

BASIC FACTS ON CONNECTION AND CURVATURE

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1. GENERAL THEORY

Let M^n be a smooth manifold and $\pi : E \rightarrow M$ a rank r vector bundle over M .

Definition 1. A connection is a linear map $\nabla : \Gamma(E) \rightarrow \Gamma(T^*M \otimes E)$ s.t. for $f \in C^\infty(M), \sigma \in \Gamma(E)$

$$\nabla(f\sigma) = df \otimes \sigma + f\nabla\sigma.$$

If X is a vector field on M , we let $\nabla_X\sigma = X \lrcorner \nabla\sigma$.

First note that a connection is local: if $\sigma \in \Gamma(E)$ vanishes on an open set U , then $\nabla\sigma$ also vanishes on U . Indeed, for any open V with $\bar{V} \subset U$ compact we can find $\chi \in C_c^\infty(U)$ s.t. $\chi \equiv 1$ on \bar{V} . Then we have $\sigma = (1 - \chi)\sigma$ and

$$\nabla\sigma = -d\chi \otimes \sigma + (1 - \chi)\nabla\sigma.$$

It follows that $\nabla\sigma = 0$ on V . Therefore, if two sections $\sigma_1, \sigma_2 \in \Gamma(E)$ satisfy $\sigma_1 = \sigma_2$ on U , then $\nabla\sigma_1 = \nabla\sigma_2$ on U . Consequently, for any local section $\sigma \in \Gamma(U, E)$ we can define $\nabla\sigma \in \Gamma(U, T^*M \otimes E)$ by extension.

Given a local frame $\{e_i\}$ on some open set U , we can write

$$\nabla e_i = \omega_i^j \otimes e_j,$$

with $\omega_i^j \in \mathcal{A}^1(U)$. Thus we get a matrix of 1-forms

$$\omega = \begin{bmatrix} \omega_1^1 & \cdots & \omega_r^1 \\ \vdots & & \vdots \\ \omega_1^r & \cdots & \omega_r^r \end{bmatrix}.$$

A local section σ on U can then be written as $\sigma = \sum_i f^i e_i$ with $f^i \in C^\infty(U)$. We have

$$\nabla\sigma = \sum_i (df^i + \omega_j^i f^j) \otimes e_i.$$

If we write $f = (f_1, \dots, f_r)^t$ as a column vector, then the connection is locally given by the map

$$f \rightarrow df + \omega f.$$

If we use another local frame $\{\tilde{e}_i\}$ on V , the connection is then determined by another matrix of 1-forms $\tilde{\omega}$ on V : $\nabla\tilde{e}_i = \tilde{\omega}_i^j \otimes \tilde{e}_j$. On $U \cap V$

$$\tilde{e}_i = a_i^j e_j,$$

with $A = \begin{bmatrix} a_i^j \end{bmatrix} \in C^\infty(U \cap V, GL(r, \mathbb{R}))$. Then

$$\nabla \tilde{e}_i = \left(da_i^j + a_i^k \omega_k^j \right) \otimes e_j.$$

On the other hand, $\nabla \tilde{e}_i = \tilde{\omega}_i^j \otimes \tilde{e}_j = \tilde{\omega}_i^k a_k^j \otimes e_j$. Therefore

$$\tilde{\omega}_i^k a_k^j = da_i^j + a_i^k \omega_k^j,$$

i.e. $A\tilde{\omega} = dA + \omega A$. Or, equivalently

$$\tilde{\omega} = A^{-1}dA + A^{-1}\omega A.$$

Let $\mathcal{A}^k(E) = \Gamma(\Lambda^k(M) \otimes E)$ be the space of E -valued differential k -forms. We can extend the connection to $\nabla : \mathcal{A}^k(E) \rightarrow \mathcal{A}^{k+1}(E)$ as follows: given $\sigma \in \mathcal{A}^k(U, E)$ we can write

$$\sigma = \sum_i \theta^i \otimes e_i,$$

where $\theta^i \in \mathcal{A}^k(U)$. Then we define

$$\begin{aligned} \nabla \sigma &= \sum_i d\theta^i \otimes e_i + (-1)^k \theta^i \wedge \nabla e_i \\ &= \sum_i (d\theta^i + \omega_k^i \wedge \theta^k) \otimes e_i. \end{aligned}$$

It is easy to verify this is well defined.

Proposition 1. *Connections always exist. In fact, the set of all connections on a vector bundle $\pi : E \rightarrow M$ is an affine space over $\mathcal{A}^1(\text{End}E)$.*

Proof. Use a partition of unity. □

Given $\sigma \in \mathcal{A}^k(U, E)$ we calculate

$$\begin{aligned} \nabla^2 \sigma &= \sum_i [d(d\theta^i + \omega_l^i \wedge \theta^l) + \omega_k^i \wedge (d\theta^k + \omega_l^k \wedge \theta^l)] \otimes e_i \\ &= \sum_i [d\omega_l^i + \omega_k^i \wedge \omega_l^k] \wedge \theta^l \otimes e_i \\ &= \sum_i \Omega_j^i \wedge \theta^j \otimes e_i, \end{aligned}$$

with $\Omega_j^i = d\omega_j^i + \omega_k^i \wedge \omega_j^k$. The matrix of 2-forms $\Omega = \begin{bmatrix} \Omega_j^i \end{bmatrix}$ is called the curvature of the connection. We have

$$\Omega = d\omega + \omega \wedge \omega.$$

If we use another frame, then

$$\begin{aligned} \tilde{\Omega} &= d\tilde{\omega} + \tilde{\omega} \wedge \tilde{\omega} \\ &= d(A^{-1}dA + A^{-1}\omega A) \\ &\quad + (A^{-1}dA + A^{-1}\omega A) \wedge (A^{-1}dA + A^{-1}\omega A) \\ &= A^{-1}(d\omega + \omega \wedge \omega)A \\ &= A^{-1}\Omega A. \end{aligned}$$

Therefore, the curvature $\Omega \in \mathcal{A}^2(\text{End}E)$.

There is a natural induced connection on E^* . Let $\{e_i^*\}$ be the dual frame, i.e. $e_i^*(e_j) = \delta_{ij}$. Then

$$0 = \nabla e_i^*(e_j) + e_i^*(\nabla e_j).$$

This implies $\nabla e_i^* = -\omega_j^i \otimes e_j^*$. If we denote the dual frame by $\{e^i\}$ instead, then

$$\nabla e^i = -\omega_j^i \otimes e^j.$$

Therefore

$$\nabla^2 e^i = -\Omega_j^i \otimes e^j.$$

Definition 2. Let X, Y be two vector fields on M . The curvature operator $R(X, Y) : \Gamma(E) \rightarrow \Gamma(E)$ is defined as

$$R(X, Y) = -\nabla_X \nabla_Y + \nabla_Y \nabla_X + \nabla_{[X, Y]}.$$

Theorem 1. Locally, for any section $\sigma = \sum_i f^i e_i$

$$R(X, Y)\sigma = -\sum_{i,j} \Omega_j^i(X, Y) f^j e_i.$$

Proof. First

$$\nabla_X \sigma = \sum_i (X f^i + \omega_j^i(X) f^j) e_i.$$

Hence

$$\begin{aligned} \nabla_Y \nabla_X \sigma &= \sum_i (Y X f^i + Y \omega_j^i(X) f^j + \omega_j^i(X) Y f^j) e_i \\ &\quad + \sum_i (X f^k + \omega_j^k(X) f^j) \omega_k^i(Y) e_i \\ &= \sum_i (Y X f^i + Y \omega_j^i(X) f^j + \omega_k^i(Y) \omega_j^k(X) f^j) e_i \\ &\quad + \sum_i (\omega_k^i(X) Y f^k + \omega_k^i(Y) X f^k) e_i. \end{aligned}$$

It follows that

$$\begin{aligned} &\nabla_X \nabla_Y \sigma - \nabla_Y \nabla_X \sigma - \nabla_{[X, Y]} \sigma \\ &= \sum_i (d\omega_j^i(X, Y) + \omega_k^i(X) \omega_j^k(Y) - \omega_k^i(Y) \omega_j^k(X)) f^j e_i \\ &= \sum_i \Omega_j^i(X, Y) f^j e_i. \end{aligned}$$

□

Proposition 2. (2nd Bianchi identity) The curvature matrix satisfies the following identity

$$d\Omega = \Omega \wedge \omega - \omega \wedge \Omega.$$

Proof. We calculate

$$\begin{aligned} d\Omega &= d\omega \wedge \omega - \omega \wedge d\omega \\ &= (\Omega - \omega \wedge \omega) \wedge \omega - \omega \wedge (\Omega - \omega \wedge \omega) \\ &= \Omega \wedge \omega - \omega \wedge \Omega. \end{aligned}$$

□

Proposition 3. *Suppose (E, ∇) is flat in the sense that the curvature is zero. Then $\forall p \in M$ there exists a neighborhood U and local frame $\{e_i\}$ on U s.t. $\nabla e_i = 0$.*

Proof. Pick an arbitrary local frame $\{s_i\}$ and let ω be the corresponding connection matrix. We want to find a new local frame $\{e_i\}$

$$e_i = a_i^j s_j,$$

s.t. $\nabla e_i = 0$. In other words, we want to find smooth $A = [a_j^i] \in GL(r, \mathbb{R})$ s.t.

$$dA + \omega A = 0.$$

By the Frobenius theorem, there is a local solution with $A = I$ at p if the curvature is zero. To apply Frobenius, consider the manifold $U \times \mathbb{R}^{n^2}$ with y_j^i the standard coordinates on \mathbb{R}^{n^2} . We have n^2 1-forms

$$\theta_j^i = dy_j^i + \omega_k^i y_j^k$$

which are linearly independent. We compute

$$\begin{aligned} d\theta_j^i &= d\omega_k^i y_j^k - \omega_k^i \wedge dy_j^k \\ &= \Omega_k^i y_j^k - \omega_k^i \wedge \theta_j^k. \end{aligned}$$

If $\Omega = 0$, the distribution $\mathcal{D} = \ker \{\theta_{ij}\}$ is involutive. The integral manifold passing through (p, I) is locally the graph of a function $y_j^i = a_j^i(x)$. \square

2. THE LEVI-CIVITA CONNECTION

A connection on TM is called an affine connection. For an affine connection ∇ we define its torsion by

$$\tau(X, Y) = \nabla_X Y - \nabla_Y X - [X, Y].$$

Theorem 2. *Let (M^n, g) be a Riemannian manifold. Then there exists a unique affine connection ∇ , called the Levi-Civita connection, that satisfies the following two conditions*

- (1) ∇ is compatible with the metric, i.e.

$$X \langle Y, Z \rangle = \langle \nabla_X Y, Z \rangle + \langle Y, \nabla_X Z \rangle.$$

- (2) ∇ is torsion-free, i.e.

$$\nabla_X Y - \nabla_Y X = [X, Y].$$

Let $\{e_i\}$ be a frame and $\{\theta^i\}$ the dual frame. Writing

$$g_{ij} = \langle e_i, e_j \rangle, \nabla e_i = \omega_i^j \otimes e_j,$$

we have $dg_{ij} = \omega_i^k g_{kj} + g_{ik} \omega_j^k$, i.e

$$dG = \omega^t G + G \omega.$$

It is more convenient to work with a local orthonormal frame.

Proposition 4. *Let $\{e_i\}$ be a local orthonormal frame. The connection matrix ω for the Levi-Civita connection is uniquely determined by the following two identities*

$$\omega^t = -\omega,$$

$$d\theta^i = \theta^j \wedge \omega_j^i.$$

Proof. The 2nd identity follows by direct calculation. Uniqueness follows from Cartan's lemma. \square

The curvature $\Omega = d\omega + \omega \wedge \omega$ is a skew-symmetric matrix of 2-forms. We have

$$\Omega_j^i = \frac{1}{2} R_{kl ij} \theta^k \wedge \theta^l.$$

Proposition 5. *Suppose (M^n, g) is flat in the sense that the curvature vanishes identically. Then for any $p \in M$ there is a local chart (U, x) about p s.t.*

$$g = dx_i \otimes dx_i$$

on U .

Proof. By Proposition 3 there exists a local frame $\{e_i\}$ s.t. $\nabla e_i = 0$ and $\langle e_i, e_j \rangle = \delta_{ij}$ at p . As $dg_{ij} = 0$, $\{e_i\}$ is orthonormal. Since $d\theta^i = 0$, there exist local smooth functions f_i s.t. $\theta^i = df_i$. By the implicit function theorem (f_1, \dots, f_n) is a local coordinate system near p and

$$g = \theta^i \otimes \theta^i = df_i \otimes df_i.$$

\square