Math 418H

Fall 2005

Lecture: Mon 10/17

- 1. Why bother with complex numbers \mathbb{C} ?
 - Define new number systems to solve equations that have no solutions in old number systems.
 - x + 1 = 0 has no soln in \mathbb{N} , so define \mathbb{Z} (negative numbers)
 - 2x 1 = 0 has no soln in \mathbb{Z} , so define \mathbb{Q} (fractions)
 - $x^2 2$ has no soln in \mathbb{Q} , so define \mathbb{R} (irrational numbers)
 - $x^2 + 1 = 0$ has no soln in \mathbb{R} , so define \mathbb{C} (imaginary numbers)

2. Formal definition of \mathbb{C}

- As with \mathbb{Q} and \mathbb{R} , we do not try to uncover the "essence" of a new number like $i = \sqrt{-1}$. We just define it by enough information to determine all its properties.
- $\mathbb{C} = \mathbb{R} \times \mathbb{R} = \{(a, b) \mid a, b \in \mathbb{R}\}$, pairs of real numbers: (a, b) represents the complex number a + bi.
- Addition: (a, b) + (c, d) := (a + c, b + d). Motivation: (a+bi) + (c+di) = (a+c) + (b+d)i.
- Multiplication: $(a, b) \cdot (c, d) := (ac bd, ad + bc).$ Motivation: $(a+bi) \cdot (c+di) = ac+bdi^2+adi+bci = (ac-bd)+(ad+bc)i.$
- Check the field axioms for \mathbb{C} . Identity elements: (0,0), (1,0). Multiplicative associativity:

$$[(a,b) \bullet (c,d)] \bullet (e,f) = (ace-adf-bcf-bde) + (acf+ade+bce-bdf)i$$

= (a,b) \lefta [(c,d) \lefta (e,f)].

• The only tricky property is the existence of multiplicative inverses. We *should* have:

$$\frac{1}{a+bi} = \frac{a-bi}{(a+bi)(a-bi)} = \frac{a-bi}{a^2+b^2} = \frac{a}{a^2+b^2} - \frac{b}{a^2+b^2}i.$$

This is motivation, but proves nothing, because we have not established that 1/(a + bi) even exists.

• Given $(a, b) \neq (0, 0)$, we define the multiplicative inverse as:

$$(a,b)^{-1} := \left(\frac{a}{a^2 + b^2}, -\frac{b}{a^2 + b^2}\right)$$

Now we prove that $(a, b) \cdot (a, b)^{-1} = (1, 0)$ by applying the definition of multiplication.

- Notation: a real number $a \in \mathbb{R}$ is identified with (a, 0), so we can regard $\mathbb{R} \subset \mathbb{C}$. Define i := (0, 1).
- Prove that $i^2 = -1$ and $(a, b) = a + b \cdot i$.
- 3. Geometric picture of \mathbb{C}
 - Picture: $\mathbb{C} = \mathbb{R}^2$, x + iy = (x, y), vectors in the real plane
 - Addition of complex numbers = usual addition of vectors (diagonal of parallelogram)
 - Multiplication of complex numbers = some kind of multiplication of plane vectors:

$$(a+ib) \cdot (x+iy) = (a,b) \cdot (x,y)$$

• Multiplying by a = (a, 0), we have

$$a \cdot (x, y) = (ax, ay) =$$
stretch (x, y) by a ,

the usual scalar multiple of a vector

• Multiplying by i = (0, 1), we have

$$i \cdot (1,0) = (0,1)$$
, $i \cdot (0,1) = (-1,0)$

and: $(x, y) \mapsto i \cdot (x, y) = (-y, x)$ is an \mathbb{R} -linear map. Thus:

$$i \cdot (x, y) = \text{ rotate } (x, y) \text{ by } 90^{\circ}$$

• Multiplying by a unit-length vector $u = \cos\theta + i\sin\theta = (\cos\theta, \sin\theta)$:

 $u \cdot (1,0) = (\cos \theta, \sin \theta)$, $u \cdot (0,1) = (-\sin \theta, \cos \theta)$

and $(x, y) \mapsto u \cdot (x, y)$ is an \mathbb{R} -linear map. Thus:

$$u \cdot (x, y) = \text{ rotate } (x, y) \text{ by } \theta.$$

Lecture: Wed 10/19

- 1. Complex multiplication = rotation
 - For $v = (a, b) \in \mathbb{C}$, consider the multiplication map

$$\begin{array}{rccc} M_v : \mathbb{R}^2 & \to & \mathbb{R}^2 \\ (x,y) & \mapsto & u \, \boldsymbol{\cdot} (x,y) \end{array}$$

This map is \mathbb{R} -linear:

$$M_v(cx, cy) = cM_v(x, y)$$

$$M_v(x_1 + x_2, y_1 + y_2) = M_v(x_1, y_1) + M_v(x_2, y_2).$$

for all $c \in \mathbb{R}$ and $(x_1, y_1), (x_2, y_2) \in \mathbb{R}^2$. Thus:

$$M_v(x, y) = x M_v(1, 0) + y M_v(0, 1)$$
.

• Multiply by i = (0, 1):

$$i \cdot (1,0) = (0,1)$$
, $i \cdot (0,1) = (-1,0)$
 $i \cdot (x,y) = \text{rotate } (x,y) \text{ by } 90^{\circ}.$

• Multiply by a unit-length vector $u = \cos\theta + i\sin\theta = (\cos\theta, \sin\theta)$:

 $u \cdot (1,0) = (\cos \theta, \sin \theta)$, $u \cdot (0,1) = (-\sin \theta, \cos \theta)$. $u \cdot (x,y) = \text{rotate} (x,y) \text{ by } \theta$.

• Write an arbitrary vector in polar coordinates: v = ru, where $r \in \mathbb{R}$ and $u = \cos\theta + i\sin\theta$. Then:

 $v \cdot (x, y) = \text{rotate } (x, y) \text{ by } \theta$, then stretch by r.

- 2. Complex multiplication: add angles, multiply lengths
 - Consider the complex product: $v_3 = v_1 \cdot v_2$, and write each number in polar form: $v_j = r_j(\cos \theta_j + i \sin \theta_j \text{ for } j = 1, 2, 3$. Then:

$$\theta_3 = \theta_1 + \theta_2 \quad , \quad r_3 = r_1 r_2 \, ;$$

that is: to multiply complex numbers, add their angles and multiply their lengths.

- First proof: Since the multiplication map $(x, y) \mapsto v_j \cdot (x, y)$ is rotating by θ_j and stretching by r_j , we can describe the product $v_1 \cdot v_2 = v_1 \cdot v_2 \cdot 1$ as follows: start with unit vector 1; rotate by θ_2 ; stretch by r_2 ; rotate by θ_1 ; stretch by r_1 . Result: rotate by $\theta_1 + \theta_2$, and stretch by r_1r_2 .
- Second proof: From the formula for complex multiplication:

$$r_1(\cos\theta_1 + i\sin\theta_1) \cdot r_2(\cos\theta_2 + i\sin\theta_2)$$

 $= r_1 r_2 \left(\left(\cos \theta_1 \cos \theta_2 - \sin \theta_1 \sin \theta_2 \right) + i \left(\cos \theta_1 \sin \theta_2 + \sin \theta_1 \cos \theta_2 \right) \right)$ $\stackrel{!}{=} r_1 r_2 \left(\cos(\theta_1 + \theta_2) + i \sin(\theta_1 + \theta_2) \right)$

by the angle-addition formulas.

- 3. Complex powers
 - 2v is the vector v stretched by 2
 - -v is the vector opposite to v
 - Let $v = r(\cos \theta + i \sin \theta)$. $v^2 = v \cdot v$ is the vector with length r^2 and angle 2θ
 - \sqrt{v} is a vector with length \sqrt{r} and angle $\frac{1}{2}\theta$.
 - There are 2 square roots because the angle θ is a miguous. We could just as well write:

$$v = r(\cos(\theta + 2\pi) + i\sin(\theta + 2\pi))$$

so that

$$\sqrt{v} = \sqrt{r} \left(\cos(\frac{1}{2}\theta + \pi) + i\sin(\frac{1}{2}\theta + \pi) \right)$$
$$= -\sqrt{r} \left(\cos\frac{1}{2}\theta + i\sin\frac{1}{2}\theta \right).$$

• DeMoivre's Theorem: $v^{1/n}$ is any vector with length $r^{1/n}$ and angle

$$\frac{\theta + 2k\pi}{n} = \frac{\theta}{n} + \frac{2\pi k}{n} \,.$$

There are n such vectors evenly spaced around the circle, corresponding to the values $k = 0, 1, \ldots, n-1$.

- 4. Complex numbers as matrices
 - Any linear mapping $M : \mathbb{R}^2 \to \mathbb{R}^2$ is defined by a 2×2 matrix. If M(1,0) = (a,b) and M(0,1) = (c,d), then: $M = \begin{bmatrix} a & c \\ b & d \end{bmatrix}$, and:

$$M(x,y) = \left[\begin{array}{cc} a & c \\ b & d \end{array} \right] \cdot \left[\begin{array}{c} x \\ y \end{array} \right]$$

Here we use row vectors and column vectors interchangeably: $(x,y) = \left[\begin{array}{c} x \\ y \end{array} \right]$

• The linear mapping M_u for $u = \cos \theta + i \sin \theta$ is given by the matrix:

$$M_u(x,y) = v \cdot (x,y) = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}.$$

This is called the *rotation matrix* of θ .

• The linear mapping M_v for v = a + bi = ru is rotation by θ and stretching by r. Its matrix is:

$$M_{v}(x,y) = v \bullet (x,y) = \left[\begin{array}{cc} a & -b \\ b & a \end{array} \right] \left[\begin{array}{cc} x \\ y \end{array} \right]$$

This is called a *complex multiplication matrix*.

• Consider the set of all complex mult matrices:

$$M_{\mathbf{C}} := \left\{ \left[\begin{array}{cc} a & -b \\ b & a \end{array} \right] \text{ where } a, b \in \mathbb{R} \right\} \,.$$

This is a "copy" of the complex number field inside the ring of 2×2 matrices. That is, there is an isomorphism of fields from the complex numbers to this ring of matrices:

$$\phi: \quad \mathbb{C} \quad \to \quad M_{\mathbf{C}}$$
$$a + bi \quad \mapsto \quad \left[\begin{array}{cc} a & -b \\ b & a \end{array} \right]$$

satisfies:

$$\phi(v_1 + v_2) = \phi(v_1) + \phi(v_2)$$
 and $\phi(v_1 \cdot v_2) = \phi(v_1) \cdot \phi(v_2)$,

where the operation on the left side of each equation is in \mathbb{C} , and the operation on the right side is an operation of matrices.

Lecture: Mon 10/24

- 1. Picturing complex functions
 - A complex function $f : \mathbb{C} \to \mathbb{C}$, f(x+iy) = u(x,y) + iv(x,y) has real component u(x,y) and imaginary component v(x,y), where $u, v : \mathbb{R}^2 \to R$ are real functions on $\mathbb{C} = \mathbb{R}^2$.
 - This is the same thing as a vector field $f : \mathbb{R}^2 \to \mathbb{R}^2$, f(x, y) = (u(x, y), v(x, y)), with x-component u(x, y) and y-component v(x, y). This can be pictured by a field plot: draw each arrow f(x, y) with its base at the point (x, y).
 - Example 1: The complex function f(z) = iz is equivalent to the vector field: f(x, y) = (-y, x) whose field plot has arrows circulating around the origin, with length proportional to their distance from the origin. This is the velocity field of a turn-table.

For a general $\alpha = r \operatorname{cis} \theta$, the field plot of $f(z) = \alpha z$ is a vortex centered at the origin, with the arrows rotated by angle θ away from the outward direction, like the velocity field of water swirling down the drain.

- Example 2: The complex function $f(z) = z^2 + (1+i)z + 1$ is equivalent to the vector field $f(x, y) = (x^2 y^2 + x y + 1, 2xy + y + x)$
- Example 3: The complex function $f(z) = \overline{z}$, complex conjugate, is equivalent to the vector field f(x, y) = (x, -y).
- 2. Derivative of a vector field
 - An arbitrary vector field f(x, y) = (u(x, y), v(x, y)) has a derivative matrix:

$$Df := \left[\begin{array}{cc} u_x & u_y \\ v_x & v_y \end{array} \right],$$

where

$$u_x(x,y) = \frac{\partial u}{\partial x} := \lim_{\epsilon \to 0} \frac{u(x+\epsilon, y) - u(x,y)}{\epsilon}$$

is the partial derivative of u(x, y) in the x-direction, etc.

• If $f : \mathbb{R} \to \mathbb{R}$ is an ordinary real function, its derivative f'(a) gives the slope of the best linear approximation to f(x) near x = a: for small ϵ , we have:

$$f(a+\epsilon) \approx f(a) + f'(a) \epsilon$$

which is just unravelling the definition of derivative:

$$f'(a) \approx \frac{f(a+\epsilon) - f(a)}{\epsilon}$$

Similarly, for a vector field $f : \mathbb{R}^2 \to \mathbb{R}^2$, the derivative matrix Df(a, b) gives the best linear-function approximation near the point (a, b): for small (ϵ_1, ϵ_2) , we have:

$$f(a+\epsilon_1, b+\epsilon_2) \approx f(a,b) + Df(a,b) \cdot \begin{bmatrix} \epsilon_1 \\ \epsilon_2 \end{bmatrix}$$

where the last operation is matrix multiplication.

• Example 2: For $f(x, y) = (x^2 - y^2 + x - y + 1, 2xy + y + x)$, we have:

$$Df(x,y) = \begin{bmatrix} 2x+1 & 2y+1 \\ -2y-1 & 2x+1 \end{bmatrix}$$

• Example 3: For f(x, y) = (x, -y), we have:

$$Df(x,y) = \left[\begin{array}{rrr} 1 & 0\\ 0 & -1 \end{array}\right]$$

- 3. Complex analytic functions
 - We say a complex function f(x + iy) = u(x, y) + iv(x, y) is complex analytic (or just analytic) if any of the following equivalent conditions apply.
 - The partial derivatives of f(z) = f(x + iy) in the real and imaginary directions are *equal*:

$$\frac{\partial f(x+iy)}{\partial x} = \lim_{\epsilon \to 0} \frac{f(z+\epsilon) - f(z)}{\epsilon} = u_x(x,y) + iv_x(x,y)$$
$$\stackrel{!}{=} \frac{\partial f(x+iy)}{\partial iy} = \lim_{\epsilon \to 0} \frac{f(z+i\epsilon) - f(z)}{i\epsilon} = v_y(x,y) - iu_y(x,y) \,.$$

We define the complex derivative f'(z) to be the common value of these partial derivatives.

• For every value z = x + iy, the derivative matrix Df(x, y) is a complex multiplication matrix M_{c+id} for some $c + id \in \mathbb{C}$:

$$Df := \begin{bmatrix} u_x & u_y \\ v_x & v_y \end{bmatrix} = \begin{bmatrix} c & -d \\ d & c \end{bmatrix}$$

We define the complex derivative f'(z) to be the complex number in this multiplication matrix:

$$f'(z) := c + id = u_x + iv_x = v_y - iu_y$$

• The component functions of f(x + iy) = u(x, y) + iv(x, y) satisfy the *Cauchy-Riemann* partial differential equations:

$$u_x = v_y \quad , \quad v_x = -u_y \,.$$

- 4. Examples: analytic and non-analytic functions
 - Example 1: f(z) = iz, f(x, y) = (-y, x), $f'(z) = (u_x, v_x) = (v_y, -u_y) = (0, 1) = i$.
 - Example 2: $f(z) = z^2 + (1+1)z + 1$, $f(x, y) = (x^2 y^2 + x y + 1, 2xy + y + x)$, $f'(z) = (u_x, v_x) = (v_y, -u_y) = (2x + 1, 2y + 1) = 2z + 1$.
 - Example 3: $f(z) = \overline{z}$, f(x, y) = (x, -y),

$$f'(z) = (u_x, v_x) = (1, 0) \stackrel{?}{=} (v_y, -u_y) = (-1, 0).$$

The equality does not hold, so f(z) is not analytic at any z!

- For a general complex analytic f(z) with roots $z = r_1, \ldots, r_n$, the field plot has a vortex around each r_i which looks approximately like the vortex of $g(z) = \alpha z$ for $\alpha = f'(r_i)$.
- 5. Combining analytic functions
 - $f(z) = \alpha$ (constant function) and f(z) = z are analytic
 - If f(z) and g(z) are analytic, then:
 - f(z) + g(z) is analytic and (f(z) + g(z))' = f'(z) + g'(z). - f(z) g(z) is analytic and (f(z) g(z))' = f'(z)g(z) + f(z)g'(z). $- f(z)/g(z) \text{ is analytic for all } z \text{ where } g(z) \neq 0, \text{ and }$

$$\left(\frac{f(z)}{g(z)}\right)' = \frac{f'(z)g(z) - f(z)g'(z)}{g(z)^2}.$$

• Corollary: All polynomial functions $f(z) \in \mathbb{C}[z]$ are complex analytic for every z. All rational functions f(z)/g(z) are complex analytic except at the points z where g(z) = 0.

- 6. Fundamental Theorem of Algebra
 - *Theorem:* Any polynomial

$$f(z) = a_0 + a_1 z + \dots + a_n z^n \in \mathbb{C}[z]$$

of degree $n \ge 1$ has at least one complex root $z = \alpha$ with $f(\alpha) = 0$.

• This means: the field plot of any polynomial f(z) has at least one vortex. The plot of a high-degree polynomial is very complicated, so this is not at all obvious!

Alternatively: any complex polynomial of degree n can be completely split into n linear factors:

$$f(z) = a_n(z - r_1) \cdots (z - r_n).$$

This will have fewer than n vortices if some of the r_i 's coincide.

- *Strategy of Proof:* First, Cauchy's Mean Value Theorem says that for any circle in the complex plane, the value of an analytic function at the center is a certain average of the values on the circle.
- Next, Liouville's Theorem: Let f(z) be complex analytic on the whole plane, with $\lim_{|z|\to\infty} f(z) = 0$, meaning that f(z) becomes very small when z is far from the origin. Then f(z) can only be the zero constant function: f(z) = 0 for all z.

Proof: Consider any particular α , and take a very large circle centered at α . Given $\epsilon > 0$, by assumption we can take an α centered circle large enough so that $|f(z)| < \epsilon$ for z on the circle. By Cauchy, the value $f(\alpha)$ is the average of the values f(z) on the circle, so $|f(\alpha)| < \epsilon$. Since this is true for any $\epsilon > 0$, we must have $|f(\alpha)| = 0$, so $f(\alpha) = 0$. This holds for each $\alpha \in \mathbb{C}$.

- Finally, suppose there were a polynomial function g(z) with no roots. Then the function f(z) = 1/g(z) would be analytic on the whole plane, and $|g(z)| = 1/|f(z)| \to 0$ for $|z| \to \infty$, since deg $g(z) \ge 1$. But by Liouville, f(z) can only be the zero constant function, a contradiction.
- Note that the innocent-looking *non-analytic* function:

$$f(z) = z\bar{z} + 1 = |z|^2 + 1$$

has no roots! Analytic functions are very special.

$$f(z) = z^2 + (1+i)z + 1$$

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$f(z) = z^2$

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Lecture: Mon 10/31

- 1. Electromagnetic vector fields
 - Let g(x, y) = (r(x, y), s(x, y)) be any vector field.
 - Divergence of g measures rate of outflow from each point:

div
$$g(x, y) := \frac{\partial r}{\partial x} + \frac{\partial s}{\partial y} = r_x(x, y) + s_y(x, y)$$
.

• Curl of g measures counter-clockwise torque (rotational force) around each point:

$$\operatorname{curl} g(x,y) := \frac{\partial s}{\partial x} - \frac{\partial r}{\partial y} = s_x(x,y) - r_y(x,y).$$

• An electric force field g(x, y) satisfies Maxwell's equations: the curl and divergence must vanish at all points:

$$\operatorname{curl} g(x, y) = \operatorname{div} g(x, y) = 0.$$

That is:

(Maxwell) $r_x = -s_y$, $r_y = s_x$.

These equations hold in a region with no charge present. In general, div g is the charge density at each point.

- 2. Complex analytic vs electric vector fields
 - Let f(x + iy) = u(x, y) + iv(x, y) be complex analytic, meaning it satisfies:

(Cauchy-Riemann) $u_x = v_y$, $u_y = -v_x$.

• Proposition: Given f(x+iy), let g(x, y) be the complex conjugate vector field: $g(z) := \overline{f(x+iy)}$,

$$g(x, y) := (u(x, y), -v(x, y)).$$

Then clearly:

f(x, y) complex analytic $\iff g(x, y)$ satisfies Maxwell.

- Example: f(z) = z, g(x, y) = (x, -y). Then f(z) is analytic everywhere and $\operatorname{curl} g = \operatorname{div} g = 0$.
- *Example:* f(z) = 1/z,

$$g(x,y) = \frac{(x,y)}{x^2 + y^2}$$
 = point-charge,

an outward force proportional to inverse of distance (which is the 2-dimensional version of Coulomb's Law). Then f(z) is analytic except at the origin, and g(x, y) satisfies Maxwell except at the origin, where there is a point-charge with infinite charge-density: div $g(0, 0) = \infty$.

- Example: g(z) = (x, y) corresponds to $f(z) = \overline{z}$. Then f(z) is not analytic, and g(x, y) does not satisfy Maxwell's equations, since $\operatorname{curl} g(x, y) = 0$ but div g(x, y) = 2 everywhere.
- 3. Parametrized curves in the plane
 - Parametrized curve: C = c(t) = (x(t), y(t)) for $a \le t \le b$. We can imagine c(t) as the position at time t of a particle moving along C from the start point c(a) = (x(a), y(a)) to the end point c(b) = (x(b), y(b)). C is a closed curve if c(a) = c(b).
 - Tangent vector at point c(t):

$$c'(t) = \lim_{\epsilon \to 0} \frac{c(t+\epsilon) - c(t)}{\epsilon} = (x'(t), y'(t)).$$

Rephrasing: for two points $c_0 = c(t_0)$ and $c_1 = c(t_1)$ close together along C, the increment vector between them is approximately the velocity vector multiplied by the time increment:

$$c_1 - c_0 \approx c'(t_1) (t_1 - t_0) = c'(t_1) \Delta t_1$$

- Example: $C = c(t) = (\cos t, \sin t)$ for $0 \le t \le 2\pi$, unit circle. Tangent vector at c(t) is: $c'(t) = (-\sin t, \cos t)$. For $t = \pi/2$, c(t) = (0, 1), c'(t) = (-1, 0).
- 4. Circulation around a curve
 - We wish to measure the total drag or circulation of g(x, y) pushing around a closed curve C. This is a large-scale version of curl g, which measures the rate of circulation of g(x, y) near a particular point.

• Drag: The drag of a constant vector field g(x, y) = (c, d) along the line segment from (0, 0) to (p, q) is the dot-product:

$$(c,d) \cdot (p,q) = cp + dq$$

the product of vector lengths times cos of the angle between.

• Circulation line integral of g(x, y) along C. Mark N points of C:

$$c_0, c_1, \ldots, c_N = c_0,$$

with $c_j = c(t_j)$. We have:

$$c_j - c_{j-1} \approx c'(t_j) (t_j - t_{j-1}) = c'(t_j) \Delta t_j$$

We can compute the total circulation of g(x, y) around C by adding up the drag along each tiny line segment from c_{j-1} to c_j :

$$\oint_{\mathcal{C}} g(x,y) \cdot dc := \lim_{N \to \infty} \sum_{j=1}^{N} g(c_j) \cdot (c_j - c_{j-1})$$
$$:= \lim_{N \to \infty} \sum_{j=1}^{N} g(c(t_j)) \cdot c'(t_j) \Delta t_j$$
$$= \int_{t=a}^{b} g(c(t)) \cdot c'(t) dt.$$

Note that $g(c(t)) \cdot c'(t)$ is a scalar-valued function of t, so the last line is an ordinary integral.

• Example: Let $C = (\cos t, \sin t)$ for $0 \le t \le 2\pi$, and g(x, y) = (1, 0)a horizontal constant vector field. Since the drag on top of the curve cancels the opposite drag on the bottom, we expect zero circulation. In fact:

$$\oint_{\mathcal{C}} g(c) \cdot dc = \int_{t=0}^{2\pi} g(\cos t, \sin t) \cdot (\cos' t, \sin' t) dt$$
$$= \int_{t=0}^{2\pi} (1,0) \cdot (-\sin t, \cos t) dt = \int_{t=0}^{2\pi} \sin t \, dt = 0.$$

- 5. Global outflow via line integrals
 - We wish to measure the total outflow or flux of g(x, y) across a closed curve C. This is a large-scale version of div g(x, y), which measures the rate of outflow near a particular point.

• Flux: The flow of a constant vector field g(x, y) = (c, d) across a line segment from (0, 0) to (p, q) is the cross-product:

$$(c,d) \times (p,q) = cq - dp,$$

the product of vector lengths times sin of the angle between.

• Flux line integral of g(x, y) along C. As before, we compute the total outflow as:

$$\oint_{\mathcal{C}} g(x,y) \times dc = \lim_{N \to \infty} \sum_{j=1}^{N} g(c_j) \times (c_j - c_{j-1}) = \int_{t=a}^{b} g(c(t)) \times c'(t) dt.$$

• Example: Again let $C = (\cos t, \sin t)$ and g(x, y) = (1, 0). Since inflow on the left should cancel outflow on the right, we expect zero flux. In fact:

$$\oint_{\mathcal{C}} g(c) \times dc = \int_{t=0}^{2\pi} (1,0) \times (-\sin t, \cos t) \, dt = \int_{t=0}^{2\pi} \cos t \, dt = 0 \, .$$

- 6. Green's Theorems: global versus local
 - Let R be a region on the plane whose boundary is a simple closed curve C (oriented counter-clockwise). Let g(x, y) be vector field which is defined and differentiable at every point of R.
 - *Theorem:* The circulation of g around the boundary curve is equal to the total curl of g inside the region:

$$\oint_{\mathcal{C}} g(c) \cdot dc = \iint_{R} \operatorname{curl} g(x, y) \, dx \, dy$$

where the right side is a double integral over the region R.

• *Theorem:* The flux of g around the boundary curve is equal to the total divergence of g inside the region:

$$\oint_{\mathcal{C}} g(c) \times dc = \iint_{R} \operatorname{div} g(x, y) \, dx \, dy.$$

- *Proof:* Divide R into little regions, and write the total line integral as a sum of line integrals over tiny regions. Inside each tiny region, g(x, y) can be replaced by its linear approximation, so that we can compute the tiny line integrals to be the area times curl g or div g.
- Corollary: If g(x, y) is an electical force field with $\operatorname{curl} g = \operatorname{div} g = 0$ inside the region R, then g has zero circulation and flux over the boundary curve C:

$$\oint_{\mathcal{C}} g(c) \cdot dc = \oint_{\mathcal{C}} g(c) \times dc = 0$$

Lecture: Wed 11/2

- 1. Complex line integral
 - Given a complex derivative F'(z), we would like to recover the orginal function F(z) by integrating. This is done as follows: let C be a non-closed curve with start-point $\alpha = c(a)$ and end-point $\beta = c(b)$. Mark N points $\alpha = c_0, c_1, \ldots, c_N = \beta$, with $c_j = c(t_j)$. Then:

$$F(\beta) - F(\alpha) = \lim_{N \to \infty} \sum_{j=1}^{N} F(c_j) - F(c_{j-1})$$

=
$$\lim_{N \to \infty} \sum_{j=1}^{N} \frac{F(c_j) - F(c_{j-1})}{c_j - c_{j-1}} \frac{c_j - c_{j-1}}{\Delta t_j} \Delta t_j$$

=
$$\int_{t=a}^{b} F'(c(t)) c'(t) dt$$

• Thus, the correct integral to use is the *complex line integral*:

$$\oint_{\mathcal{C}} f(z) \, dz := \int_{t=a}^{b} f(c(t)) \, c'(t) \, dt \,,$$

where the product in the integral is complex multiplication, and the result is a complex number. That is, if f(x + iy) = u(x, y) + iv(x, y) and c(t) = x(t) + iy(t), then:

$$\oint_{\mathcal{C}} f(z) dz = \int_{t=a}^{b} u(c(t)) x'(t) - v(c(t)) y'(t) dt + i \int_{t=a}^{b} u(c(t)) y'(t) + v(c(t)) x'(t) dt$$

• Fundamental Theorem of Calculus: If F(z) is analytic, and C is a (not necessarily closed) curve from α to β , then:

$$F(\beta) - F(\alpha) = \oint_{\mathcal{C}} F'(z) dz.$$

• Example: f(z) = 1/z, $C = c(t) = (r \cos t, r \sin t)$. Then $f(x+iy) = (x-iy)/(x^2+y^2)$, and:

$$\oint_{\mathcal{C}} f(z) dz = \int_{t=0}^{2\pi} f(r \cos t + ir \sin t) (r \cos' t + ir \sin' t) dt$$
$$= \int_{t=0}^{2\pi} \frac{1}{r^2} (r \cos t - ir \sin t) (-r \sin t + ir \cos t) dt$$
$$= \int_{t=0}^{2\pi} i (\cos^2 t + \sin^2 t) dt = 2\pi i$$

- 2. Cauchy Integral Theorem
 - Theorem: If R is a plane region whose boundary is the closed curve C, and f(z) is complex analytic for every $z \in R$, then the complex line integral of f(z) over C is zero:

$$\oint f(z) \, dz = 0$$

• First Proof: If we can find F(z) with f(z) = F'(z), and we take $\alpha = \beta$ being the start- and end-point of the closed curve C, then:

$$\int_{\mathcal{C}} f(z) \, dz = F(\alpha) - F(\beta) = 0 \, .$$

For example, if $f(z) = z^2 + 1$ then we can take $F(z) = \frac{1}{3}z^3 + z$. But how do we find such an F(z) in general? For example, f(z) = 1/zdoes *not* satisfy the Theorem, so it *cannot* be the derivative of any function F(z). We need a better proof.

• Second Proof: We reduce the complex line integral of f(z) to circulation and flux integrals of the corresponding electric field, the conjugate $g(z) := \overline{f(z)}$ with curl $g = \operatorname{div} g = 0$. First, note that the complex product relates to the dot and cross products as follows:

$$\alpha \,\beta = \overline{\alpha} \cdot \beta + \overline{\alpha} \times \beta \,.$$

(Just write out real and imaginary parts of both sides.) Thus:

$$\begin{split} \oint_{\mathcal{C}} f(z) \, dz &= \int_{t=a}^{b} f(c(t)) \, c'(t) \, dt \\ &= \int_{t=a}^{b} \overline{f(c(t))} \cdot c'(t) \, dt + i \int_{t=a}^{b} \overline{f(c(t))} \times c'(t) \, dt \\ &= \oint_{\mathcal{C}} g(c) \cdot dc + i \oint_{\mathcal{C}} g(c) \times dc \\ &= \iint_{R} \operatorname{curl} g(x, y) \, dx \, dy + i \iint_{R} \operatorname{div} g(x, y) \, dx \, dy = 0 \end{split}$$

- 3. Cauchy Mean Value Theorem
 - Let $C = C(r, \gamma)$ be a circle with radius r and center γ , and suppose f(z) is complex analytic in the disk bounded by C. Then the average value of f(z) on the circle C is equal to the value $f(\gamma)$ in the center:

$$\frac{1}{2\pi r} \int_{\mathcal{C}(r,\gamma)} f(c(t)) \left| c'(t) \right| dt = f(\gamma) \,.$$

• Proof: First, note that $c'(t) = i(c(t) - \gamma)$, so:

$$\oint_{\mathcal{C}} \frac{f(z)}{z - \gamma} dz = \int_{t=0}^{2\pi} \frac{f(c(t))}{c(t) - \gamma} c'(t) dt$$

= $i \int_{t=0}^{2\pi} f(c(t)) dt$
= $\frac{i}{r} \int_{t=0}^{2\pi} f(c(t)) |c'(t)| dt$.

Thus, the average value can be computed as:

$$A(r) := \frac{1}{2\pi r} \int_{\mathcal{C}(r,\gamma)} f(c(t)) \, |c'(t))| \, dt = \frac{1}{2\pi i} \oint_{\mathcal{C}(r,\gamma)} \frac{f(z)}{z - \gamma} \, dz$$

Let \mathcal{D} be the closed curve which first rounds the circle $\mathcal{C}(r, \gamma)$ counterclockwise, then traverses a radial line segment from radius r to a smaller radius ϵ , then rounds the circle $\mathcal{C}(\epsilon, \gamma)$ clockwise, then goes back along the same radis from ϵ to r.

The closed curve \mathcal{D} is the boundary of a ring-shaped region in which $f(z)/(z-\gamma)$ is analytic, so that the complex integral vanishes by Cauchy's Theorem:

$$0 = \oint_{\mathcal{D}} \frac{f(z)}{z - \gamma} dz = \oint_{\mathcal{C}(r,\gamma)} \frac{f(z)}{z - \gamma} dz - \oint_{\mathcal{C}(\epsilon,\gamma)} \frac{f(z)}{z - \gamma} dz = A(r) - A(\epsilon) dz$$

That is, the average does not depend on the radius of the circle. But f(z) is continuous, so as the circle $C(r, \epsilon)$ approaches the central point γ , the average value of f(z) on the circle approaches $f(\gamma)$:

$$A(r) = A(\epsilon) = \lim_{\epsilon \to 0} A(\epsilon) = f(\gamma) \,.$$

Math 418H

Lecture: Mon 11/7

- 1. Fundamental Theorem of Algebra
 - *Theorem:* Any polynomial

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$$f(z) = a_0 + a_1 z + \dots + a_n z^n \in \mathbb{C}[z]$$

of degree $n \ge 1$ has at least one complex root $z = \alpha$ with $f(\alpha) = 0$.

• First step: We give a proof by contradiction. Suppose f(z) were a polynomial with no roots. Then its reciprocal g(z) := 1/f(z) would be analytic everywhere. Furthermore:

$$\lim_{|z|\to\infty} |f(z)| = \lim_{|z|\to\infty} |a_n z^n| = \infty,$$

meaning that f(z) has large radius if z is far from the origin. Thus $\lim_{|z|\to\infty} g(z) = 0$, meaning that g(z) has small radius when z is far from the origin.

• Second step, Liouville's Theorem: Let g(z) be a function which is complex analytic on the whole plane, with $\lim_{|z|\to\infty} g(z) = 0$. Then g(z) can only be the zero constant function: g(z) = 0 for all z.

Proof: Consider any particular $\gamma \in \mathbb{C}$, and take a very large circle $\mathcal{C}(r,\gamma)$ with radius r and center γ . Given $\epsilon > 0$, by assumption we can take radius large enough so that $|g(z)| < \epsilon$ for z on the circle $\mathcal{C}(r,\gamma)$. By Cauchy's Mean Value Theorem, the value $g(\gamma)$ at the center is the average of the value of g(z) on the circle $\mathbb{C}(r,\gamma) = c(t)$:

$$g(\gamma) = \operatorname{Avg}_{c \in \mathcal{C}(r,\gamma)} g(c) := \frac{1}{2\pi r} \int g(c(t)) |c'(t)| dt.$$

Taking lengths and applying the triangle inequality,

$$|\operatorname{Avg}_{\mathcal{C}} F(c)| \le \operatorname{Avg}_{\mathcal{C}} |F(c)|,$$

we have:

$$|g(\gamma)| = |\operatorname{Avg}_{\mathcal{C}(r,\gamma)} g(c)| \le \operatorname{Avg}_{\mathcal{C}(r,\gamma)} |g(c)| \le \epsilon \,.$$

Since this is true for any $\epsilon > 0$, we must have $|g(\gamma)| = 0$. This holds for each $\gamma \in \mathbb{C}$.

• Third step: Since g(z) = 1/f(z) is not the zero constant function, we have a contradiction. Thus there cannot exist any non-vanishing polynomial $f(z) \in \mathbb{C}[z]$.

- Paraphrasing: Liouville's Theorem says that if a non-constant analytic function becomes very small as $|z| \to \infty$, then g(z) must compensate for this by having non-anlytic points somewhere (for example, blowing up to infinity). Hence, if an analytic f(z) becomes very large as $|z| \to \infty$ (as does a polynomial), then f(z) must compensate for this by vanishing somewhere, i.e., having roots.
- This is a pure existence proof: it shows that a root-free polynomial function f(z) would lead to an analytic function g(z) violating the Cauchy Mean Value Theorem. The proof gives no clue how to find a root for a given f(z): we will give an algorithm for this next time.
- 2. Factoring polynomials
 - Proposition: Every monic complex polynomial f(z) of degree n can be uniquely factored in $\mathbb{C}[z]$ as a product of n linear functions.

$$f(z) = (z - \alpha_1) \cdots (z - \alpha_n).$$

That is, the irreducible polynomials of $\mathbb{C}[z]$ are linear.

Proof: By the Fundamental Theorem, f(z) has a root $z = \alpha$ and thus a linear factor: $f(z) = (z-\alpha_1) f_1(z)$, where $f_1(z)$ has degree n-1. Repeat this for $f_1(z)$ until all factors are linear.

• Proposition: Every monic real polynomial f(z) of degree n can be uniquely factored in $\mathbb{R}[z]$ as a product of linear and quadratic functions:

$$f(z) = (z - \alpha_1) \cdots (z - \alpha_k) q_1(z) \cdots q_\ell(z),$$

where $\alpha_j \in \mathbb{R}$, $q_j(z) \in \mathbb{R}[z]$ has degree 2, and $k + 2\ell = n$. That is, the irreducible polynomials of $\mathbb{R}[z]$ are linear and quadratic.

Proof: A real polynomial $f(z) \in \mathbb{R}[z]$ can be factored into complex linear factors as above. But if $f(\alpha) = 0$, then $f(\overline{\alpha}) = \overline{f(\alpha)} = 0$, so the non-real roots come in complex conjugate pairs. Each such pair $\alpha \neq \overline{\alpha}$ with $\alpha = a + bi$ gives a real factor:

$$(z-\alpha)(z-\overline{\alpha}) = z^2 + (\alpha + \overline{\alpha})z + \alpha\overline{\alpha} = z^2 + 2az + (a^2 + b^2) \in \mathbb{R}[z]$$

These factors are irreducible in $\mathbb{R}[z]$ since their roots $\alpha, \overline{\alpha}$ are not in \mathbb{R} by assumption.

• Example: Let $f(z) = z^4 + 1$, having roots $\alpha_1 = \operatorname{cis}(\frac{\pi}{4}) = \frac{\sqrt{2}}{2}(1+i)$, $\alpha_2 = \operatorname{cis}(\frac{3\pi}{4}) = \frac{\sqrt{2}}{2}(-1+i)$, and their conjugates $\overline{\alpha}_1$, $\overline{\alpha}_2$. Factoring:

$$f(z) = (z - \alpha_1)(z - \overline{\alpha}_1)(z - \alpha_2)(z - \overline{\alpha}_2)$$

= $(z^2 + (\alpha_1 + \overline{\alpha}_1) z + \alpha_1 \overline{\alpha}_1) (z^2 + (\alpha_2 + \overline{\alpha}_2) z + \alpha_2 \overline{\alpha}_2)$
= $(z^2 + \sqrt{2} z + 1) (z^2 - \sqrt{2} z + 1)$