y(t), z(t))$ satisfies the equation $z = x^2 + 4y^2$. That is, when

$$z(t) = x(t)^2 + 4y(t)^2$$

So we must solve

$$-t - t^2 = 4t^2 + 0$$

Rearranging, we obtain

$$0 = t(5t + 1)$$

It follows that the curve intersects the surface at $t = 0, -1/5$. From (3) we conclude that points of intersection are $(0, 0, 0)$ and $(-2/5, 0, 4/25)$.

Example 3. Find the parametric equations for the curve that represents the intersection of the surfaces below.

$$(4) \quad 1 = \frac{x^2}{4} + \frac{y^2}{9}$$

$$(5) \quad z = 3 - 2x$$

Solution:

This one's a bit tricky if you forget to parameterize the elliptic cylinder. A (more or less) standard parameterization of (4) is given by

$$(6) \quad \begin{aligned} x(t) &= 2 \cos t \\ y(t) &= 3 \sin t \end{aligned}$$

Now (5) and (6) imply that

$$\begin{aligned} z(t) &= 3 - 2x(t) \\ &= 3 - 4 \cos t \end{aligned}$$

See the blue curve in Figure 1 below.

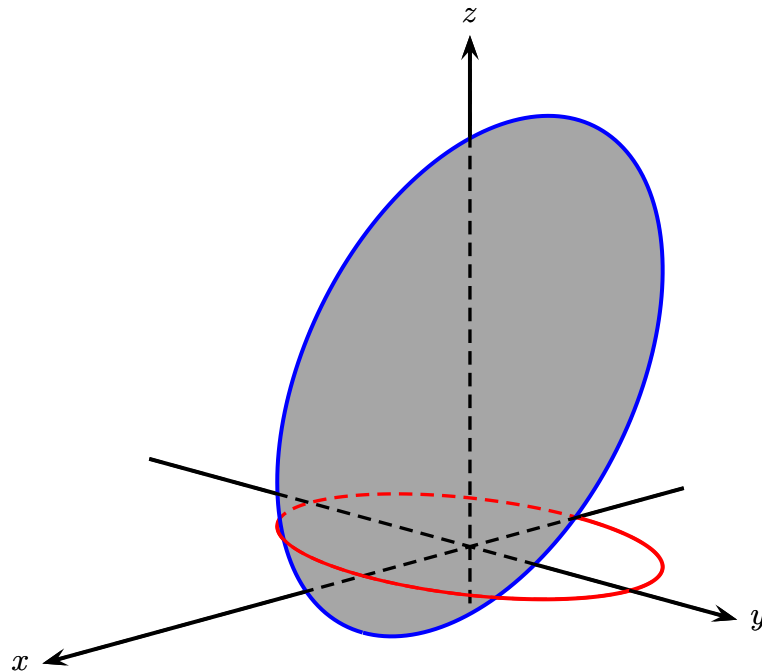


Figure 1: Intersection of Two Surfaces

The above figure requires some explanation. The blue curve is the intersection of the two surfaces. The red curve is the intersection of the elliptical cylinder $36 = 9x^2 + 4y^2$ with the xy -plane. The tilted gray ellipse includes all the points in the plane $z = 3 - 2x$ such that $9x^2 + 4y^2 < 1$. The paraboloid is not shown.

Limits and Continuity

We define the limit of a vector-valued function component-wise. That is

Definition. The Limit of a Vector-Valued Function

Let $\mathbf{r}(t) = f(t)\mathbf{i} + g(t)\mathbf{j} + h(t)\mathbf{k}$ be a vector function and \mathbf{L} be a vector. We say that \mathbf{r} has a limit \mathbf{L} as t approaches t_0 if for every $\epsilon > 0$ there is a $\delta = \delta(\epsilon) > 0$ such that

$$(7) \quad |\mathbf{r}(t) - \mathbf{L}| < \epsilon \text{ whenever } 0 < |t - t_0| < \delta$$

In this case we write

$$(8) \quad \lim_{t \rightarrow t_0} \mathbf{r}(t) = \mathbf{L}$$

Fortunately, we have the following

Proposition 1. Let $\mathbf{L} = L_1\mathbf{i} + L_2\mathbf{j} + L_3\mathbf{k}$. Then (8) holds whenever

$$\lim_{t \rightarrow t_0} f(t) = L_1, \quad \lim_{t \rightarrow t_0} g(t) = L_2, \quad \lim_{t \rightarrow t_0} h(t) = L_3$$

In this case, we write

$$(9) \quad \lim_{t \rightarrow t_0} \mathbf{r}(t) = \left(\lim_{t \rightarrow t_0} f(t) \right) \mathbf{i} + \left(\lim_{t \rightarrow t_0} g(t) \right) \mathbf{j} + \left(\lim_{t \rightarrow t_0} h(t) \right) \mathbf{k}$$

Finally, we have

Definition. Continuity at a Point

A vector-valued function $\mathbf{r}(t)$ is **continuous** at $t = t_0$ if

$$(10) \quad \lim_{t \rightarrow t_0} \mathbf{r}(t) = \mathbf{r}(t_0)$$

The function is called continuous if (10) at every point in its domain.

Remark. By Proposition 1, a vector-valued function is continuous at $t = t_0$ if and only if each of its component functions are.

Example 4. Limits and Continuity of a Space Curve

Let $\mathbf{r}(t) = \cos t \mathbf{i} - 3t^2 \mathbf{j} + \frac{1}{\sin t} \mathbf{k}$.

Then $\mathbf{r}(t)$ is continuous everywhere in its domain since each of its component functions are. What is its domain?