## HW DUE 03/28

## MATH 309, SECTION 6

Problems: 5.2: 4bc, 6; 6.2: 8ab, 12; 6.4: 2; plus the following:

(1) Show that if  $T: V \to W$  is a linear map, then the image of T

$$\operatorname{Im}(T) = \{ \mathbf{w} \in W \mid \mathbf{w} = T(\mathbf{v}) \text{ for some } \mathbf{v} \in V \}$$

is a subspace of W.

(2) Consider the linear operator  $T : \mathbb{R}^4 \to \mathbb{R}^2$  given by

$$T\begin{bmatrix} x_1\\ x_2\\ x_3\\ x_4 \end{bmatrix} = \begin{bmatrix} x_1 & +3x_2 & +2x_4\\ & & x_3 & +3x_4 \end{bmatrix}.$$

Calculate and find a basis for both  $\operatorname{Ker} T$  and  $\operatorname{Im} T$ .

(3) Consider the linear operator  $T : \mathbb{R}^3 \to \mathbb{R}^3$  given by

$$T\begin{bmatrix} x_1\\ x_2\\ x_3 \end{bmatrix} = \begin{bmatrix} x_1 & +x_3\\ x_2 & +x_3\\ x_1 & +2x_2 & +2x_3 \end{bmatrix}.$$

Find a basis for  $\operatorname{Ker} T$  and  $\operatorname{Im} T$ .

- (4) (6.7:4) Suppose  $T : V \to W$  is linear and Ker  $T = \{\mathbf{0}\}$ . Prove that if  $\{\mathbf{v}_1, \ldots, \mathbf{v}_n\}$  is a linearly independent subset of V, then  $\{T(\mathbf{v}_1), \ldots, T(\mathbf{v}_n)\}$  is a linearly independent subset of W.
- (5) (6.7:5) Suppose  $T: V \to W$  is linear and onto. Suppose  $\{\mathbf{v}_1, \ldots, \mathbf{v}_n\}$  spans V. Show that  $\{T(\mathbf{v}_1), \ldots, T(\mathbf{v}_n)\}$  spans W.

Sample problem worked out: Consider the linear operator  $\mathbb{R}^3 \to \mathbb{R}^3$  given by

$$T\begin{bmatrix}x\\y\\z\end{bmatrix} = \begin{bmatrix}x&+z\\y&+z\\x&+y&+2z\end{bmatrix}.$$

The kernel of T is all (x, y, z) such that T(x, y, z) = (0, 0, 0); i.e. solutions to

$$\begin{bmatrix} x & +z \\ y & +z \\ x & +y & +2z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}.$$

We easily solve this system using Gaussian elimination:

$$\begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 1 & 1 & 2 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

The third column represents a free variable, so we have the solution space is

$$\operatorname{Ker} T = \{(-r, -r, r) \mid r \in \mathbb{R}\}\$$
  
=  $\{r(-1, -1, 1) \in \mathbb{R}^3 \mid r \in \mathbb{R}\}\$   
=  $span\{(-1, -1, 1)\}$ 

Therefore, (-1, -1, 1) is a basis for Ker *T*, and  $(\frac{-1}{\sqrt{3}}, \frac{-1}{\sqrt{3}}, \frac{1}{\sqrt{3}})$  is an orthonormal basis for Ker *T*.

To calculate the image, it is easiest to write it as a span of a finite set of vectors. Note that

$$T\begin{bmatrix}x\\y\\z\end{bmatrix} = \begin{bmatrix}x&+z\\y&+z\\x&+y&+2z\end{bmatrix} = x\begin{bmatrix}1\\0\\1\end{bmatrix} + y\begin{bmatrix}0\\1\\1\end{bmatrix} + z\begin{bmatrix}1\\1\\2\end{bmatrix},$$

so Image  $T = \text{span}\{(1,0,1), (0,1,1), (1,1,2)\}$ . To write a basis for Image T, we need the vectors to be linearly independent. Checking linear independence of  $\{(1,0,1), (0,1,1), (1,1,2)\}$  uses the same Gaussian elimination as above. We quickly see that  $\{(1,0,1), (0,1,1), (1,1,2)\}$  is not linearly independent. The reduced row echelon form shows us (1,0,1) and (0,1,1) are linearly independent, and that (1,1,2) is a linear combination of the other two. Therefore,

 $Image \ T = span\{(1,0,1), (0,1,1), (1,1,2)\} = span\{(1,0,1), (0,1,1)\},$ 

and  $\{(1,0,1), (0,1,1)\}$  are linearly independent, so  $\{(1,0,1), (0,1,1)\}$  is a basis for Image T.