

Multivariable calculus

- MTH132 & 133: $f: R \rightarrow R$

one-dimensional functions

Examples: $y = x^2$, $y = \sin x$, ...

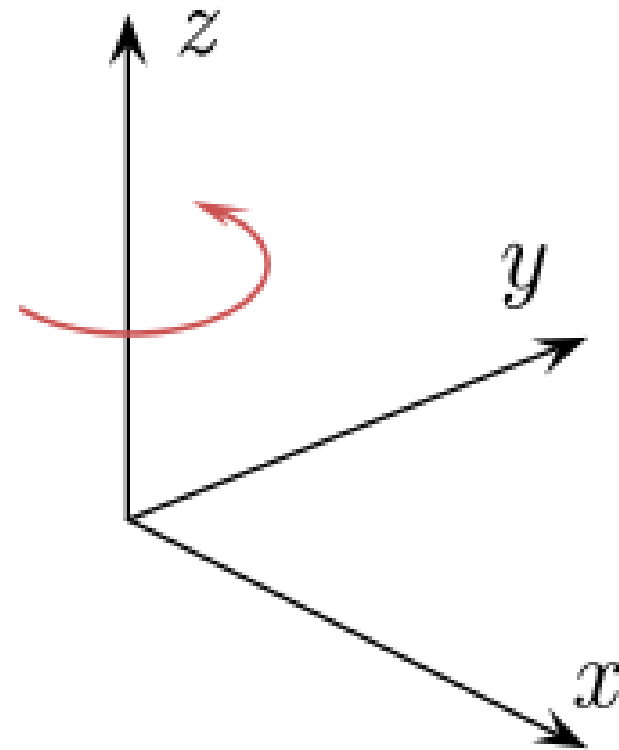
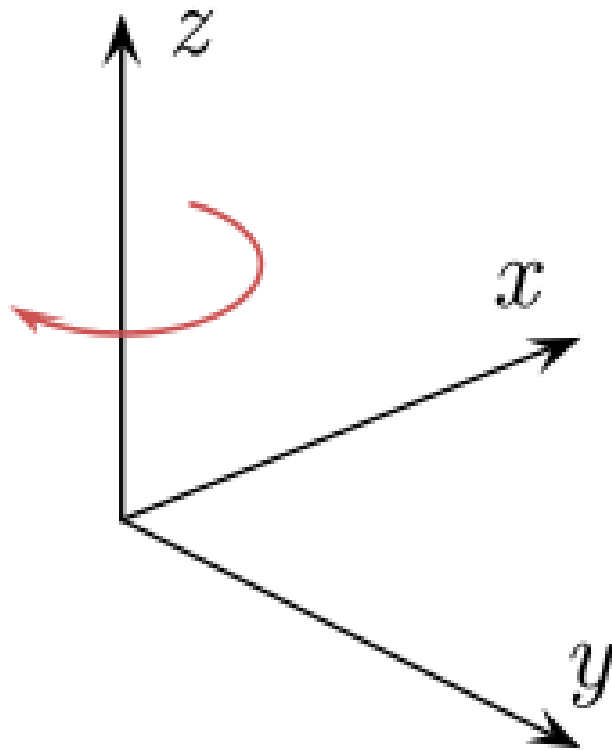
- MTH234: $f: R^2 \rightarrow R$ or $f: R^3 \rightarrow R$

or $f: R \rightarrow R^2$, $R \rightarrow R^3$

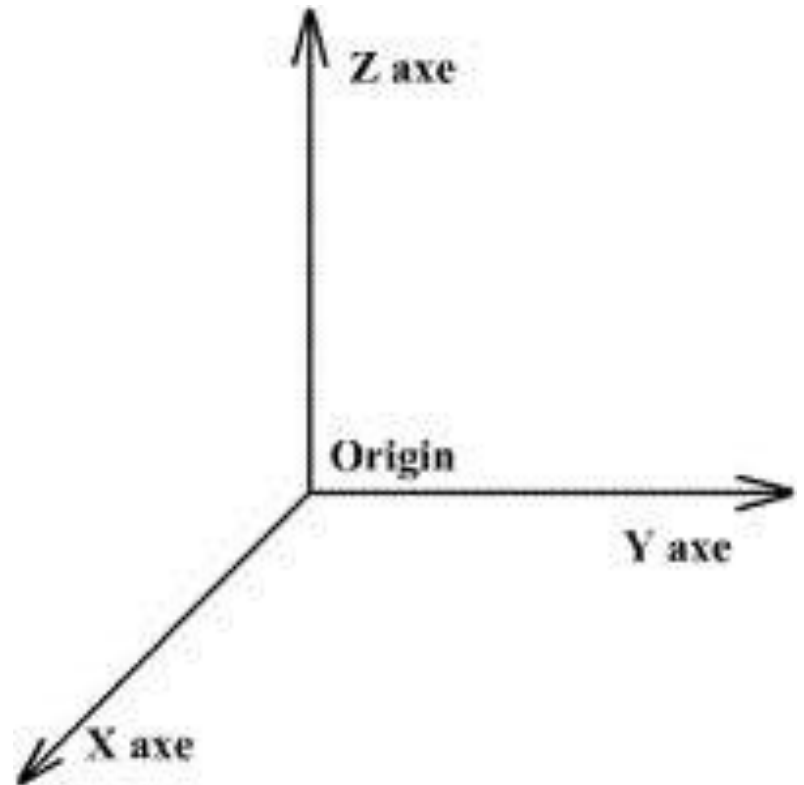
Examples: $z = x^2 + y^2$, $(x, y) = (\sin t, \cos t)$

3-dimensional coordinate system

- Left-handed (LH) system
- Right-handed (RH) system

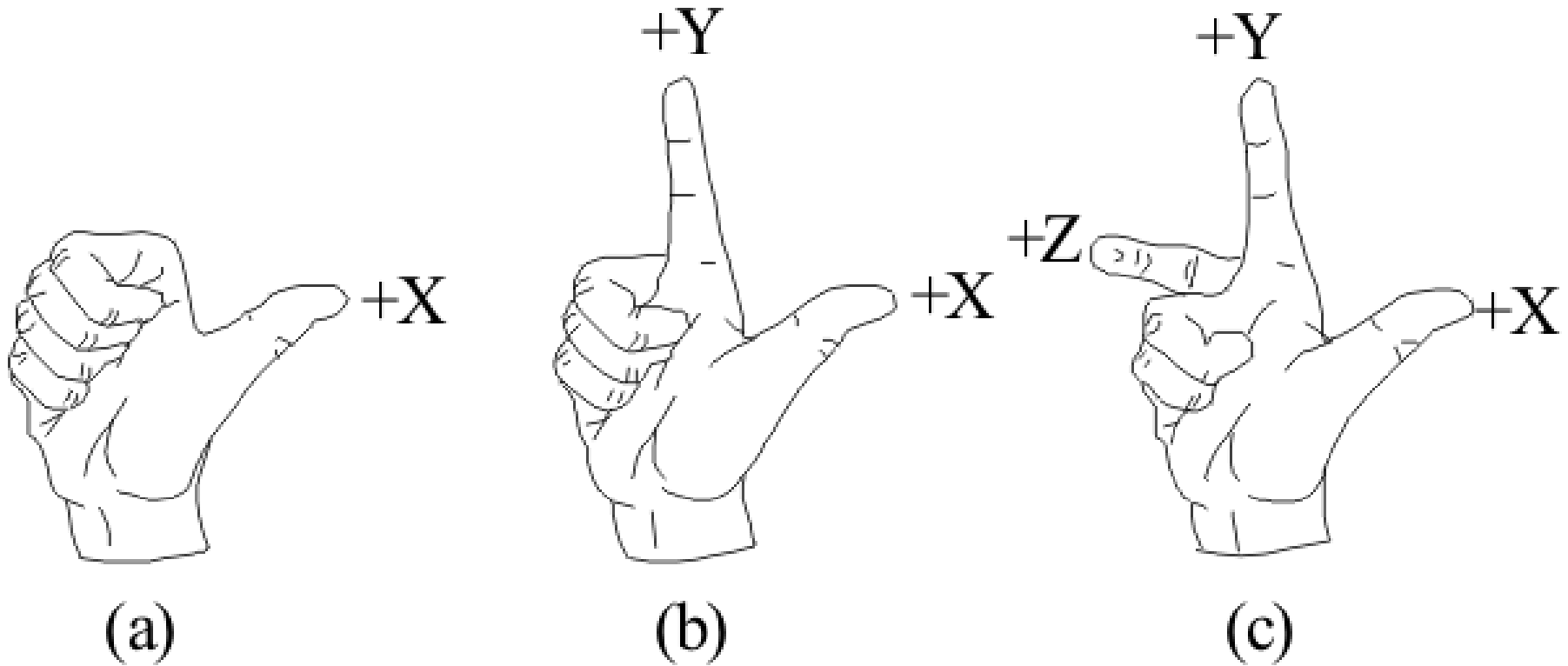


Right-handed coordinate system



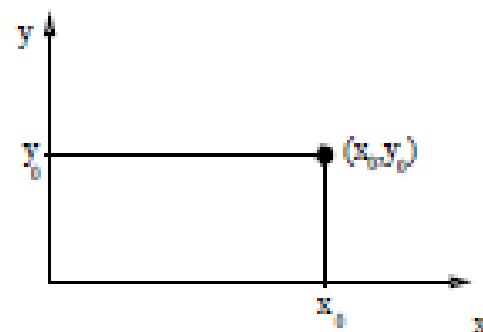
Note: In this course, we will use the right-handed system.

Right-handed coordinate system

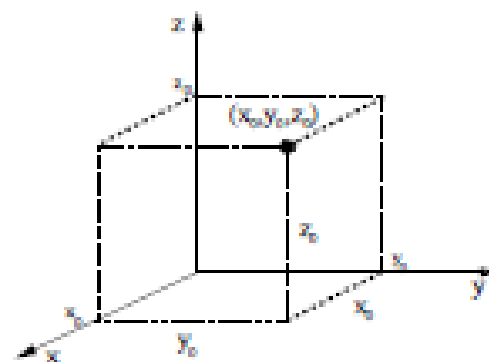


Cartesian coordinates.

Cartesian coordinates on \mathbb{R}^2 : Every point on a plane is labeled by an ordered pair (x, y) by the rule given in the figure.



Cartesian coordinates in \mathbb{R}^3 : Every point in space is labeled by an ordered triple (x, y, z) by the rule given in the figure.

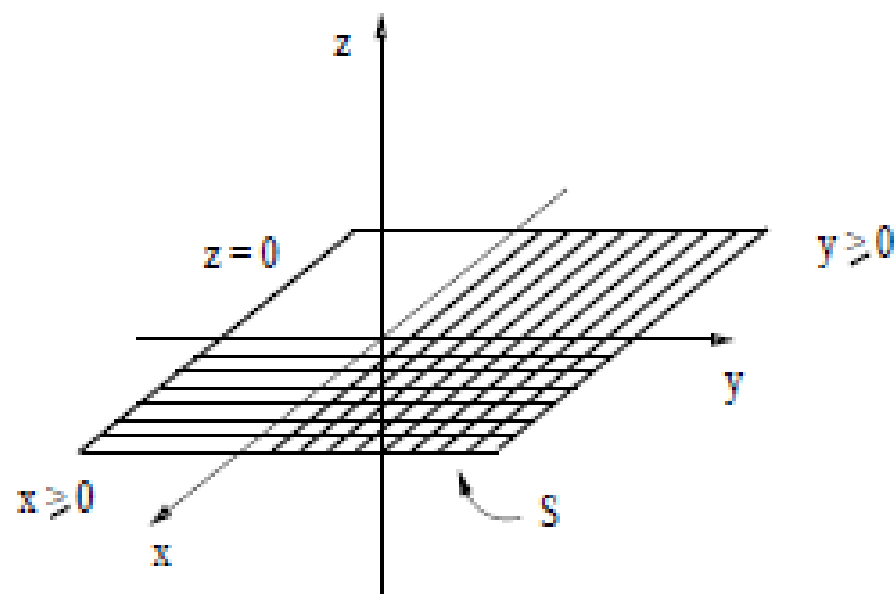


Cartesian coordinates.

Example

Sketch the set $S = \{x \geq 0, y \geq 0, z = 0\} \subset \mathbb{R}^3$.

Solution:



Distance between 2 points:

Theorem

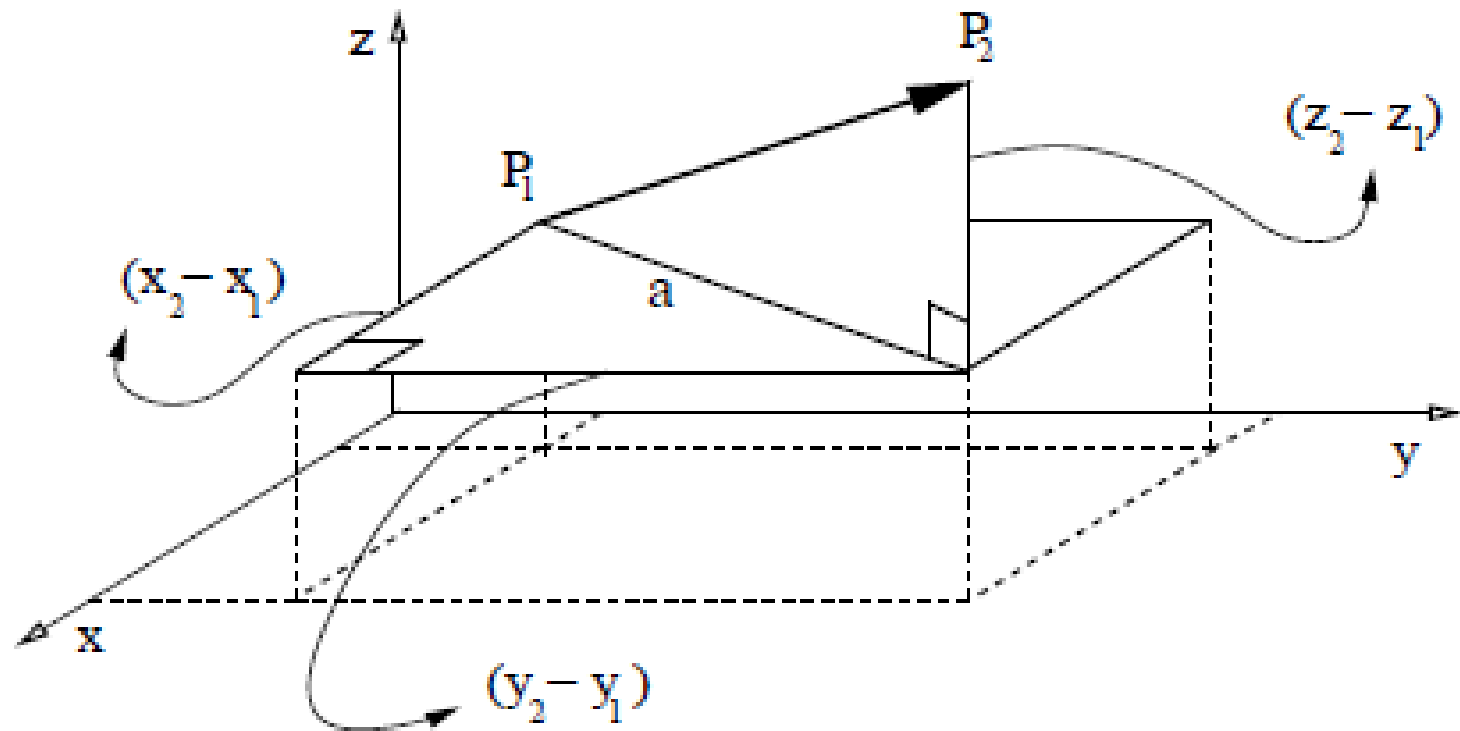
The distance $|P_1P_2|$ between the points $P_1 = (x_1, y_1, z_1)$ and $P_2 = (x_2, y_2, z_2)$ is given by

$$|P_1P_2| = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}.$$

The distance between points in space is crucial to define the idea of limit to functions in space.

Proof.

Pythagoras Theorem.

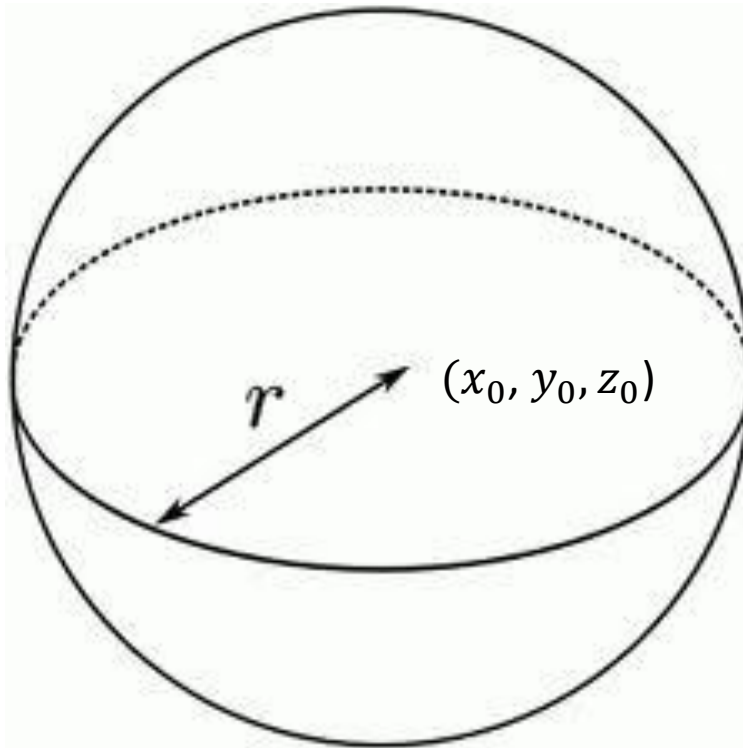


$$|P_1P_2|^2 = a^2 + (z_2 - z_1)^2, \quad a^2 = (x_2 - x_1)^2 + (y_2 - y_1)^2.$$

□

Sphere equation

$$(x - x_0)^2 + (y - y_0)^2 + (z - z_0)^2 = r^2$$



Equation of a sphere

Example

Graph the sphere $x^2 + y^2 + z^2 + 4y = 0$.

Solution: Complete the square.

$$0 = x^2 + y^2 + 4y + z^2$$

$$0 = x^2 + \left[y^2 + 2 \left(\frac{4}{2} \right) y + \left(\frac{4}{2} \right)^2 \right] - \left(\frac{4}{2} \right)^2 + z^2$$

$$0 = x^2 + \left(y + \frac{4}{2} \right)^2 + z^2 - 4.$$

$$x^2 + y^2 + 4y + z^2 = 0 \quad \Leftrightarrow \quad x^2 + (y + 2)^2 + z^2 = 2^2.$$

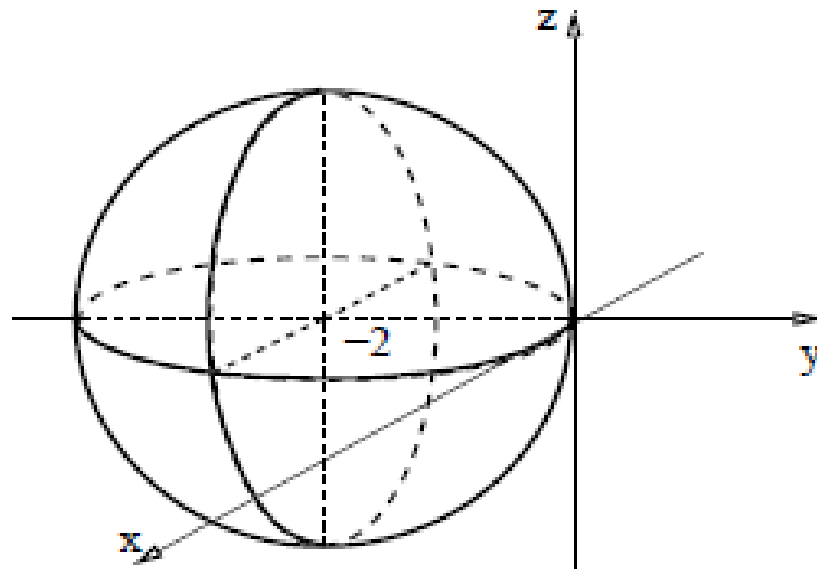
Equation of a sphere

Example

Graph the sphere $x^2 + y^2 + z^2 + 4y = 0$.

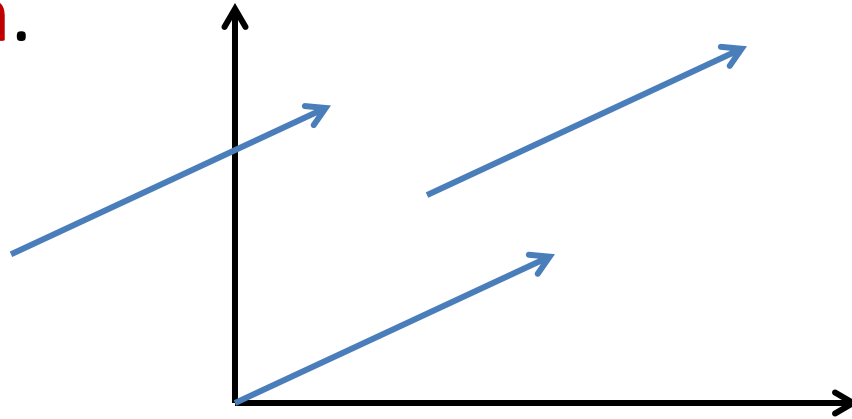
Solution: $x^2 + y^2 + 4y + z^2 = 0 \Leftrightarrow x^2 + (y + 2)^2 + z^2 = 2^2$.

Then, we conclude that $P_0 = (0, -2, 0)$ and $R = 2$. Therefore,



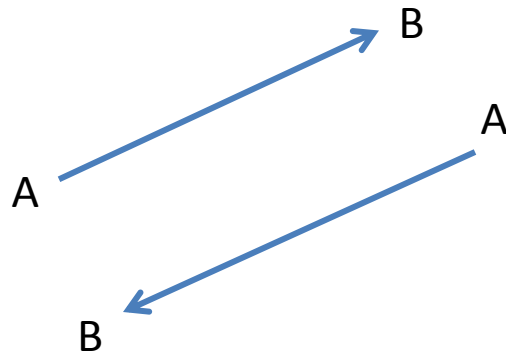
Vectors in \mathbb{R}^2 and \mathbb{R}^3

Definition: A vector is a directed line, \overrightarrow{AB} from point A (initial point) to point B (terminal point) and has its length denoted by $|\overrightarrow{AB}|$. Two vectors are equal if they have the same **length** and **direction**.



Note

- Initial point and terminal point are not unique.
- \overrightarrow{AB} and \overrightarrow{BA} are of the same length but of opposite in directions.



Components of a vector in Cartesian coordinates

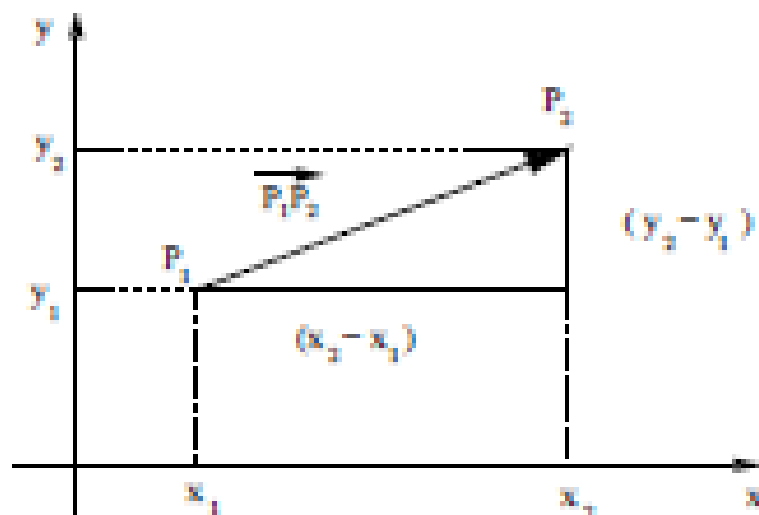
Theorem

Given the points $P_1 = (x_1, y_1)$, $P_2 = (x_2, y_2) \in \mathbb{R}^2$, the vector $\overrightarrow{P_1P_2}$ determines a unique ordered pair, called vector components,

$$\langle \overrightarrow{P_1P_2} \rangle = \langle (x_2 - x_1), (y_2 - y_1) \rangle.$$

Proof:

Draw the vector $\overrightarrow{P_1P_2}$ in Cartesian coordinates. \square



Remark: A similar result holds for vectors in space.

Components of a vector in Cartesian coordinates

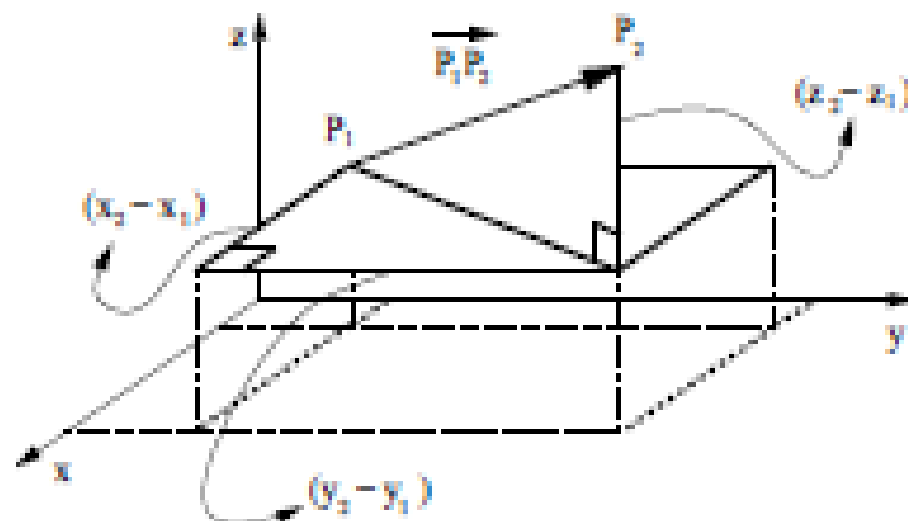
Theorem

Given the points $P_1 = (x_1, y_1, z_1)$, $P_2 = (x_2, y_2, z_2) \in \mathbb{R}^3$, the vector $\overrightarrow{P_1P_2}$ fixes a unique ordered triple, called vector components,

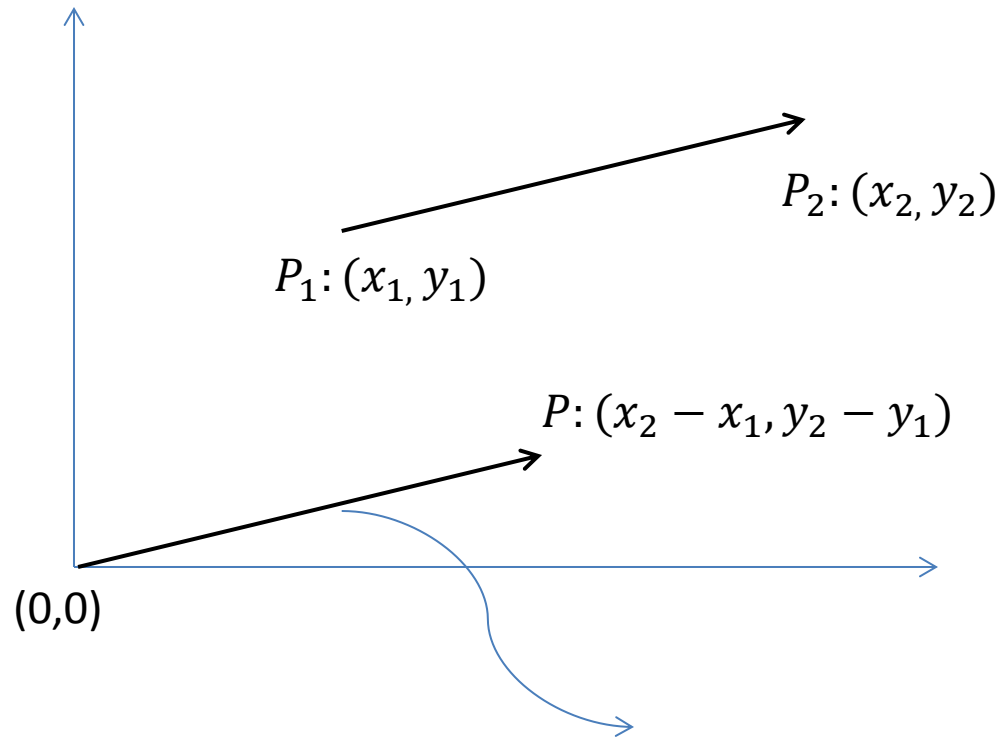
$$(\overrightarrow{P_1P_2}) = ((x_2 - x_1), (y_2 - y_1), (z_2 - z_1)).$$

Proof:

Draw the vector $\overrightarrow{P_1P_2}$ in Cartesian coordinates. \square



Standard position



Standard vector (representative)

$\mathbf{v}: \langle v_1, v_2 \rangle$ or $\vec{v}: \langle v_1, v_2 \rangle$ or $\underline{v}: \langle v_1, v_2 \rangle$

Remark: Similar concepts can be defined in 3-D

Vector algebra operations

- Addition:

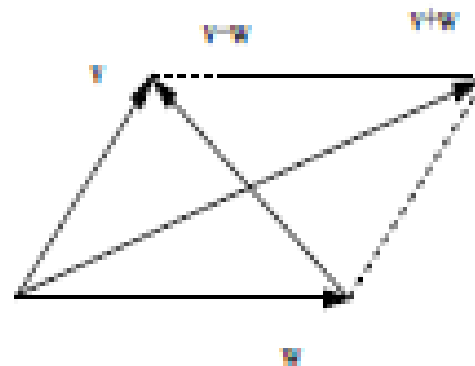
$$\vec{u} = \langle u_1, u_2, u_3 \rangle, \vec{v} = \langle v_1, v_2, v_3 \rangle$$
$$\vec{u} + \vec{v} = \langle u_1 + v_1, u_2 + v_2, u_3 + v_3 \rangle$$

- Scalar multiplications: Let r be a real number

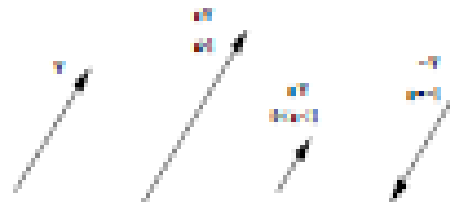
$$r\vec{u} = \langle ru_1, ru_2, ru_3 \rangle$$

Addition and scalar multiplication.

Remark: The addition and difference of two vectors.



Remark: The scalar multiplication stretches a vector if $a > 1$ and compresses the vector if $0 < a < 1$.



Magnitude of a vector and unit vectors.

Definition

The *magnitude* or *length* of a vector $\overrightarrow{P_1P_2}$ is the distance from the initial point to the terminal point.

- ▶ If the vector $\overrightarrow{P_1P_2}$ has components

$$\overrightarrow{P_1P_2} = \langle (x_2 - x_1), (y_2 - y_1), (z_2 - z_1) \rangle,$$

then its magnitude, denoted as $|\overrightarrow{P_1P_2}|$, is given by

$$|\overrightarrow{P_1P_2}| = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}.$$

- ▶ If the vector \mathbf{v} has components $\mathbf{v} = \langle v_x, v_y, v_z \rangle$, then its magnitude, denoted as $|\mathbf{v}|$, is given by

$$|\mathbf{v}| = \sqrt{v_x^2 + v_y^2 + v_z^2}.$$

Magnitude of a vector and unit vectors.

Definition

A vector \mathbf{v} is a *unit vector* iff \mathbf{v} has length one, that is, $|\mathbf{v}| = 1$.

Example

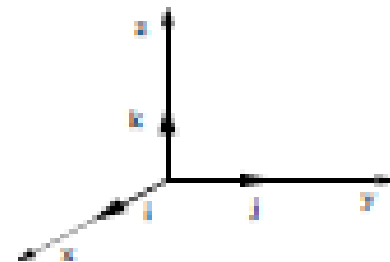
Show that $\mathbf{v} = \left\langle \frac{1}{\sqrt{14}}, \frac{2}{\sqrt{14}}, \frac{3}{\sqrt{14}} \right\rangle$ is a unit vector.

Solution:

$$|\mathbf{v}| = \sqrt{\frac{1}{14} + \frac{4}{14} + \frac{9}{14}} = \sqrt{\frac{14}{14}} \Rightarrow |\mathbf{v}| = 1.$$

Example

The unit vectors $\mathbf{i} = \langle 1, 0, 0 \rangle$, $\mathbf{j} = \langle 0, 1, 0 \rangle$, and $\mathbf{k} = \langle 0, 0, 1 \rangle$ are useful to express any other vector in \mathbb{R}^3 .



Addition and scalar multiplication.

Theorem

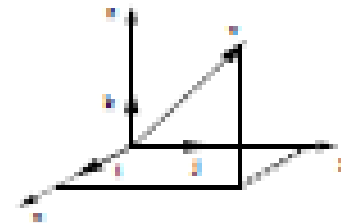
Every vector $\mathbf{v} = \langle v_x, v_y, v_z \rangle$ in \mathbb{R}^3 can be expressed in a unique way as a linear combination of vectors $\mathbf{i} = \langle 1, 0, 0 \rangle$,

$\mathbf{j} = \langle 0, 1, 0 \rangle$, and $\mathbf{k} = \langle 0, 0, 1 \rangle$ as follows

$$\mathbf{v} = v_x \mathbf{i} + v_y \mathbf{j} + v_z \mathbf{k}.$$

Proof: Use the definitions of vector addition and scalar multiplication as follows,

$$\begin{aligned} \mathbf{v} &= \langle v_x, v_y, v_z \rangle \\ &= \langle v_x, 0, 0 \rangle + \langle 0, v_y, 0 \rangle + \langle 0, 0, v_z \rangle \\ &= v_x \langle 1, 0, 0 \rangle + v_y \langle 0, 1, 0 \rangle + v_z \langle 0, 0, 1 \rangle \\ &= v_x \mathbf{i} + v_y \mathbf{j} + v_z \mathbf{k}. \end{aligned}$$



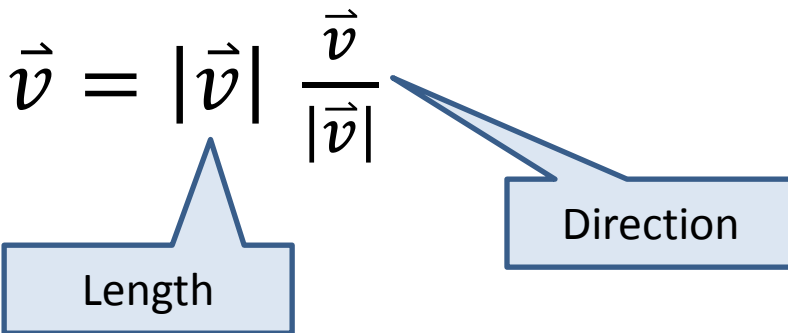
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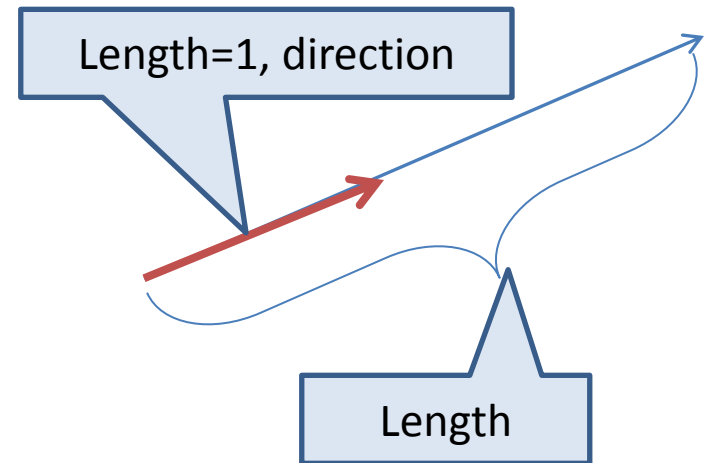
Addition and Scalar Multiplication

- $\vec{a} + \vec{b} = \vec{b} + \vec{a}$
- $\vec{a} + (\vec{b} + \vec{c}) = (\vec{a} + \vec{b}) + \vec{c}$
- $\vec{a} + \vec{0} = \vec{a}$
- $\vec{a} + (-\vec{a}) = \vec{0}$
- $c(\vec{a} + \vec{b}) = c\vec{a} + c\vec{b}$
- $(c + d)\vec{a} = c\vec{a} + d\vec{a}$
- $(cd)\vec{a} = c(d\vec{a})$
- $1\vec{a} = \vec{a}$

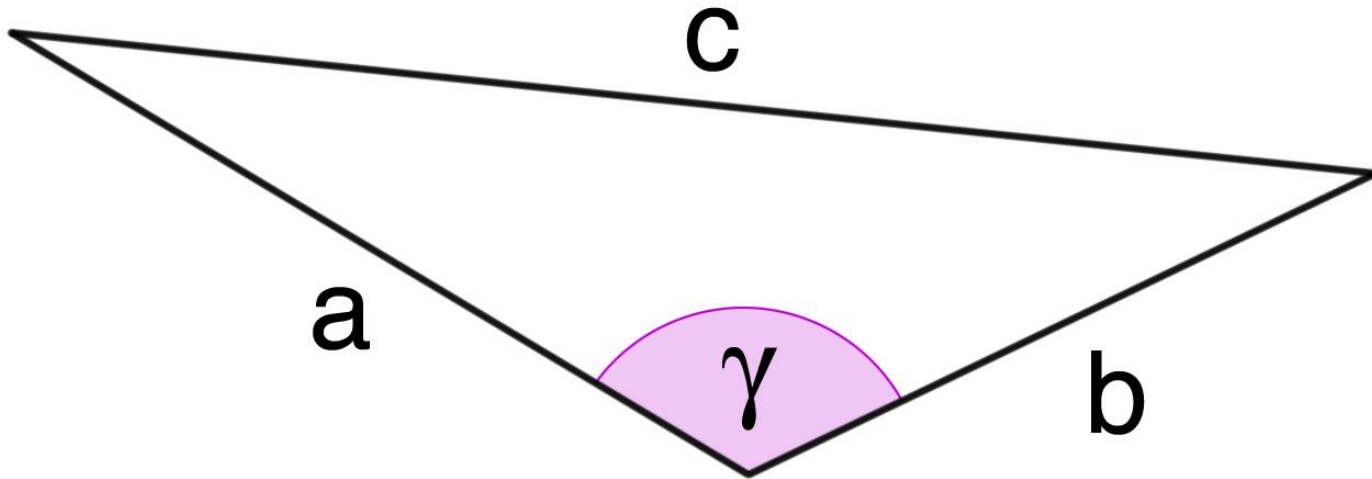
Vector decompositions

- $\vec{v} = v_1\vec{i} + v_2\vec{j} + v_3\vec{k}$

- $\vec{v} = |\vec{v}| \frac{\vec{v}}{|\vec{v}|}$
The diagram shows the formula $\vec{v} = |\vec{v}| \frac{\vec{v}}{|\vec{v}|}$. A callout box labeled "Length" points to the magnitude $|\vec{v}|$ in the numerator. Another callout box labeled "Direction" points to the unit vector $\frac{\vec{v}}{|\vec{v}|}$.



Law of cosines

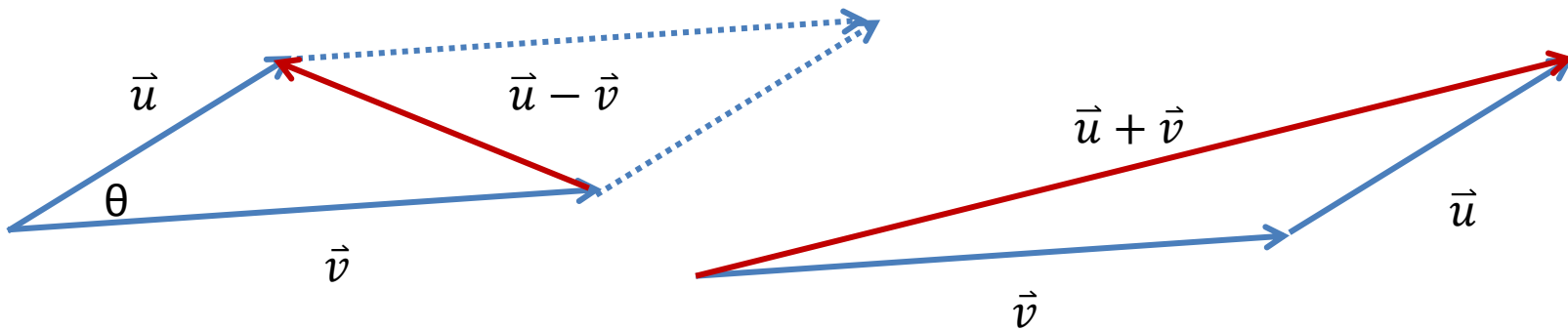


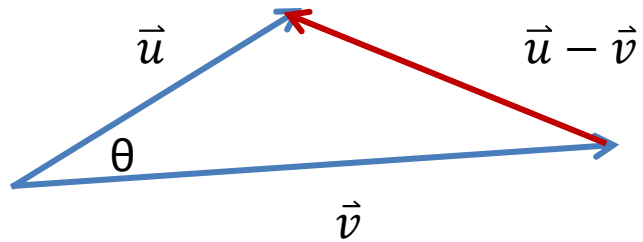
$$c^2 = a^2 + b^2 - 2ab(\cos(\gamma))$$

Theorem

Let $\vec{u} = \langle u_1, u_2, u_3 \rangle$ and $\vec{v} = \langle v_1, v_2, v_3 \rangle$ be two vectors (standard position) and θ be the angle between the two vectors. Then,

$$|\vec{u}| |\vec{v}| \cos \theta = u_1 v_1 + u_2 v_2 + u_3 v_3$$





Idea of the proof:

Law of cosines

$$\rightarrow 2|\vec{u}||\vec{v}|\cos\theta = |\vec{u}|^2 + |\vec{v}|^2 - |\vec{u} - \vec{v}|^2$$

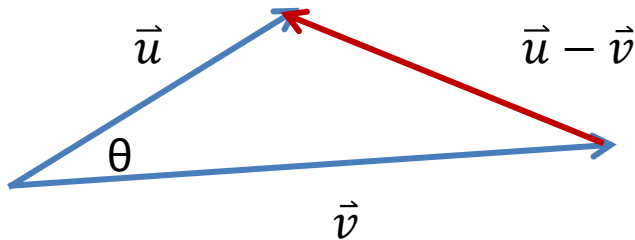
Also recall: $|u|^2 = u_1^2 + u_2^2 + u_3^2$

Definition:

Let $\vec{u} = \langle u_1, u_2, u_3 \rangle$ and $\vec{v} = \langle v_1, v_2, v_3 \rangle$ be two vectors (standard position) and θ be the angle between the two vectors. Then,

$$\vec{u} \cdot \vec{v} = |\vec{u}| |\vec{v}| \cos \theta = u_1 v_1 + u_2 v_2 + u_3 v_3$$

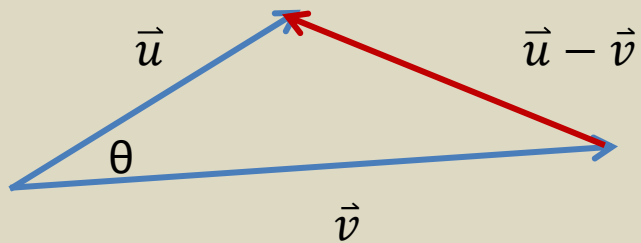
Is call the dot product of these two vectors



Definition

- Geometric definition:

$$\vec{u} \cdot \vec{v} = |\vec{u}| |\vec{v}| \cos \theta$$



- Algebraic definition:

$$\vec{u} \cdot \vec{v} = u_1 v_1 + u_2 v_2 + u_3 v_3$$

The dot product of two vectors is a scalar

Example

Compute $\mathbf{v} \cdot \mathbf{w}$ knowing that $\mathbf{v}, \mathbf{w} \in \mathbb{R}^3$, with $|\mathbf{v}| = 2$, $\mathbf{w} = \langle 1, 2, 3 \rangle$ and the angle in between is $\theta = \pi/4$.

Solution: We first compute $|\mathbf{w}|$, that is,

$$|\mathbf{w}|^2 = 1^2 + 2^2 + 3^2 = 14 \quad \Rightarrow \quad |\mathbf{w}| = \sqrt{14}.$$

We now use the definition of dot product:

$$\mathbf{v} \cdot \mathbf{w} = |\mathbf{v}| |\mathbf{w}| \cos(\theta) = (2) \sqrt{14} \frac{\sqrt{2}}{2} \quad \Rightarrow \quad \mathbf{v} \cdot \mathbf{w} = 2\sqrt{7}.$$

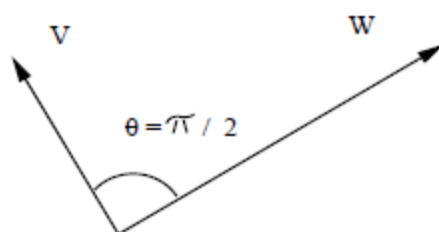
◁

- ▶ The angle between two vectors usually is not known in applications.
- ▶ It is useful to have a formula for the dot product involving the vector components.

Perpendicular vectors have zero dot product.

Definition

Two vectors are *perpendicular*, also called *orthogonal*, iff the angle in between is $\theta = \pi/2$.



Theorem

The non-zero vectors \mathbf{v} and \mathbf{w} are perpendicular iff $\mathbf{v} \cdot \mathbf{w} = 0$.

Proof.

$$\left. \begin{array}{l} 0 = \mathbf{v} \cdot \mathbf{w} = |\mathbf{v}| |\mathbf{w}| \cos(\theta) \\ |\mathbf{v}| \neq 0, \quad |\mathbf{w}| \neq 0 \end{array} \right\} \Leftrightarrow \left\{ \begin{array}{l} \cos(\theta) = 0 \\ 0 \leq \theta \leq \pi \end{array} \right. \Leftrightarrow \theta = \frac{\pi}{2}.$$

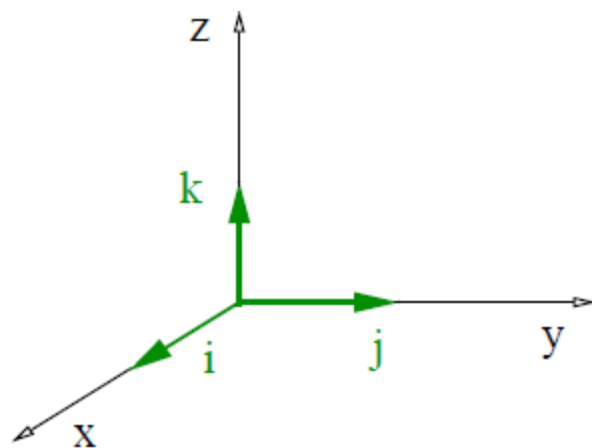
□

The dot product of \mathbf{i} , \mathbf{j} and \mathbf{k} is simple to compute

Example

Compute all dot products involving the vectors \mathbf{i} , \mathbf{j} , and \mathbf{k} .

Solution: Recall: $\mathbf{i} = \langle 1, 0, 0 \rangle$, $\mathbf{j} = \langle 0, 1, 0 \rangle$, $\mathbf{k} = \langle 0, 0, 1 \rangle$.



$$\mathbf{i} \cdot \mathbf{i} = 1,$$

$$\mathbf{i} \cdot \mathbf{j} = 0,$$

$$\mathbf{i} \cdot \mathbf{k} = 0,$$

$$\mathbf{j} \cdot \mathbf{j} = 1,$$

$$\mathbf{j} \cdot \mathbf{i} = 0,$$

$$\mathbf{j} \cdot \mathbf{k} = 0,$$

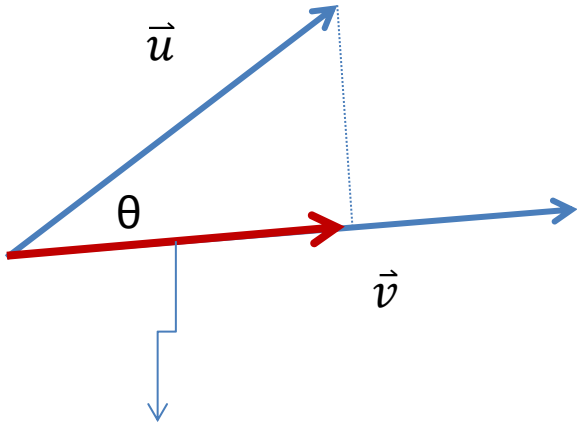
$$\mathbf{k} \cdot \mathbf{k} = 1,$$

$$\mathbf{k} \cdot \mathbf{i} = 0,$$

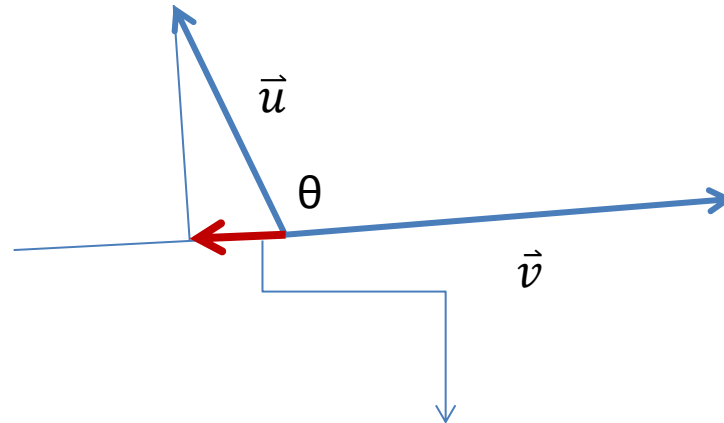
$$\mathbf{k} \cdot \mathbf{j} = 0.$$



Projection of one vector onto the other vector



Projection of \vec{u} onto \vec{v}



Projection of \vec{u} onto \vec{v}

$$|\vec{u}| \cos \theta = \begin{cases} \text{length of the red arrow, } \theta < \pi/2 \\ -\text{length of the red arrow, } \theta > \pi/2 \end{cases}$$

----- Scalar component of \mathbf{u} in the direction of \mathbf{v} .

(Definition)

Definition

$$\text{proj}_{\vec{v}} \vec{u} = (|\vec{u}| \cos \theta) \frac{\vec{v}}{|\vec{v}|}$$



Signed length
Scalar component



Unit vector in the
direction of \vec{v}

Definition (continue)

$$\begin{aligned} \text{proj}_{\vec{v}} \vec{u} &= (|\vec{u}| \cos \theta) \frac{\vec{v}}{|\vec{v}|} \\ &= \frac{|\vec{u}| |\vec{v}| \cos \theta}{|\vec{v}|} \frac{\vec{v}}{|\vec{v}|} \\ &= \frac{\vec{u} \cdot \vec{v}}{|\vec{v}|^2} \vec{v} \end{aligned}$$

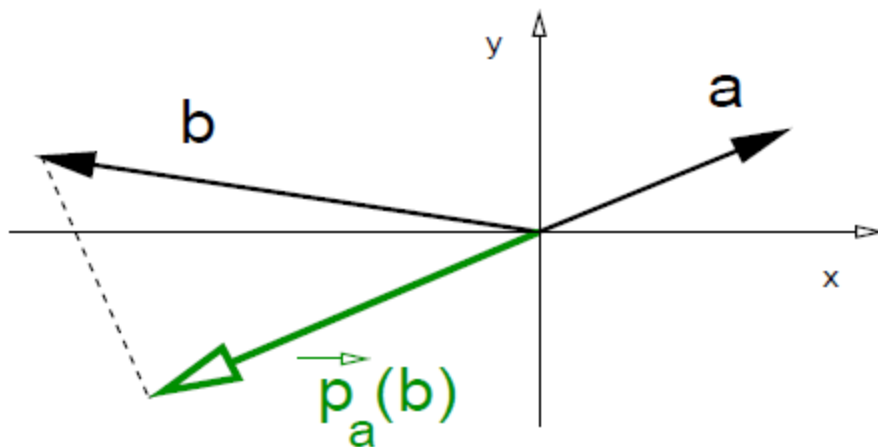
Example

Find the vector projection of $\mathbf{b} = \langle -4, 1 \rangle$ onto $\mathbf{a} = \langle 1, 2 \rangle$.

Solution: The vector projection of \mathbf{b} onto \mathbf{a} is the vector

$$\mathbf{p}_a(b) = \left(\frac{\mathbf{b} \cdot \mathbf{a}}{|\mathbf{a}|} \right) \frac{\mathbf{a}}{|\mathbf{a}|} = \left(-\frac{2}{\sqrt{5}} \right) \frac{1}{\sqrt{5}} \langle 1, 2 \rangle.$$

We therefore obtain $\mathbf{p}_a(b) = -\left\langle \frac{2}{5}, \frac{4}{5} \right\rangle$.



Properties of dot product

$$1. \quad \vec{u} \cdot \vec{v} = \vec{v} \cdot \vec{u}$$

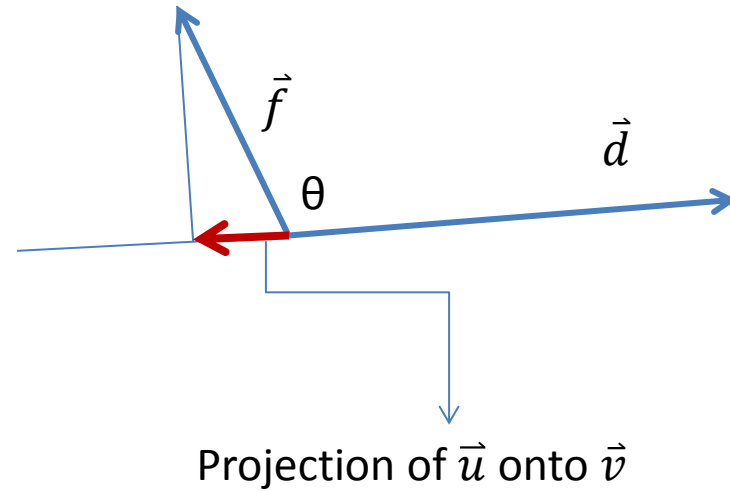
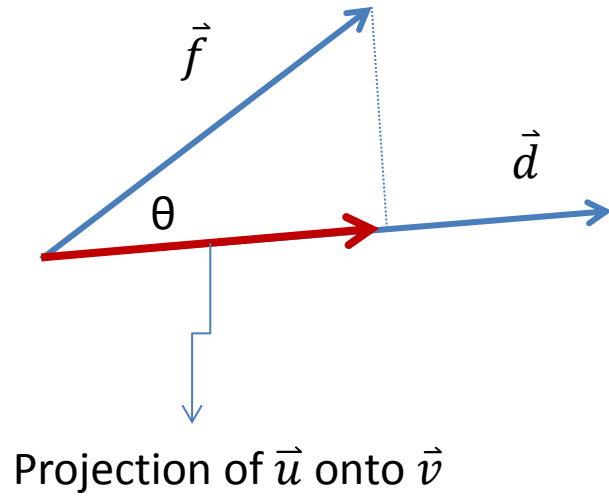
$$2. \quad (c\vec{u}) \cdot \vec{v} = \vec{u} \cdot (c\vec{v})$$

$$3. \quad \vec{u} \cdot (\vec{v} + \vec{w}) = \vec{u} \cdot \vec{v} + \vec{u} \cdot \vec{w}$$

$$4. \quad \vec{u} \cdot \vec{u} = |\vec{u}|^2$$

$$5. \quad \vec{0} \cdot \vec{v} = 0$$

Work



$$\begin{aligned} \text{Work} &= \text{Scalar component} * |\vec{d}| = |\vec{f}| \cos \theta * |\vec{d}| \\ &= \boxed{\vec{f} \cdot \vec{d}} \end{aligned}$$