

Math 254 H 4/13/2020 Differential Forms

A more natural way to differentiate....

Preliminary: covector (linear function)

Vector space V $\varphi: V \rightarrow \mathbb{R}$
 $v \mapsto \varphi(\vec{v})$

vectors \vec{v}

dual vector space $V^* = \{ \text{covectors } \varphi \}$

add $(\varphi + \psi)(\vec{v}) = \varphi(\vec{v}) + \psi(\vec{v})$

scalar mult $(c\varphi)(\vec{v}) = c(\varphi(\vec{v}))$

Use dot product to describe covectors: mult ~~in~~ in \mathbb{R}

$$\varphi(\vec{v}) = \vec{c} \cdot \vec{v} = \text{"height of } \vec{v} \text{ in direction } \vec{c} \text{"}$$

(\vec{c} called by $|\vec{c}|$)

$$\varphi = \vec{c}^*$$

Derivative of $f: \mathbb{R}^n \rightarrow \mathbb{R}$: gives linear approximation of $f(\vec{a})$ at each point \vec{a}

$$f(\vec{a} + \vec{h}) \approx f(\vec{a}) + Df_{\vec{a}}(\vec{h})$$

center \vec{a} \uparrow
increment \vec{h}

$$Df_{\vec{a}}: \mathbb{R}^n \rightarrow \mathbb{R}$$

linear fun = covector

$$Df_{\vec{a}} = (\nabla f(\vec{a}))^*$$

$$Df_{\vec{a}}(\vec{h}) = (\text{grad } f) \cdot \vec{h}$$

① $\nabla f = \vec{F}$ vector field = vector at each point
 $\nabla f(\vec{a}) = \vec{F}(\vec{a})$

Instead: $Df =$ covector field = covector at each point
 = differential form

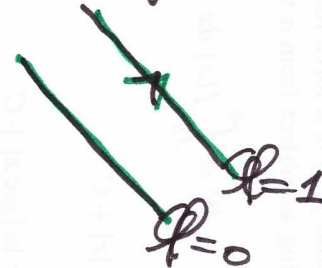
notation \parallel
 df differential form so $df_{\vec{a}} : \mathbb{R}^n \rightarrow \mathbb{R}$

$$df_{\vec{a}}(\vec{h}) = Df_{\vec{a}}(\vec{h})$$

$$= \nabla f(\vec{a}) \cdot \vec{h}$$

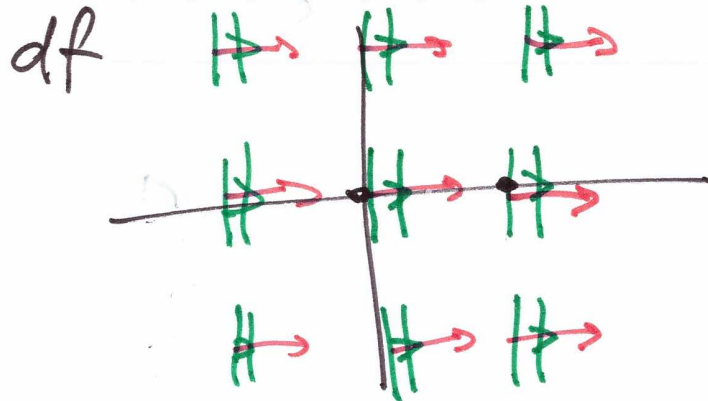
$$= \begin{bmatrix} \frac{\partial f}{\partial x_1} & \dots & \frac{\partial f}{\partial x_n} \end{bmatrix} \cdot \begin{bmatrix} h_1 \\ \vdots \\ h_n \end{bmatrix}$$

picture of covector $\mathcal{Q} : \mathbb{R}^2 \rightarrow \mathbb{R}$



$\mathcal{Q}(\vec{v}) = 0$ all \vec{v}
 draw as •

② \mathbb{R}^2 , $f(x,y) = x$

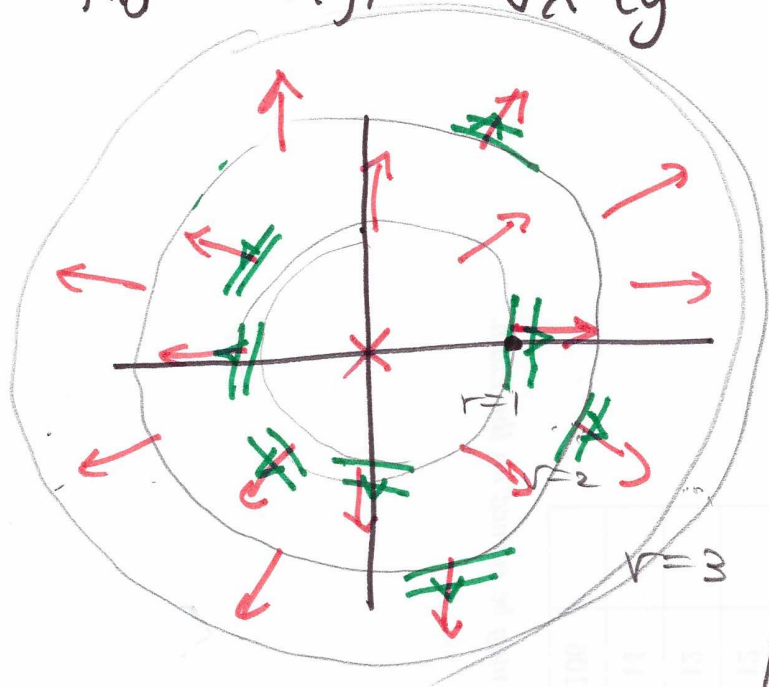


$$df = dx$$

$$dx_{\vec{a}}(h_1, h_2) = h_1$$

$$\nabla f = \nabla x = (1, 0)$$

① $f(x,y) = r(x,y) = \sqrt{x^2 + y^2}$

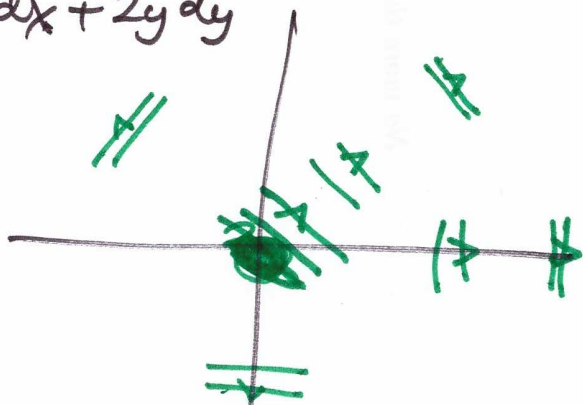


$f: \mathbb{R}^2 \rightarrow \mathbb{R}$
 $df_{\vec{a}}: \mathbb{R}^2 \rightarrow \mathbb{R}$

$df_{\vec{a}}(h_1, h_2)$
 $= \nabla f(\vec{a}) \cdot (h_1, h_2)$
 $= \frac{\partial f}{\partial x}(\vec{a}) h_1 + \frac{\partial f}{\partial y}(\vec{a}) h_2$

$\nabla r(\vec{a}) = \frac{\vec{a}}{|\vec{a}|}$

② $f(x,y) = x^2 + y^2 = r^2$
 $dr = 2x dx + 2y dy$



d
 $df = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy$

Not every differential form \mathcal{Q} appears as df for function f .
 (since not every \vec{F} vector field is ∇f for some f)

Any diff form \mathcal{Q} , can define its line integral over a curve.

Line integral of diff form \mathcal{Q} over $\vec{c}(t)$ $0 \leq t \leq 1$

$$Pdx + qdy$$

$$(x(t), y(t))$$

$$\int_C \mathcal{Q} = \int_{t=0}^1 \mathcal{Q}(\vec{c}'(t)) dt$$

$$= \int_{t=0}^1 P(x(t), y(t)) x'(t) + q(x(t), y(t)) y'(t) dt$$

$$\mathcal{Q} = F^*$$

$$\int \vec{F} \cdot d\vec{c}$$