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## S.MÜLLER TANG Qi <br> B.S. YAN <br> On a new class of elastic deformations not allowing for cavitation

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## Numdam

# On a new class of elastic deformations not allowing for cavitation 

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Abstract. - Let $\Omega \subset \mathbb{R}^{n}$ be open and bounded and assume that $u: \Omega \rightarrow \mathbb{R}^{n}$ satisfies $u \in \mathrm{~W}^{1, p}\left(\Omega, \mathbb{R}^{n}\right)$, adj $\mathrm{D} u \in \mathrm{~L}^{q}\left(\Omega ; \mathbb{R}^{n \times n}\right)$ with $p \geqq n-1$, $q \geqq \frac{n}{n-1}$. We show that for $g \in \mathrm{C}^{1}\left(\mathbb{R}^{n} ; \mathbb{R}^{n}\right)$ with bounded gradient, one

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has the identity $\frac{\partial}{\partial x^{j}}\left\{\left(g^{i} \circ u\right)(\operatorname{adj} \mathrm{D} u)_{i}^{j}\right\}=(\operatorname{div} g)^{\circ} u \operatorname{det} \mathrm{D} u$ in the sense of distributions. As an application, we obtain existence results in nonlinear elasticity under weakened coercivity conditions. We also use the above identity to generalize Šverák's (cf. [Sv88]) regularity and invertibility results, replacing his hypothesis $q \geqq \frac{p}{p-1}$ by $q \geqq \frac{n}{n-1}$. Finally if $q=\frac{n}{n-1}$ and if $\operatorname{det} \mathrm{D} u \geqq 0$ a.e., we show that $\operatorname{det} \mathrm{D} u \ln (2+\operatorname{det} \mathrm{D} u)$ is locally integrable.

Résumé. - Soit $\Omega \subset \mathbb{R}^{n}$ un ouvert borné et soit $u: \Omega \rightarrow \mathbb{R}^{n}$ une application dans $\mathbb{W}^{1, p}\left(\Omega ; \mathbb{R}^{n}\right)$ avec adj $\mathrm{D} u \in \mathrm{~L}^{q}\left(\Omega ; \mathbb{R}^{n \times n}\right)$ et $p \geqq n-1, q \geqq \frac{n}{n-1}$. On montre l'identité $\frac{\partial}{\partial x^{j}}\left\{\left(g^{i} \circ u\right)(\operatorname{adj} \mathrm{D} u)_{i}^{j}\right\}=(\operatorname{div} g) \circ u \operatorname{det} \mathrm{D} u$ au sens de distributions si $g \in \mathbf{C}^{1}\left(\mathbb{R}^{n} ; \mathbb{R}^{n}\right)$ avec gradient borné. Par conséquence on obtient des nouveaux résultats d'existence en élasticité non linéaire. On obtient aussi une généralisation de résultats de Šverák sur la régularité et l'invertibilité en remplaçant l'hypothèse $q \geqq \frac{p}{p-1}$ par $q \geqq \frac{n}{n-1}$. Finalement si $q=\frac{n}{n-1}$ et $\operatorname{det} \mathrm{D} u \geqq 0$ p.p. on montre que $\operatorname{det} \mathrm{D} u \ln (2+\operatorname{det} \mathrm{D} u)$ est localement intégrable.

## 1. INTRODUCTION

Let $\Omega$ be a bounded open set in $\mathbb{R}$. In this paper we study the properties of maps $u: \Omega \rightarrow \mathbb{R}^{n}$ which belong to the Sobolev spaces $\mathrm{W}^{1, p}\left(\Omega ; \mathrm{R}^{n}\right)$ for "low" values of $p$ and discuss applications to nonlinear elasticity. There is a striking difference in the behaviour of such maps for different values of $p$. If $p>n$, then $u$ behaves, in many ways, like a Lipschitz or even $\mathrm{C}^{1}$ map. Specifically, it has a continuous representative, maps null sets onto null sets, the area formula holds (see Marcus and Mizel [MM73]), global topological arguments apply (see Ball [Ba81] and Ciarlet and Necas [CN87]) and the Jacobian det $\mathrm{D} u$ is weakly (sequentially) continuous as a map from $\mathbf{W}^{1, p}$ to $\mathbf{L}^{p / n}$ (see Reshetnyak [Re67] and Ball [Ba77]).

By contrast, many of these properties may fail if $p \leqq n$. Besicovitch [Be50] constructed a continuous map from the closed unit disk $\overline{\mathrm{D}} \subset \mathbb{R}^{2}$ to $\mathbb{R}^{3}$ which is in $W^{1,2}\left(\mathrm{D} ; \mathbb{R}^{3}\right)$ and whose image has positive three-dimensional Lebesgue measure. More recently Maly and Martio [MM92] have resolved a long-standing question by giving an example of a continuous map $u \in \mathrm{~W}^{1, n}\left(\Omega ; \mathbb{R}^{n}\right)$ satisfying det $\mathrm{D} u=0$ a.e. for which $u(\Omega)$ has positive measure. Counterexamples to the weak continuity of the Jacobian were given by Ball and Murat [BM84]. Müller, Spector and Tang [MST91] gave another example that topological arguments may fail drastically by constructing a map satisfying $u \in \mathbf{W}^{1, p}\left(\mathrm{D} ; \mathbb{R}^{2}\right)$ for all $p<2$ with $\left.u\right|_{\partial \mathrm{D}}=\mathrm{id}$ such that $u$ is injective on $\mathrm{D} \backslash \mathrm{N}$ (where N is a null set) and such that the image of $u$ contains sets of positive measure both in D and in $\mathbb{R}^{2} \backslash \overline{\mathrm{D}}$. Here care has to be taken with the definition of the image but the pathology occurs with all reasonable definitions, see the paper quoted above for details.

The study of maps in $\mathrm{W}^{1, p}$ with $p<n$ is of great interest in nonlinear elasticity. First, for commonly used stored-energy density functions, there exist deformations with finite energy which are not in $\mathrm{W}^{1, n}$ (cf. the discussion in [Ba77]). Secondly, Ball [Ba82] has shown that in these function classes, discontinuous equilibrium solutions with a discontinuity corresponding to the formation of a cavity can occur. The functions studied there are of the following type $\left[\mathrm{B}(0, r)\right.$ denotes the ball in $\mathbb{R}^{n}$ with center 0 and radius $r$ ]

$$
u: x \rightarrow \mathrm{R}(|x|) \frac{x}{|x|}: \mathrm{B}(0,1) \rightarrow \mathrm{B}(0, \mathrm{R}(1))
$$

with $\mathrm{R}(t)>0, \mathrm{R}^{\prime}(t)>0, \mathrm{R}(0)>0$.



An existence theorem in that class is still outstanding due to the failure of weak continuity of the Jacobian. Therefore Ball's methods do not apply directly.

In the current work we do not attack that problem (see Müller and Spector [MS92] for some progress in that direction) but rather extend previous weak continuity and regularity results thus allowing for weaker growth conditions in the existence theory. Following Ball [Ba77] and Šverák [Sv88], we consider function classes which involve not only information on the gradient $\mathrm{D} u$ but also on its adjugate matrix (the transpose of the cofactor matrix) adj $\mathrm{D} u$. Geometrically adj $\mathrm{D} u$ controls the deformation of (codimension 1) surface elements while $\mathrm{D} u$ controls the deformation of line elements. In the context of elasticity, certain commonly used storedenergy densities (like those proposed by Ogden [Og72]) lead to, in their simplest form, an energy density of the form

$$
\begin{equation*}
\mathrm{W}(\mathrm{~F})=\alpha|\mathrm{F}|^{p}+\beta|\operatorname{adj} \mathrm{F}|^{q}+h(\operatorname{det} \mathrm{~F}), \tag{1.1}
\end{equation*}
$$

where $\alpha, \beta>0$ and where $h$ is a non-negative and convex function. We thus consider the function classes

$$
\begin{gathered}
\mathrm{A}_{p, q}(\Omega)=\left\{u \in \mathbf{W}^{1, p}\left(\Omega ; \mathbb{R}^{n}\right): \operatorname{adj} \mathrm{D} u \in \mathrm{~L}^{q}\left(\Omega ; \mathbb{R}^{n \times n}\right)\right\}, \\
\mathrm{A}_{p, q}^{+}(\Omega)=\left\{u \in \mathrm{~A}_{p, q}(\Omega): \operatorname{det} \mathrm{D} u>0 \text { a.e. }\right\}
\end{gathered}
$$

the latter class being motivated by the fact that a deformation of an elastic body should be orientation preserving. In his remarkable paper, Šverák [Sv88] showed that if $u \in \mathrm{~A}_{p, q}(\Omega)$ with $p \geqq n-1, q \geqq \frac{p}{p-1}$ and if the trace $\left.u\right|_{\partial \Omega}$ satisfies certain regularity and continuity conditions then the following
degree formula holds (see section 2 and [Sc69] for the definition of the Brouwer degree)

$$
\begin{equation*}
\int_{\Omega}(f \circ u) \operatorname{det} \mathrm{D} u d x=\operatorname{deg}\left(u, \partial \Omega, y_{0}\right) \int_{\mathbb{R}^{n}} f(y) d y \tag{1.2}
\end{equation*}
$$

provided that $f$ is smooth and has its support in the connected component of $\mathbb{R}^{n} \backslash u(\partial \Omega)$ which contains $y_{0}$. Šverak observed that (1.2) rules out cavitation. For the example $x \rightarrow \frac{x}{|x|} \mathrm{R}(|x|), \mathrm{R}(0)>0, \mathrm{R}^{\prime}(t)>0$, which is a map with cavitation it suffices to choose $f$ with support in $\mathrm{B}(0, \mathrm{R}(0))$. For $u \in \mathrm{~A}_{p, q}^{+}(\Omega)$ it allows one to define a set-valued image $\mathrm{F}(a, u)$ for every $a \in \Omega$. Moreover, he deduces from (1.2) that functions in $\mathrm{A}_{p, q}^{+}(\Omega)$ are continuous (not just approximately or finely continuous) outside a set of Hausdorff dimension $n-p$. Under additional conditions on the boundary values, he shows the existence of an inverse function defined almost everywhere and analyses its regularity (see also Tang Qi [TQ88]). The condition on $q$ at first glance appears to be natural in view of the identity

$$
\begin{equation*}
(\operatorname{det} F) I d=F(\operatorname{adj} F), \tag{1.3}
\end{equation*}
$$

which by Hölder's inequality gives $\operatorname{det} \mathrm{D} u \in \mathrm{~L}^{1}$ if $q \geqq \frac{p}{p-1}$.
In the current work we generalize the degree formula and all of its consequences to the case $q \geqq \frac{n}{n-1}$. Note that one has, by taking determinant in (1.3),

$$
\begin{equation*}
|\operatorname{det} \mathrm{F}| \leqq|\operatorname{adj} \mathrm{F}|^{n /(n-1)} \tag{1.4}
\end{equation*}
$$

so that still $\operatorname{det} \mathrm{D} u \in \mathrm{~L}^{1}$ in this case. The most important result of this paper is the following divergence identity.

Theorem A. - Let $p \geqq n-1, q \geqq \frac{n}{n-1}, u \in \mathrm{~A}_{p, q}(\Omega), g \in \mathrm{C}^{1}\left(\mathbb{R}^{n} ; \mathbb{R}^{n}\right)$ with $|\mathrm{D} g| \leqq \mathrm{C}$. Consider the distribution

$$
h:=\frac{\partial}{\partial x^{j}}\left\{\left(g^{i} \circ u\right)(\operatorname{adj} \mathrm{D} u)_{i}^{j}\right\} .
$$

Then

$$
\begin{equation*}
h=(\operatorname{div} g)^{\circ} u \operatorname{det} \mathrm{D} u \tag{1.5}
\end{equation*}
$$

in the sense of distributions (and hence in $\mathrm{L}^{1}$ ).
For smooth functions, (1.5) follows from the fact that adj $\mathrm{D} u$ is diver-gence-free, i.e.

$$
\begin{equation*}
\frac{\partial}{\partial x^{j}}(\operatorname{adj} \mathrm{D} u)_{i}^{j}=0 \quad \text { for } \quad i=1, \ldots, n \tag{1.6}
\end{equation*}
$$

(see [Mo66], Lemma 4.4.6; here as in the following we employ the summation convention) in connection with (1.3). If $q \geqq \frac{p}{p-1}$, then (1.5) can be established by approximating $u$ by smooth functions $u^{(v)}$ and $\operatorname{adj} \mathrm{D} u$ by divergence free $b^{(v)}$. To obtain (1.5) for $q \geqq \frac{n}{n-1}$ we exploit the geometric significance of $\operatorname{adj} \mathrm{D} u$ and not just (1.6) and make, in particular, use of a suitable version of the isoperimetric inequality (see Lemma 3.1, Theorem 3.2 and their proofs).

In the critical case $q=\frac{n}{n-1}$, one obtains $\operatorname{det} \mathrm{D} u \in \mathrm{~L}^{1}(\Omega)$ from (1.4) and by scaling arguments one would, in general, expect no better estimate. If det $\mathrm{D} u \geqq 0$, one has, however, the following higher integrability property which generalizes the results in [Mu89] and [Mu90b]. Other interesting higher integrability results have recently been obtained by Iwaniec and Sbordone [IS91], Brezis, Fusco and Sbordone [BFS92], Greco and Iwaniec [GI92] and Iwaniec and Lutoborski [IL92].

Theorem B. - Let $u \in \mathrm{~A}_{n-1, n /(n-1)}(\Omega)$ and assume that $\operatorname{det} \mathrm{D} u \geqq 0$ a.e. Then $\operatorname{det} \mathrm{D} u \ln (2+\operatorname{det} \mathrm{D} u) \in \mathrm{L}_{\mathrm{loc}}^{1}(\Omega)$. More precisely if $\mathrm{B}(a, 2 r) \subset \Omega$, we have

$$
\int_{\mathrm{B}(a, r)} \operatorname{det} \mathrm{D} u \ln \left(2+\frac{\operatorname{det} \mathrm{D} u}{(\operatorname{det} \mathrm{D} u)_{\mathrm{B}}}\right) d x \leqq \mathrm{C} \int_{\mathrm{B}(a, 2 r)}|\operatorname{adj} \mathrm{D} u|^{n /(n-1)} d x,
$$

where

$$
(\operatorname{det} \mathrm{D} u)_{\mathrm{B}}=\int_{\mathrm{B}(a, r)} \operatorname{det} \mathrm{D} u d x=\frac{1}{|\mathrm{~B}(a, r)|} \int_{\mathrm{B}(a, r)} \operatorname{det} \mathrm{D} u .
$$

Coifman, Lions, Meyers and Semmes [CLMS89] showed that if $u \in \mathrm{~W}^{1, n}\left(\mathbb{R}^{n} ; \mathbb{R}^{n}\right)$ then $\operatorname{det} \mathrm{D} u$ lies in the Hardy space $\mathscr{H}^{1}\left(\mathbb{R}^{n}\right)$. It would be interesting to know if the same conclusion holds when $u \in \mathrm{~A}_{n-1, n /(n-1)}$.

While we have emphasized motivations from nonlinear elasticity, it should be noted that the study of properties of $\mathrm{W}^{1, p}$ maps arises in many other contexts and in particular in the analytic approach to quasiconformal mappings. Of the vast literature, we only mention the survey article by Bojarski and Iwaniec [BI83] and the books by Reshetnyak [Re85] and Rickman [Ri93], where further references can be found.

The remainder of the paper is organised as follows. Section 2 summarizes the notation (which follows [Sv88]) and gives some auxiliary results. Section 3, which is the core of the paper, contains the proofs of Theorems A and B. In section 4 these results are applied to nonlinear elasticity. Focusing on the physically relevant case $n=3$, we show, in particular, that for a stored energy density of the form (1.1), minimizers
exist if $p \geqq 2, q \geqq \frac{3}{2}$. This improves results of Ball and Murat [BM84], Zhang [Zh90] and [Mu90 b] which all require $q \geqq \frac{p}{p-1}$. Finally in section 5 we deduce the degree formula (1.2) from Theorem A. This allows one to generalize Šverák's results to the case $q \geqq \frac{n}{n-1}$ and we state some of these explicity.

## 2. PRELIMINARIES

Except for Lemma 2.3 and Propositions 2.4 and 2.5 , this section is essentially identical to section 2 of [Sv88] although we do not make use of differential forms. We include it here to keep the present exposition self-contained.

We begin by recalling some facts from multilinear algebra ( $c f$. Federer [Fe69], Chapter 1 or Flanders [F163]). We denote by . the scalar product of vectors in $\mathbb{R}^{n}$ and by $\Lambda$ their exterior product. For $n \geqq 2$ we identify the space $\Lambda_{n-1} \mathbb{R}^{n}$ of $(n-1)$ vectors with $\mathbb{R}^{n}$ by means of the map $*: \Lambda_{n-1} \mathbb{R}^{n} \rightarrow \mathbb{R}^{n}$.

The map

$$
\left(\xi_{1}, \ldots, \xi_{n-1}\right) \mapsto \xi_{1} \Lambda \ldots \Lambda \xi_{n-1}
$$

is characterized by the following conditions:
(i) It is multilinear and alternating.
(ii) If $e_{1}, \ldots, e_{n}$ is the canonical basis of $\mathbb{R}^{n}$, then

$$
*\left(e_{1} \Lambda \ldots \Lambda \hat{e}_{i} \Lambda \ldots \Lambda e_{n}\right)=(-1)^{n-i} e_{i}
$$

where, as usual, the symbol under ${ }^{\wedge}$ is to be obmitted.
If $\xi, \eta \in \mathbb{R}^{3}$ then $\xi \Lambda \eta$ is the usual vector product.
For a linear map $F: \mathbb{R}^{n} \rightarrow \mathbb{R}^{n}$, the map $\Lambda_{n-1} F$ is defined by

$$
\left(\Lambda_{n-1} \mathrm{~F}\right)\left(\xi_{1} \Lambda \ldots \Lambda \xi_{n-1}\right)=\mathrm{F} \xi_{1} \Lambda \ldots \Lambda \mathrm{~F} \xi_{n-1}
$$

and its norm is given by

$$
\begin{array}{r}
\left|\Lambda_{n-1} \mathrm{~F}\right|=\sup \left\{\left|\Lambda_{n-1} \mathrm{~F}\left(\xi_{1} \Lambda \ldots \Lambda \xi_{n-1}\right)\right|: \xi_{i} \in \mathbb{R}^{n}\right. \\
\left.\quad \text { and }\left|\xi_{1} \Lambda \ldots \Lambda \xi_{n-1}\right| \leqq 1\right\} .
\end{array}
$$

If A is the matrix of F with respect to the canonical basis, given by $\mathrm{F} e_{i}=a_{i}^{j} e_{j}$ (we recall that the summation convention is in force), then the matrix B of $\Lambda_{n-1} \mathrm{~F}$ is the cofactor matrix of A ,

$$
\begin{equation*}
\mathrm{B}=(\operatorname{cof} \mathrm{A})=(\operatorname{adj} \mathrm{A})^{\mathrm{T}}=\mathrm{A}^{-\mathrm{T}} \operatorname{det} \mathrm{~A} . \tag{2.1}
\end{equation*}
$$

The norm of a matrix A will be identified with that of the linear map that the matrix represents in the canonical basis. Hence for $F$ and $A$ as above, one has

$$
\left|\Lambda_{n-1} \mathrm{~F}\right|=|\operatorname{Cof} \mathrm{A}|=|\operatorname{adj} \mathrm{A}|
$$

If V is an $(n-1)$ dimensional subspace and $\mathrm{F}: \mathrm{V} \rightarrow \mathbb{R}^{n}$ is a linear map then $\Lambda_{n-1} \mathrm{~F}: \Lambda_{n-1} \mathrm{~V} \rightarrow \mathbb{R}^{n}$ is defined by

$$
\left(\Lambda_{n-1} F\right)\left(\xi_{1} \Lambda \ldots \Lambda \xi_{n-1}\right)=F \xi_{1} \Lambda \ldots \Lambda F \xi_{n-1}
$$

and its norm is now given by

$$
\begin{align*}
& \left|\Lambda_{n-1} \mathrm{~F}\right|=\sup \left\{\left|\Lambda_{n-1} \mathrm{~F}\left(\xi_{1} \Lambda \ldots \Lambda \xi_{n-1}\right)\right|: \xi_{i} \in \mathrm{~V},\right. \\
& \left.\quad \text { and }\left|\xi_{1} \Lambda \ldots \Lambda \xi_{n-1}\right| \leqq 1\right\} . \tag{2.2}
\end{align*}
$$

Let $v$ be a unit vector normal to $V$. Then the one dimensional space $\Lambda_{n-1} \mathrm{~V}$ may be identified with $\{\lambda v: \lambda \in \mathbb{R}\}$. Let $\tilde{\mathrm{F}}: \mathbb{R}^{n} \rightarrow \mathrm{R}^{n}$ be a linear extension of F . If A is the matrix of $\widetilde{\mathrm{F}}$ with respect to the canonical basis and if $v=v^{j} e_{j}$, one has

$$
\begin{align*}
& \left(\Lambda_{n-1} \mathrm{~F}\right) v=(\operatorname{adj} \mathrm{A})_{i}^{i} v^{j} e_{i},  \tag{2.3}\\
& \left|\Lambda_{n-1} \mathrm{~F}\right|=\left|\left(\Lambda_{n-1} \mathrm{~F}\right) v\right| . \tag{2.4}
\end{align*}
$$

In the following, $\Omega$ will always denote a nonempty, bounded, open subset of $\mathbb{R}^{n}, n \geqq 2$. By $\mathrm{L}^{p}(\Omega)$ and $\mathrm{W}^{1, p}(\Omega)$, we denote the spaces of $p$ summable and Sobolev functions, respectively. A function is in $L_{\text {ioc }}^{p}(\Omega)$ if $f \in \mathrm{~L}^{p}\left(\Omega^{\prime}\right)$ for all open sets $\Omega^{\prime}$ compactly contained in $\Omega$. A vector-or matrix - valued function is in $\mathrm{L}^{p}$ (resp. $\mathrm{W}^{1, p}$ ) if all its components are; we use the notation $\mathrm{L}^{p}\left(\Omega ; \mathbb{R}^{n}\right)$ etc. By $\mathrm{C}^{r}(\Omega)$ we denote the space of $r$ times continuously differentiable functions; and $\mathscr{D}(\Omega)=\mathrm{C}_{0}^{\infty}(\Omega)$ is the space of smooth functions with compact support. Its dual $\mathscr{D}^{\prime}(\Omega)$ is the space of distributions.

Weak convergence is indicated by the half-narrow - , weak-* convergence by $\stackrel{*}{\sim}$. By 。 we denote composition of functions, by $*$ the convolution.

We let

$$
\begin{gathered}
\mathrm{B}(a, r)=\left\{x \in \mathbb{R}^{n}:|x-a|<r\right\}, \\
\mathrm{S}(a, r)=\left\{x \in \mathbb{R}^{n}:|x-a|=r\right\}, \quad \mathrm{B}=\mathrm{B}(0,1) .
\end{gathered}
$$

For $a \in \Omega$, we let $r_{a}=\operatorname{dist}\left(a, \mathbb{R}^{n} \backslash \Omega\right)$. The $n$-dimensional Lebesgue measure is denoted by $\mathrm{L}^{n}, k$-dimensional Hausdorff measure by $\mathrm{H}^{k}$.

We will occasionally consider Sobolev spaces of functions defined on $\partial \Omega$. We say that $\Omega$ has Lipschitz boundary (see [Ne67], p. 14) if there exist numbers $\alpha>0, \beta>0$ and coordinate systems

$$
\left(y_{r}^{1}, \ldots, y_{r}^{n}\right)=\left(y_{r}^{\prime}, y_{r}^{n}\right), \quad r=1, \ldots, \mathbf{M}
$$

as well as Lipschitz continuous functions

$$
a_{r}: \bar{\Delta}_{r}=\left\{\left|y_{r}^{i}\right| \leqq \alpha ; i=1, \ldots, n-1\right\} \rightarrow \mathbb{R}
$$

such that each point $x \in \partial \Omega$ can be represented in at least one coordinate system in the form $x=\left(y_{r}^{\prime}, a\left(y_{r}^{\prime}\right)\right)$. Moreover, one requires that the points $\left(y_{r}^{\prime}, y_{r}^{n}\right)$ with $\left|y_{r}^{\prime}\right| \in \Delta_{r}$ lie in $\Omega$ if $a\left(y_{r}^{\prime}\right)<y_{r}^{\prime}<a\left(y_{r}^{\prime}\right)+\beta$ and that they lie outside $\bar{\Omega}$ if $a\left(y_{r}^{\prime}\right)-\beta<y_{r}^{n}<a\left(y_{r}^{\prime}\right)$. Morrey ([Mo66], Definition 3.4.1) called such sets strongly Lipschitz.

A function $u: \partial \Omega \rightarrow \mathbb{R}$ is in $\mathrm{W}^{1, p}(\partial \Omega)\left[\right.$ resp. $\left.\mathrm{L}^{q}(\partial \Omega)\right]$ if all the functions $u_{r}\left(y_{r}^{\prime}\right):=u\left(\left(y_{r}^{\prime}, a_{r}\left(y_{r}\right)\right)\right.$ (with $y_{r}$ and $a_{r}$ as above) are in $\mathrm{W}^{1, p}\left(\Delta_{r}\right)$ [resp. $\left.\mathrm{L}^{q}\left(\Delta_{r}\right)\right]$. We say that $u \in \mathrm{~A}_{p, q}(\partial \mathrm{Q})$ if

$$
\begin{equation*}
u \in \mathrm{~W}^{1, p}\left(\partial \Omega ; \mathbb{R}^{n}\right) \quad \text { and } \quad\left|\Lambda_{n-1} \mathrm{D} u\right| \in \mathrm{L}^{q}(\partial \Omega) \tag{2.5}
\end{equation*}
$$

We will use the fact that $\mathrm{W}^{1, p}$ functions have $\mathrm{W}^{1, p}$ traces on a.e. sphere. More precisely we let $\rho \in \mathrm{C}_{0}^{\infty}(\mathrm{B}), \rho \geqq 0, \int_{\mathrm{B}} \rho=1, \rho_{\varepsilon}(x)=\varepsilon^{-n} \rho\left(\frac{x}{\varepsilon}\right)$ and we have

Proposition 2.1. - Let $p \geqq 1, u \in \mathbf{W}^{1, p}(\Omega), a \in \Omega, r_{a}=\operatorname{dist}(a, \partial \Omega)$. Then there exists an $\mathrm{L}^{1}$ null set $\mathrm{N}_{a}$ such that for all $r \in\left(0, r_{a}\right) \backslash \mathrm{N}_{a}$

$$
\left.\rho_{\varepsilon} * u \rightarrow u\right|_{\mathrm{S}(a, r)} \quad \text { in } \mathrm{W}^{1, p}(\mathrm{~S}(a, r))
$$

Moreover if $u \in \mathrm{~A}_{p, q}(\Omega)$ with $p \geqq 1, q \geqq 1$, then $u \in \mathrm{~A}_{p, q}(\mathrm{~S}(a, r))$ for $\mathrm{L}^{1}$ a.e. $r \in\left(0, r_{a}\right)$.

Remark. - Here $\left.u\right|_{\mathrm{s}(a, r)}$ is understood in the sense of trace (see e.g. [Ne67], Chapters 2.4 and 2.5).

Proof. - To prove the first assertion, consider polar co-ordinates in $\mathrm{B}\left(a, r_{a}-\frac{1}{k}\right) \backslash \mathbf{B}\left(a, \frac{1}{k}\right)$ and use Fubini's theorem to find $\mathrm{L}^{1}$ null sets $\mathrm{N}_{a}^{k}$ such that the conclusion holds for $r \in\left(\frac{1}{k}, r_{a}-\frac{1}{k}\right) \backslash \mathrm{N}_{a}^{k}$. Then let $\mathrm{N}_{a}=\bigcup_{k=1} \mathrm{~N}_{a}^{k}$. The proof of the second assertion is similar (see also Morrey [Mo66], Chapter 3.1 or Nečas [Ne67], Theorem 2.2.2).

We briefly recall some facts about the Brouwer degree (see e.g. Schwartz [Sc69] for more details). Let $\Omega \subset \mathbb{R}^{n}$ be bounded, open and let $u: \bar{\Omega} \rightarrow \mathbb{R}^{n}$ be a $\mathrm{C}^{\infty}$ map. If $y_{0} \in \mathrm{R}^{n} \backslash u(\partial \Omega)$ is such that $\operatorname{det} \mathrm{D} u(x) \neq 0$ for all $x \in u^{-1}\left(y_{0}\right)$, one defines

$$
\operatorname{deg}\left(u, \Omega, y_{0}\right)=\sum_{x \in u^{-1}(y)} \operatorname{sgn} \operatorname{det} \mathrm{D} u(x) .
$$

If $f$ is a $\mathrm{C}^{\infty}$ function supported in the connected component of $\mathrm{R}^{n} \backslash u(\partial \Omega)$ which contains $y_{0}$, one can show that

$$
\begin{equation*}
\int_{\Omega}(f \circ u) \operatorname{det} \mathrm{D} u d x=\operatorname{deg}\left(u, \Omega, y_{0}\right) \int_{\mathbb{R}^{n}} f d y . \tag{2.6}
\end{equation*}
$$

Using this formula and approximating by $\mathrm{C}^{\infty}$ functions, one can define $\operatorname{deg}(u, \Omega, y)$ for any continuous function $u: \Omega \rightarrow \mathbb{R}^{n}$ and any $y \in \mathbb{R}^{n} \backslash u(\partial \Omega)$. Moreover the degree only depends on $\left.u\right|_{\partial \Omega}$.

Indeed if $\Omega$ has Lipschitz boundary and if $u \in \mathrm{C}^{\infty}\left(\Omega ; \mathrm{R}^{n}\right)$, then the degree can be expressed as a boundary integral as follows. First recall the identity (see [Mo66], Lemma 4.4.6)

$$
\frac{\partial}{\partial x^{j}}(\operatorname{adj} \mathrm{D} u)_{i}^{j}=0 \quad \text { for } \quad i=1, \ldots, n
$$

Let $f$ be as above and let $g: \mathbb{R}^{n} \rightarrow \mathbb{R}^{n}$ be $\mathrm{C}^{\infty}$ with $\operatorname{div} g=f$ then the above identity in connection with (1.3) implies that

$$
\frac{\partial}{\partial x^{j}}\left(\left(g^{i} \circ u\right)(\operatorname{adj} \mathrm{D} u)_{i}^{j}\right)=(f \circ u) \operatorname{det} \mathrm{D} u
$$

By the Gauss-Green formula (for Lipschitz sets) and (2.3)

$$
\begin{equation*}
\int_{\Omega}(f \circ u) \operatorname{det} \mathrm{D} u d x=\int_{\partial \Omega}(g \circ u) \cdot\left(\Lambda_{n-1} \mathrm{D} u\right) v d \mathrm{H}^{n-1} \tag{2.7}
\end{equation*}
$$

and by (2.6)

$$
\begin{equation*}
\operatorname{deg}\left(u, \partial \Omega, y_{0}\right) \int_{\mathbb{R}^{n}} f d y=\int_{\partial \Omega}\left(g^{\circ} u\right) \cdot\left(\Lambda_{n-1} \mathrm{D} u\right) \vee d \mathrm{H}^{n-1} \tag{2.8}
\end{equation*}
$$

Here $v$ denotes the outward normal of $\partial \Omega$ (which exists $\mathrm{H}^{n-1}$ a.e.) and $\mathrm{D} u$ is viewed as a map from the tangent space of $\partial \Omega$ to $\mathbb{R}^{n}$.

Lemma 2.2 ([Sv88], Lemma 1). - Assume that $\Omega$ has Lipschitz boundary and that $p \geqq n-1$. Then (2.8) holds for every

$$
u \in \mathbf{W}^{1, p}\left(\partial \Omega ; \mathbb{R}^{n}\right) \cap \mathbf{C}^{0}\left(\partial \Omega ; \mathbb{R}^{n}\right)
$$

Proof. - It suffices to show that there exists a sequence $\tilde{u}_{k} \in \mathrm{C}^{\infty}\left(\bar{\Omega} ; \mathbb{R}^{n}\right)$ with $\left.\tilde{u}_{k}\right|_{\partial \Omega} \rightarrow u$ uniformly and in $\mathrm{W}^{1, p}(\partial \Omega)$. This is clear if $\Omega$ has smooth boundary and well-known to experts if $\Omega$ has Lipschitz boundary. We include the details for the convenience of the reader.

By a partition of unity (see e.g. [Ne67], p. 27) and a change of coordinates we may assume that there is a Lipschitz function $a$ and constants $\alpha, \beta>0$ such that

$$
\begin{gathered}
\operatorname{supp} u \subset \partial \Omega \cap \mathrm{U}, \\
\Omega \cap \mathrm{U}=\left\{\left(x^{\prime}, x_{n}\right): a\left(x^{\prime}\right)<x_{n}<a\left(x^{\prime}\right)+\beta, x^{\prime} \in \Delta\right\}, \\
\\
\partial \Omega \cap \mathrm{U}=\left\{\left(x^{\prime}, a\left(x^{\prime}\right)\right): x^{\prime} \in \Delta\right\}
\end{gathered}
$$

where

$$
\Delta=(-\alpha, \alpha)^{n-1}, \quad \mathrm{U}=\left\{\left(x^{\prime}, x_{n}\right): x^{\prime} \in \Delta, a\left(x^{\prime}\right)-\beta<x_{n}<a\left(x^{\prime}\right)+\beta\right\}
$$

We may assume $a(0)=0$ and, by possibly decreasing $\alpha,|a| \leqq \beta / 4$. Let

$$
v\left(x^{\prime}\right)=u\left(x^{\prime}, a\left(x^{\prime}\right)\right)
$$

By the definition of $\mathrm{W}^{1, p}(\partial \Omega), v \in \mathrm{~W}^{1, p}(\Delta)$. Moreover $\operatorname{supp} v \subset \Delta$ and $v \in \mathrm{C}^{0}(\Delta)$. Hence there exist $v_{k} \in \mathrm{C}_{0}^{\infty}(\Delta)$ which converge to $v$ in $\mathrm{W}^{1, p}$ and uniformly. Let $\eta \in C_{0}^{\infty}(-\beta / 2, \beta / 2)$ with $\eta \equiv 1$ on $[-\beta / 4, \beta / 4]$ and let $\tilde{u}_{k}(x)=\eta\left(x_{n}\right) v_{k}\left(x^{\prime}\right)$.

Clearly $\tilde{u}_{k} \in \mathrm{C}_{0}^{\infty}\left(\mathbb{R}^{n}\right)$ and $u_{k}\left(x^{\prime}, a\left(x^{\prime}\right)\right)=v_{k}\left(x^{\prime}\right)$. Hence

$$
\left.\left.\tilde{u}_{k}\right|_{\partial \Omega} \rightarrow u\right|_{\partial \Omega} \quad \text { in } \mathrm{W}^{1, p}(\partial \Omega) \cap \mathrm{C}^{0}(\partial \Omega),
$$

by the definition of convergence in $\mathrm{W}^{1, p}(\partial \Omega)$ (see [Ne67], p. 94). The proof is finished.

We need the following criterion for weak compactness in $L^{1}$.
Lemma 2.3 ([MS47], [Me66]). - Let $\mathrm{E} \subset \mathbb{R}^{n}$ be measurable with finite measure and let $f^{(v)}$ be a sequence in $\mathrm{L}^{1}(\mathrm{E})$. Then $f^{(v)}$ is relatively weakly sequentially compact in $\mathrm{L}^{1}(\mathrm{E})$ if and only if there exists a function $\gamma: \mathbb{R}_{0}^{+} \rightarrow \mathbb{R}_{0}^{+}$with $\lim _{t \rightarrow \infty} \gamma(t) / t=\infty$ such that

$$
\sup _{v} \int_{E} \gamma\left(\left|f^{(v)}\right|\right) d x<\infty .
$$

Moreover $\gamma$ may be chosen as an increasing function. An immediate consequence of the lemma is

Proposition 2.4. - If $g^{(v)} \rightharpoonup g$ in $\mathrm{L}^{1}(\mathrm{E})$ and $\left|f^{(v)}\right| \leqq \mathrm{C}\left|g^{(v)}\right|$ then $f^{(v)}$ is weakly compact in $\mathrm{L}^{1}(\mathrm{E})$.

We will use the following version of the chain rule. The result and its proof are well-known to experts. We include the result for the convenience of the reader.

Proposition 2.5. - Let $\Omega^{\prime}, \Omega \subset \mathbb{R}^{n}$ be open, let $\varphi: \bar{\Omega}^{\prime} \rightarrow \bar{\Omega}$ be a biLipschitz homeomorphism. If $u \in \mathrm{~W}^{1, p}(\Omega)$ then $u^{\circ} \varphi \in \mathbf{W}^{1, p}\left(\Omega^{\prime}\right)$ and the distributional derivatives satisfy

$$
\begin{equation*}
\mathrm{D}\left(u^{\circ} \varphi\right)=(\mathrm{D} u)^{\circ} \varphi \mathrm{D} \varphi . \tag{2.9}
\end{equation*}
$$

Warning. - The chain rule is meaningless if one has no control on $\varphi^{-1}$. Consider the following example (pointed out to us by F . Murat).

Let $\varphi: \mathbb{R}^{2} \rightarrow \mathbb{R}^{2}, \varphi(x, y)=(x, x), u: \mathbb{R}^{2} \rightarrow \mathbb{R}, u(x, y)=|x-y|^{-\alpha}$. One has $u \in \mathrm{~W}^{1, p}\left(\mathbb{R}^{2}\right)$ if $p<\frac{2}{1+\alpha}$ but $u^{\circ} \varphi \equiv+\infty$. If $u(x, y)=|x-y|$, then $u^{\circ} \varphi \equiv 0$ but (2.9) does not make sense as $\mathrm{D} u$ is nowhere defined on $\varphi\left(\mathbb{R}^{2}\right)$.

Proof. - See Morrey [Mo66], Theorem 3.1.7. Use e.g. the area formula to pass to the limit in his equation (3.1.6).

## 3. THE DIVERGENCE IDENTITIES

In this section we prove the divergence identities as well as the higher integrability of the Jacobian (Theorems A and B of the Introduction) and deduce an "isoperimetric" inequality (Lemma 3.4). We recall the notation

$$
r_{a}=\operatorname{dist}(a, \partial \Omega)
$$

The main tool is
Lemma 3.1. - Let $p>n-1, u \in \mathbf{W}^{1, p}\left(\Omega ; \mathbb{R}^{n}\right), a \in \Omega$. Then there exists an $\mathrm{L}^{1}$ null set $\mathrm{N}_{a}$ such that for all $r \in\left(0, r_{a}\right) \backslash \mathrm{N}_{a}$ and for all $g \in \mathrm{C}^{1}\left(\mathbb{R}^{n} ; \mathbb{R}^{n}\right)$ with $|\mathrm{Dg}| \leqq \mathrm{C}$ one has

$$
\begin{align*}
& \left|\int_{\mathrm{S}(a, t)}(g \circ u) \cdot\left(\Lambda_{n-1} \mathrm{D} u\right) \vee d \mathrm{H}^{n-1}\right| \\
& \leqq \mathrm{C}(n)\|\operatorname{div} g\|_{\infty}\left\{\int_{\mathrm{S}(a, r)}\left|\Lambda_{n-1} \mathrm{D} u\right| d \mathrm{H}^{n-1}\right\}^{n / n-1} \tag{3.1}
\end{align*}
$$

The same estimate holds for $p=n-1$, provided that $g$ is also bounded.
Remarks. - 1. At $x \in \mathbf{S}(a, r), \mathrm{D} u(x)$ is interpreted as a map from the tangent space $\mathrm{T}_{x} \mathrm{~S}$ to $\mathbb{R}^{n}$; see (2.2) for the definition of $\Lambda_{n-1} \mathrm{D} u$ and recall from (2.3), (2.4) that for smooth $u$, one has

$$
\left(\Lambda_{n-1} \mathrm{D} u\right) v=(\operatorname{adj} \mathrm{D} u)_{i}^{j} v_{j} e_{i} \quad \text { and } \quad\left|\Lambda_{n-1} \mathrm{D} u\right|=\left|\left(\Lambda_{n-1} \mathrm{D} u\right) v\right|
$$

2. If $p=n-1$ and if $g$ is not bounded, the estimate still holds if the integral on the left hand side is replaced by the dual pairing between $w^{1, n^{-1}}\left(\partial \Omega ; \mathbb{R}^{n}\right)$ and its dual (see the remarks after the proof for the details). If, in addition, $\left|\Lambda_{n-1} \mathrm{D} u\right| \in \mathrm{L}^{s}(\mathrm{~S}(a, r))$ for some $s>1$, then $(g \circ u)\left(\Lambda_{n-1} \mathrm{D} u\right) v \in \mathrm{~L}^{1}(\mathrm{~S}(a, r))$ and (3.1) holds in the form stated; see the discussion after the proof of the lemma.

Proof. - First assume that $u \in \mathrm{C}^{\infty}\left(\overline{\mathrm{B}(a, r)} ; \mathbb{R}^{n}\right)$. By (2.7),

$$
\begin{equation*}
\int_{\mathrm{S}(a, r)}(g \circ u) \cdot\left(\Lambda_{n-1} \mathrm{D} u\right) \vee d \mathrm{H}_{n-1}=\int_{\mathrm{B}(a, r)}(\operatorname{div} g)^{\circ} u \operatorname{det} \mathrm{D} u d x \tag{3.2}
\end{equation*}
$$

and by the change of variables formula (see e.g. [Sv88])

$$
\begin{equation*}
\int_{\mathrm{B}(a, r)}(\operatorname{div} g)^{\circ} u \operatorname{det} \mathrm{D} u d x=\int_{\mathbb{R}^{n}}(\operatorname{div} g)(y) \operatorname{deg}(u, \mathrm{~B}(a, r), y) d y . \tag{3.3}
\end{equation*}
$$

Now (see [Mu90 b], equations (3.1) to (3.4)) using the fact that the degree is an integer as well as the Sobolev embedding theorem for BV functions
and taking into account the first remark above, one finds

$$
\begin{align*}
& \int_{\mathbb{R}^{n}}|\operatorname{deg}(u, \mathrm{~B}(a, r), y)| d y \\
& \leqq \int_{\mathbb{R}^{n}} \mid\left.\operatorname{deg}(u, \mathrm{~B}(a, r), y)\right|^{n /(n-1)} d y \\
& \leqq \mathrm{C}(n)\left\{\int_{\mathrm{S}(a, r)}\left|\Lambda_{n-1} \mathrm{D} u\right| d \mathrm{H}_{n-1}\right\}^{n /(n-1)} \tag{3.4}
\end{align*}
$$

Combining (3.2) to (3.4), the lemma follows for $u \in C^{\infty}\left(\Omega ; \mathbb{R}^{n}\right)$ (with $\mathrm{N}_{a}=\varnothing$ ).

Now let $u \in W^{1, p}\left(\Omega ; \mathbb{R}^{n}\right), \mathrm{R}<r_{a}$. By virtue of Proposition 2.1, there exists an $\mathrm{L}^{1}$ null set N and a sequence $u^{(k)} \in \mathrm{C}^{\infty}\left(\mathrm{B}(a, \mathrm{R}) ; \mathbb{R}^{n}\right)$ such that for $r \in(0, \mathrm{R}) \backslash \mathrm{N}$, one has

$$
u^{(k)} \rightarrow u \quad \text { in } \mathrm{W}^{1, p}\left(\mathrm{~S}(a, r) ; \mathbb{R}^{n}\right)
$$

It follows from (2.2) that

$$
\left(\Lambda_{n-1} \mathrm{D} u^{(k)}\right) v \rightarrow\left(\Lambda_{n-1} \mathrm{D} u\right) v \quad \text { in } \mathrm{L}^{p /(n-1)}\left(\mathrm{S}(a, r) ; \mathbb{R}^{n}\right)
$$

In view of (2.4), one easily passes to the limit on the right hand side of (3.1). If $p>n-1$, by the Sobolev embedding theorem, $u^{(k)} \rightarrow u$ in $\mathrm{L}^{\infty}\left(\mathrm{S}(a, r) ; \mathbb{R}^{n}\right)$ which allows one to pass to the limit on the left hand side of (3.1). Similarly if $g$ is bounded, one has (for a subsequence) $g \circ u^{(k)} \rightarrow g \circ u \mathrm{H}^{n-1}$ a.e. and $\left|g \circ u^{(k)}\right| \leqq \mathrm{C}_{1}$ so that one may pass to the limit using Egoroff's theorem and the equi-integrability of $\mathrm{L}^{1}$ functions.

Further remarks on $p=n-1$. - If $g$ is unbounded then in general one does not have $(g \circ u) .\left(\Lambda_{n-1} \mathrm{D} u\right) v \in \mathrm{~L}^{1}(\mathrm{~S}(a, r))$ so that the integral on the left hand side of (3.1) does not make sense. It can, however, be reinterpreted as a duality pairing by viewing $\left(\Lambda_{n-1} \mathrm{D} u\right) v$ as a distribution. We only sketch the idea. Let $\Omega=\mathrm{B}(a, r)$ and consider the functional

$$
\mathrm{J}_{u}(\varphi):=\int_{\Omega}(\operatorname{adj} \mathrm{D} u)_{i}^{j} \frac{\partial}{\partial x^{j}} \varphi^{i} d x
$$

Using the fact that $\frac{\partial}{\partial x^{j}}(\operatorname{adj} \mathrm{D} u)_{i}^{j}=0$ in $\mathscr{D}^{\prime}(\Omega)$ [which follows from (1.6) by approximation], one shows that $J_{u}(\varphi)$ only depends on the trace $\left.\varphi\right|_{\partial \Omega}$. Recall that there is a bounded extension operator

$$
\mathrm{E}: \mathrm{W}^{1, n-1}(\partial \Omega) \rightarrow \mathrm{W}^{1, n}(\Omega)
$$

Indeed it suffices to apply the Sobolev embedding theorem

$$
\mathrm{W}^{1, n-1}(\partial \Omega) \rightarrow \mathrm{W}^{1-1 / n, n}(\partial \Omega)
$$

(use the fact that the $\mathbf{W}^{s, p}$ norm is defined via local charts, [Ne67], p. 94 and [Ad75], Theorem 7.5.8 (ii)) and then the inverse trace theorem (see [Ne67], Theorem 2.5.7).

Using E one sees that $\mathrm{J}_{u} \in\left(\mathbf{W}^{1, n^{-1}}\left(\partial \Omega ; \mathbb{R}^{n}\right)\right)^{\prime}$. Moreover for smooth $u$, one easily verifies that $\mathrm{J}_{u}=\left(\Lambda_{n-1} \mathrm{D} u\right) v$. Using the density of smooth functions and the above extension operator, one deduces that $u \rightarrow \mathrm{~J}_{u}$ is a continuous operator from $\mathrm{W}^{1, n-1}(\partial \Omega ; \mathbb{R})$ to its dual.

Thus with $\boldsymbol{u}^{(k)}$ as in the proof of the lemma, one has

$$
\left(\Lambda_{n-1} \mathrm{D} u^{(k)}\right) v \rightarrow\left(\Lambda_{n-1} \mathrm{D} u\right) v \quad \text { in }\left(\mathrm{W}^{1, n-1}\left(\partial \Omega ; \mathbb{R}^{n}\right)\right)^{\prime}
$$

while by the chain rule for Sobolev functions (see [GT83], Lemma 7.5)

$$
g^{\circ} u^{(k)} \rightarrow g^{\circ} u \quad \text { in } W^{1, n-1}\left(\partial \Omega ; \mathbb{R}^{n}\right)
$$

Hence (3.1) holds if the integral on the left is replaced by the duality pairing $\left\langle g^{\circ} u,\left(\Lambda_{n-1} \mathrm{D} u\right) v\right\rangle$. Finally if $\left(\Lambda_{n-1} \mathrm{D} u\right) v \in \mathrm{~L}^{s}(\partial \Omega)$ for some $s>1$, one has $(g \circ u) .\left(\Lambda_{n-1} \mathrm{D} u\right) v \in \mathrm{~L}^{1}(\partial \Omega)$ and the duality pairing can be expressed as integral. Indeed if suffices to approximate $\left(\Lambda_{n-1} \mathrm{D} u\right) v$ in $L^{s} \cap\left(\mathbf{W}^{1, n-1}\right)^{\prime}$ by smooth functions and to observe that by the Sobolev embedding theorem $g^{\circ} u \in \mathrm{~L}^{q}\left(\partial \Omega ; \mathbb{R}^{n}\right)$ for all $q<\infty$.

The main result of this section is
Theorem 3.2 (divergence identities). - Let $p \geqq n-1, q \geqq \frac{n}{n-1}$, $u \in \mathrm{~A}_{p, q}(\Omega), g \in \mathrm{C}^{\mathbf{1}}\left(\mathbb{R}^{n} ; \mathbb{R}^{n}\right)$ with $|\mathrm{D} g| \leqq \mathrm{C}$. Consider the distribution

$$
\begin{equation*}
h:=\frac{\partial}{\partial x^{j}}\left\{\left(g^{i \circ} u\right)(\operatorname{adj} \mathrm{D} u)_{i}^{j}\right\} . \tag{3.5}
\end{equation*}
$$

Then $h \in \mathrm{~L}_{\mathrm{loc}}^{1}(\Omega)$ and $h=(\operatorname{div} g)^{\circ} u \operatorname{det} \mathrm{D} u$ a.e.
Remarks. - 1. For $q \geqq \frac{p}{p-1}$, the result is well-known (see [Sv88]); it suffices to approximate $u$ by smooth functions and (adj $\mathrm{D} u)_{i}^{j}$ by divergence free vector fields.
2. Note that in view of the inequality (1.4) a posteriori, one has $f \in \mathrm{~L}^{s}(\Omega), s=\frac{q(n-1)}{n}$.
3. The result is very close to being optimal. The standard counter example is obtained by letting $\Omega$ be the unit ball in $\mathbb{R}^{n}, u(x)=\frac{x}{|x|}$, $g(y)=\frac{1}{n} y$. Then $u \in \mathrm{~W}^{1, p}(\Omega), \forall p<n, \operatorname{det} \mathrm{D} u=0$. a.e. but $f=|\Omega| \delta_{0}$.
4. The improvement from $q \geqq \frac{p}{p-1}$ to $q \geqq \frac{n}{n-1}$ uses the special structure of $\operatorname{adj} \mathrm{D} u$, not just the fact that $\frac{\partial}{\partial x^{j}}(\operatorname{adj} \mathrm{D} u)_{i}^{j}=0$. Indeed for every $p \in[n-1, n)$ there exist $v \in \mathbf{W}^{1, p}(\Omega)$ and $\sigma \in \mathrm{L}^{q}\left(\mathbb{R}^{n}, \mathbb{R}^{n}\right)$, for all $q<\frac{p}{p-1}$, with $\operatorname{div} \sigma=0$ in $\mathscr{D}^{\prime}$ such that $\nabla v . \sigma=0$ a.e. while $\operatorname{div} v \sigma \neq 0$ in $\mathscr{D}^{\prime}$ (see [Mu91 b], Corollary 6.2).

Proof. - Note that $g{ }^{\circ} u \in \mathrm{~W}^{1, p}\left(\Omega ; \mathbb{R}^{n}\right)$ and that

$$
\frac{1}{p}+\frac{1}{q} \leqq \frac{1}{n-1}+\frac{n-1}{n}<1+\frac{1}{n} .
$$

Hence by the Sobolev embedding theorem $\left(g^{i} \circ u\right)(\operatorname{adj} \mathrm{D} u)_{i}^{j} \in \mathrm{~L}_{\mathrm{loc}}^{1}(\Omega)$ and $h$ is well-defined as a distribution. Moreover by [Mu90a], it suffices to show that $h \in \mathrm{~L}_{\mathrm{loc}}^{1}(\Omega)$.

To this end, consider a radial mollifier

$$
\rho(x)=\psi(|x|), \quad \rho \in \mathrm{C}_{0}^{\infty}(\mathrm{B}(0,1)), \quad \int_{\mathbb{R}^{n}} \rho d x=1
$$

Let $\rho_{\varepsilon}(x)=\varepsilon^{-n} \rho\left(\frac{x}{\varepsilon}\right)$, fix $\Omega^{\prime} \subset \subset \Omega$. We will show that $h \in \mathrm{~L}^{1}\left(\Omega^{\prime}\right)$. The distribution $\rho_{\varepsilon} * h$ is defined by

$$
\left\langle\rho_{\varepsilon} * h, \psi\right\rangle=\left\langle h, \rho_{\varepsilon} * \psi\right\rangle .
$$

For sufficiently small $\varepsilon$, one has $\rho_{\varepsilon} * h \in \mathscr{D}^{\prime}\left(\Omega^{\prime}\right)$. In fact $\rho_{\varepsilon} * h \in \mathrm{C}^{\infty}\left(\bar{\Omega}^{\prime}\right)$. Moreover $\rho_{\varepsilon} * h \rightharpoonup h$ in $\mathscr{D}^{\prime}\left(\Omega^{\prime}\right)$. It thus sufficies to show that the convergence occurs weakly in $\mathrm{L}^{1}\left(\Omega^{\prime}\right)$. Let $\varepsilon<\frac{1}{2} \operatorname{dist}\left(\Omega^{\prime}, \partial \Omega\right)$, and $a \in \Omega^{\prime}$. Then

$$
\begin{aligned}
&\left(\rho_{\varepsilon} * h\right)(a)=- \int_{\mathbb{R}^{n}}\left(g^{i} \circ u\right)(x)(\operatorname{adj} \mathrm{D} u)_{i}^{j}(x)\left(\frac{\partial}{\partial x^{j}} \rho_{\varepsilon}\right)(x-a) d x \\
&=-\int_{\mathbb{R}^{n}}\left(g^{i} \circ u\right)(x)(\operatorname{adj} \mathrm{D} u)_{i}^{j}(x) \varepsilon^{-(n+1)} \psi^{\prime}\left(\frac{|x-a|}{\varepsilon}\right) \frac{x_{j}-a_{j}}{|x-a|} d x \\
&=-\varepsilon^{-(n+1)} \int_{0}^{\varepsilon}\left\{\int_{\mathrm{S}(a, r)}\left(g^{\circ} u\right) \cdot\left(\Lambda_{n-1} \mathrm{D} u\right) \vee d \mathrm{H}_{n-1}\right\} \psi^{\prime}\left(\frac{r}{\varepsilon}\right) d r .
\end{aligned}
$$

Thus by Lemma 3.1 and Hölder's inequality

$$
\begin{aligned}
&\left(\rho_{\varepsilon} * h\right)(a) \leqq \mathrm{C} \varepsilon^{-(n+1)} \int_{0}^{\varepsilon}\left\{\int_{\mathrm{S}(a, r)}\left|\Lambda_{n-1} \mathrm{D} u\right| d \mathrm{H}_{n-1}\right\}^{n /(n-1)} d r \\
& \leqq \mathrm{C} \varepsilon^{-(n+1)} \int_{0}^{\varepsilon}\left\{\int_{\mathrm{S}(a, r)}\left|\Lambda_{n-1} \mathrm{D} u\right|^{n /(n-1)} d \mathrm{H}_{n-1}\right\} r d r \\
& \leqq \mathrm{C} \varepsilon^{-n} \int_{\mathrm{B}(a, \varepsilon)}|\operatorname{adj} \mathrm{D} u|^{n /(n-1)} d x .
\end{aligned}
$$

Note that $\mathbf{B}(a, \varepsilon) \subset \Omega$ since $\varepsilon<\frac{1}{2} \operatorname{dist}\left(\Omega^{\prime}, \partial \Omega\right)$. Let $w=|\operatorname{adj} \mathbf{D} u|^{n /(n-1)}$; we may assume without loss of generality that

$$
\left.\rho\right|_{\mathbf{B}(0,1 / 2)} \geqq|\mathrm{B}(0,1)|^{-1}
$$

and deduce

$$
\left|\rho_{\varepsilon} * h\right| \leqq \mathrm{C}\left|\rho_{2 \varepsilon} * w\right| \text { in } \Omega^{\prime} .
$$

Choose $\varepsilon_{v} \rightarrow 0$. As $\rho_{2 \varepsilon_{v}} * w \rightarrow w$ in $\mathrm{L}^{1}\left(\Omega^{\prime}\right)$, Proposition 2.4 implies that $\rho_{\varepsilon_{v}} * h$ is weakly compact in $\mathrm{L}^{1}\left(\Omega^{\prime}\right)$ and hence $\rho_{\varepsilon_{v}} * h \rightharpoonup h$ in $\mathrm{L}^{1}\left(\Omega^{\prime}\right)$, since convergence in $\mathscr{D}^{\prime}(\Omega)$ is already known. In particular, $h \in \mathrm{~L}^{1}\left(\Omega^{\prime}\right)$ and the proof is finished.

In the critical case $q=\frac{n}{n-1}$ it follows from the inequality

$$
|\operatorname{det} \mathrm{F}| \leqq|\operatorname{adj} \mathrm{F}|^{n /(n-1)}
$$

that $\operatorname{det} \mathrm{D} u \in \mathrm{~L}^{1}(\Omega)$. From scaling arguments one would think that this is optimal. Under the assumption $\operatorname{det} \mathrm{D} u \geqq 0$, however, one has the following higher integrability result which generalises the results in [Mu89], [Mu90 b] (see also Iwaniec and Sbordone [IS91], Brezis, Fusco and Sbordone [BFS92], Greco and Iwaniec [GI92] and Iwaniec and Lutoborski [IL92])

Theorem 3.3. - Let $u \in \mathrm{~A}_{n-1, n /(n-1)}(\Omega)$ and assume that $\operatorname{det} \mathrm{D} u \geqq 0$ a.e., then $\operatorname{det} \mathrm{D} u \ln (2+\operatorname{det} \mathrm{D} u) \in \mathrm{L}_{\mathrm{loc}}^{1}(\Omega)$. More precisely, if $\mathrm{B}(a, 2 r) \subset \Omega$ then

$$
\int_{\mathbf{B}(a, r)} \operatorname{det} \mathrm{D} u \ln \left(2+\frac{\operatorname{det} \mathrm{D} u}{(\operatorname{det} \mathrm{D} u)_{\mathrm{B}}}\right) d x \leqq \mathrm{C} \int_{\mathbf{B}(a, 2 r)}|\operatorname{adj} \mathrm{D}|_{\mathbf{B}(a, 2 r)}^{n /(n-1)} d x,
$$

where

$$
(\operatorname{det} \mathrm{D} u)_{\mathrm{B}}=\int_{\mathrm{B}(a, r)} \operatorname{det} \mathrm{D} u d x=\frac{1}{|\mathrm{~B}(a, r)|} \int_{\mathrm{B}(a, r)} \operatorname{det} \mathrm{D} u .
$$

Coifman, Lions, Meyer and Semmes [CLMS89] showed that if $u \in \mathrm{~W}^{1, n}\left(\mathbb{R}^{n} ; \mathbb{R}^{n}\right)$ then $\operatorname{det} \mathrm{D} u$ lies in the Hardy space $\mathscr{H}^{1}\left(\mathbb{R}^{n}\right)$. Since a non negative $f$ is (locally) in $\mathscr{H}^{1}$ if and only if $f \log (2+f)$ is in $\mathrm{L}_{\text {loc }}^{1}$, it seems natural to ask whether $u \in \mathrm{~A}_{n-1, n /(n-1)}\left(\mathbb{R}^{n}\right)$ implies that $\operatorname{det} \mathrm{D} u \in \mathscr{H}^{1}\left(\mathbb{R}^{n}\right)$. We do not know whether this is true or not.

Proof. - The result follows from Theorem 6.2 in [Mu90b] since Theorem 3.2 above implies condition (6.1) of that paper. For the convenience of reader we sketch the proof. We recall that for a function $f \in \mathrm{~L}^{1}\left(\mathbb{R}^{n}\right)$ the maximal function $\mathrm{M} f$ is defined by

$$
\mathbf{M} f(x):=\sup _{\mathbf{R}>0} f_{\mathbf{B}(x . \mathbf{R})}|f| d y
$$

If $f$ is supported in $\mathbf{B}=\mathbf{B}(a, \mathbf{R})$ and $\mathbf{M} f$ is integrable over $\mathbf{B}(a, r)$, then by a result of E. Stein [St.69]

$$
\begin{equation*}
\int_{\mathrm{B}}|f| \log \left(2+\frac{|f|}{f_{\mathrm{B}}|f|}\right) d y \leqq \int_{\mathrm{B}} \mathbf{M} f d y \tag{3.6}
\end{equation*}
$$

Now consider a ball $\mathrm{B}=\mathrm{B}(a, \mathrm{R})$ such that $\mathrm{B}(a, 2 \mathrm{R}) \subset \Omega$ and let

$$
f=\chi_{\mathrm{B}(a, \mathrm{R})} \operatorname{det} \mathrm{D} u .
$$

We need to estimate $\mathrm{M} f$. Fix $x \in \mathrm{~B}(a, \mathrm{R})$, let $\rho<\mathrm{R} / 2$. By the isoperimetric inequality (see Lemma 3.4 below) and the positivity of $\operatorname{det} \mathrm{D} u$ we have for a.e. $r \in(\rho, 2 \rho)$
$\left\{\int_{\mathrm{B}(x, \rho)} \operatorname{det} \mathrm{D} u d y\right\}^{(n-1) / n} \leqq\left\{\int_{\mathrm{B}(x, r)} \operatorname{det} \mathrm{D} u d y\right\}^{(n-1) / n} \leqq \mathrm{C} \int_{\mathrm{S}(x, r)}|\operatorname{adj} \mathrm{D} u| d y$.
Integrate from $\rho$ to $2 \rho$ and divide by $\rho^{n-1}$ to get

$$
\left\{f_{\mathrm{B}(x, \rho)} \operatorname{det} \mathrm{D} u d y\right\} \leqq \mathrm{C}\left\{\mathrm{~J}_{\mathrm{B}(x, 2 \rho)}|\operatorname{adj} \mathrm{D} u| d y\right\}^{n /(n-1)}
$$

Let

$$
g=\chi_{\mathrm{B}(a, 2 \mathrm{R})}|\operatorname{adj} \mathrm{D} u| .
$$

It follows that

$$
\begin{aligned}
& \mathrm{M} f(x) \leqq \mathrm{C}[\mathrm{M} g(x)]^{n /(n-1)}+\sup _{\rho>\mathrm{R} / 2} \int_{\mathrm{B}(x, \rho)} f d y \\
& \leqq \mathrm{C}[\mathrm{M} g(x)]^{n /(n-1)}+\mathrm{CR}^{-n} \int_{\mathrm{B}(a, \mathrm{R})} \operatorname{det} \mathrm{D} u d y
\end{aligned}
$$

Now by assumption $g \in \mathrm{~L}^{n /(n-1)}\left(\mathbb{R}^{n}\right)$ and hence (see e.g. [St70]),

$$
\|\mathrm{M} g\|_{n /(n-1)} \leqq \mathrm{C}\|g\|_{n /(n-1)}
$$

Taking into account of (1.4), we deduce

$$
\int_{\mathrm{B}(a, \mathbf{R})} \mathrm{M} f d x \leqq \mathrm{C} \int_{\mathrm{B}(a, 2 \mathrm{R})}|\operatorname{adj} \mathrm{D} u|^{n /(n-1)} d x
$$

In view of (3.6) the proof is finished.

Lemma 3.4. - Let $p \geqq n-1, q \geqq \frac{n}{n-1}, u \in \mathrm{~A}_{p, q}(\Omega)$. Let $a \in \Omega$, for $\mathrm{L}^{1}$ a.e. $r \in\left(0, r_{a}\right)$ one has

$$
\begin{aligned}
\left\{\left|\int_{\mathrm{B}(a, r)} \operatorname{det} \mathrm{D} u d x\right|\right. & \}^{(n-1) / n} \\
& \leqq \mathrm{C} \int_{\mathrm{S}(a, r)}\left|\Lambda_{n-1} \mathrm{D} u\right| d \mathrm{H}^{n-1} \leqq \mathrm{C} \int_{\mathrm{S}(a, r)}|\operatorname{adj} \mathrm{D} u| d \mathrm{H}^{n-1}
\end{aligned}
$$

Proof. - This follows from Lemma 6.1 in [Mu90 b] and Theorem 3.2 above. To keep the current exposition self-contained, we sketch the proof. Fix $a \in \Omega$. We first claim that Theorem 3.2 implies that for all $v \in \mathrm{C}_{0}^{1}\left(\mathbb{R}^{n}, \mathbb{R}^{n}\right)$ and a.e. $r \in\left(0, r_{a}\right)$
$\int_{\mathbf{B}(a, r)}(\operatorname{div} v)(u(x)) \operatorname{det} \mathrm{D} u(x) d x=\int_{\mathrm{S}(a, r)}\left(v^{\circ} u\right) .\left(\Lambda_{n-1} \mathrm{D} u\right) \vee d \mathrm{H}^{n-1}$
Indeed by Theorem 3.2, one has for all $\psi \in \mathrm{C}_{0}^{\infty}(\Omega)$

$$
\int_{\Omega} \psi(\operatorname{div} v)(u(x)) \operatorname{det} \mathrm{D} u(x) d x=-\int_{\Omega}\left(v^{i} \circ u\right)(\operatorname{adj} \mathrm{D} u)_{i}^{j} \frac{\partial}{\partial x_{j}} \psi d x
$$

and choosing test functions $\psi^{(j)}(x)=\widetilde{\psi}^{(j)}(|x-a|)$ which approximate $\chi_{\mathrm{B}(a, r)}$, one easily shows (3.7) (see [Mu90 b], p. 30 for the details).

Secondly, we claim that there exists an integer-valued function $d$ such that for every continuous $g: \mathbb{R}^{n} \rightarrow \mathbb{R}$, one has

$$
\begin{equation*}
\int_{\mathrm{B}(a, r)} g(u(x)) \operatorname{det} \mathrm{D} u(x) d x=\int_{\mathbb{R}^{n}} g(y) d(y) d y . \tag{3.8}
\end{equation*}
$$

To see this, observe that $u$ is approximately differentiable on $\Omega \backslash E$, with $\mathrm{L}^{n}(\mathrm{E})=0$ (see [Mo66], Lemma 3.1.1 and [Fe69], 3.1.4) and hence by the area formula (see [Fe69], 3.25, 3.2.20 or [Sv88], Theorem 2) one has for every measurable set $A \subset \Omega \backslash E$

$$
\begin{equation*}
\int_{\mathbf{A}} g(u(x))|\operatorname{det} \mathrm{D} u(x)| d x=\int_{\mathbb{R}^{n}} g(y) \mathrm{N}(u, \mathrm{~A}, y) d y \tag{3.9}
\end{equation*}
$$

where $\mathrm{N}(u, \mathrm{~A}, y)$ denotes the number of elements in the set $\{x \in \mathrm{~A}: u(x)=y\}$. Let

$$
\mathrm{A}^{ \pm}=\{x \in \mathbf{B}(a, r): \pm \operatorname{det} \mathrm{D} u(x)>0\}
$$

and

$$
d(y)=\mathrm{N}\left(u, \mathrm{~A}^{+}, y\right)-\mathrm{N}\left(u, \mathrm{~A}^{-}, y\right) .
$$

Application of (3.9) to $\mathrm{A}^{+}$and $\mathrm{A}^{-}$yields (3.8).

Now let $r$ be such that (3.7) holds. Combining this with (3.8), we deduce that for all $v \in \mathbf{C}_{0}^{1}\left(\mathbb{R}^{n}, \mathbb{R}^{n}\right)$

$$
\left|\int_{\mathbb{R}^{n}}(\operatorname{div} v)(y) d(y) d y\right| \leqq\|v\|_{\mathrm{C}^{0}} \int_{\mathrm{S}(a, r)}\left|\Lambda_{n-1} \mathrm{D} u\right| d \mathrm{H}^{n-1} .
$$

Hence $d$ is of bounded variation and the Sobolev embedding (see e.g. [Gi84], Theorem 1.2.3) yields

$$
\|d\|_{\mathrm{L}^{n /(n-1)}} \leqq \mathrm{C}\|\mathrm{D} d\|_{\mathcal{M}} \leqq \mathrm{C} \int_{\mathrm{S}(a, r)}\left|\Lambda_{n-1} \mathrm{D} u\right| d \mathrm{H}^{n-1}
$$

Finally, apply (3.8) with $g \equiv 1$ and use the fact that $d$ is integer valued to deduce

$$
\begin{aligned}
\left|\int_{\mathrm{B}(a, r)} \operatorname{det} \mathrm{D} u d x\right|= & \left|\int_{\mathbb{R}^{n}} d d y\right| \leqq \int_{\mathbb{R}^{n}}|d|^{n /(n-1)} d y \\
& \leqq \mathrm{C}\left\{\int_{\mathrm{S}(a, r)}\left|\Lambda_{n-1} \mathrm{D} u\right| d \mathrm{H}^{n-1}\right\}^{n /(n-1)}
\end{aligned}
$$

## 4. APPLICATIONS TO NONLINEAR ELASTICITY

In this section, we establish existence of minimizers in nonlinear elasticity under weakened coercivity conditions on the integrand. We begin with the following weak continuity result.

Lemma 4.1. - Let $p \geqq n-1, q>\frac{n}{n-1}$ and let $u^{(v)}$ be a sequence in $\mathrm{A}_{p, q}(\Omega)$ satisfying

$$
u^{(v)} \rightharpoonup u \quad \text { in } \mathrm{W}^{1, p}\left(\Omega ; \mathbb{R}^{n}\right),
$$

$\operatorname{adj} \mathrm{D} u^{(v)}$ bounded in $\mathrm{L}^{q}\left(\Omega ; \mathbb{R}^{n \times n}\right)$.
Then

$$
\begin{gather*}
\operatorname{adj} \mathrm{D} u^{(v)} \rightharpoonup \operatorname{adj} \mathrm{D} u \quad \text { in } \mathrm{L}^{q}\left(\Omega ; \mathbb{R}^{n \times n}\right),  \tag{4.1}\\
\operatorname{det} \mathrm{D} u^{(v)} \rightharpoonup \operatorname{det} \mathrm{D} u \quad \text { in } \mathrm{L}^{s}(\Omega), \quad s=\frac{q(n-1)}{n} \tag{4.2}
\end{gather*}
$$

If $q=\frac{n}{n-1}$ and if $\operatorname{det} \mathrm{D} u^{(v)} \geqq 0$ a.e., then instead of (4.2), one has

$$
\operatorname{det} \mathrm{D} u^{(v)} \rightharpoonup \operatorname{det} \mathrm{D} u \quad \text { in } \mathrm{L}^{1}(\mathrm{~K})
$$

for all compact sets $\mathrm{K} \subset \boldsymbol{\Omega}$.
Proof. - Since $p \geqq n-1$ one has (see Ball [Ba77], Dacorogna [Da89], Chapter 4, Theorem 2.6)

$$
\operatorname{adj} \mathrm{D} u^{(v)} \rightharpoonup \operatorname{adj} \mathrm{D} u \quad \text { in } \mathrm{D}^{\prime}(\Omega) .
$$

By hypothesis adj $\mathrm{D} u^{(v)}$ is also bounded in $\mathrm{L}^{q}, q>1$. Hence the convergence is weakly in $\mathrm{L}^{q}$. To prove (4.2), consider the distribution

$$
\operatorname{Det} \mathrm{D} u^{(v)}:=\frac{1}{n} \frac{\partial}{\partial x^{j}}\left[\left(u^{(v)}\right)^{i}\left(\operatorname{adj} \mathrm{D} u^{(v)}\right)_{i}^{j}\right]
$$

Since $\frac{1}{p}+\frac{1}{q} \leqq \frac{1}{n-1}+\frac{n-1}{n}<1+\frac{1}{n}$, Det $\mathrm{D} u^{(v)}$ is well-defined by the Sobolev embedding theorem and using the compactness of the embedding and (4.1) one sees that

$$
\operatorname{Det} \mathrm{D} u^{(v)} \rightharpoonup \operatorname{Det} \mathrm{D} u \quad \text { in } \mathscr{D}^{\prime}(\Omega) .
$$

Now apply Theorem 3.2 with $g(y)=\frac{1}{n} y$ to deduce that

$$
\operatorname{det} \mathrm{D} u^{(v)}=\operatorname{Det} \mathrm{D} u^{(v)} \quad \text { and } \quad \operatorname{Det} \mathrm{D} u=\operatorname{det} \mathrm{D} u .
$$

If $q>\frac{n}{n-1}$, then $\operatorname{det} \mathrm{D} u$ is bounded in $\mathrm{L}^{s}(\Omega)(s>1)$ by (1.4); assertion (4.2) follows. If $q=\frac{n}{n-1}$ and $\operatorname{det} \mathrm{D} u^{(v)} \geqq 0$ a.e., the assertion follows by applying Theorem 3.3 in connection with Lemma 2.3.

Consider now an elastic body which occupies an open, bounded set $\Omega \subset \mathbb{R}^{3}$ (with Lipschitz boundary) in a reference configuration. Let $\partial \Omega_{1}$ be a subset of $\partial \Omega$ with positive two-dimensional measure. We assume that the deformation $u: \Omega \rightarrow \mathbb{R}^{3}$ is prescribed on $\partial \Omega_{1}$ while $\partial \Omega_{2}=\partial \Omega \backslash \partial \Omega_{1}$ is traction free. We seek to minimize the elastic energy

$$
\mathrm{I}(u)=\int_{\Omega} \mathrm{W}(x, u, \mathrm{D} u) d x
$$

in the function class

$$
\mathscr{A}=\left\{u \in \mathrm{~W}^{1,1}\left(\Omega ; \mathbb{R}^{3}\right): u=\bar{u} \text { on } \partial \Omega_{1}, \mathrm{I}(u)<\infty\right\} .
$$

We allow W to take the value $+\infty$ to incorporate the constraint $\operatorname{det} \mathrm{D} u>0$ which corresponds to the fact that the deformation is (locally) orientation preserving.

Theorem 4.2. - Assume that
(i) (polyconvexity)

$$
\mathrm{W}(x, u, \mathrm{~F})=g(x, u, \mathrm{~F}, \operatorname{adj} \mathrm{~F}, \operatorname{det} \mathrm{~F}),
$$

where $g(x, u,$.$) is convex;$
(ii) (continuity) $g(x, .,$.$) is continuous (as a function with values in$ $\overline{\mathbb{R}}=\mathbb{R} \cup\{+\infty\}), g(., u, F, \operatorname{adj} F, \operatorname{det} F)$ is measurable;
(iii) $\mathrm{W}(x, u, \mathrm{~F})=+\infty$ if and only if $\operatorname{det} \mathrm{F} \leqq 0$;
(iv) (coercivity)

$$
\mathrm{W}(x, u, \mathrm{~F}) \geqq a\left(|\mathrm{~F}|^{p}+|\operatorname{adj} \mathrm{F}|^{q}\right),
$$

where $a>0, p \geqq 2, q \geqq \frac{3}{2}$. Assume furthermore that $\mathscr{A} \neq \varnothing$. Then I attains its minimum on $\mathscr{A}$.

Proof. - Applying Lemma 4.1 to a minimizing sequence, this is by now standard (see [Ba77] or [Mu90b], Theorem 6.2).

The theorem improves results of Ball and Murat [BM84], Zhang [Zh90] and $\left[\mathrm{Mu} 90 b\right.$ ] which all require $q \geqq \frac{p}{p-1}$. Non-zero dead load traction conditions and other modification can be incorporated in the standard way (see [Ba77]).

## 5. REGULARITY AND INVERTIBILITY PROPERTIES

We use the divergence identities in Theorem 3.2 to generalise Šverák's degree formula to the class $\mathrm{A}_{p, q}(\Omega), p>n-1, q \geqq \frac{n}{n-1}$. Once this is done his results and proofs apply verbatim to our larger class. Here we only spell out some of these explicitly and refer the reader to [Sv88] for the details. Recall the definition of $\mathrm{A}_{p, q}(\partial \Omega)$ from (2.5).

Theorem 5.1 (degree formula). - Let $\Omega \subset \mathbb{R}^{n}$ be a bounded, open set with Lipschitz boundary, let $p \geqq n-1, q \geqq \frac{n}{n-1}$. Assume that $u \in \mathrm{~A}_{p, q}(\Omega)$ and that its trace belongs to $\mathrm{A}_{p, q}(\partial \Omega)$ and has a continuous representative $\bar{u}$. Let $y_{0} \in \mathbb{R}^{n} \backslash \bar{u}(\partial \Omega)$ and let $f$ be a bounded and smooth function supported in the component of $\mathbb{R}^{n} \backslash \bar{u}(\partial \Omega)$ which contains $y_{0}$. Then

$$
\begin{equation*}
\int_{\Omega}(f \circ u) \operatorname{det} \mathrm{D} u d x=\operatorname{deg}\left(u, \partial \Omega, y_{0}\right) \int_{\mathbb{R}^{n}} f d y . \tag{5.1}
\end{equation*}
$$

Remarks. -1 . If $p>n-1$ then the trace has a continuous representative by the Sobolev embedding theorem.
2. For the results discussed below it suffices to have the degree formula (5.1) for smooth domains. We stated the more general version with future applications in mind.

We postpone the proof of the theorem until the end of this section and first discuss some of its consequences. From now on, we assume that
$p>n-1, q \geqq \frac{n}{n-1}$. Šverák observed that if one considers functions in

$$
\mathrm{A}_{p, q}^{+}(\Omega)=\left\{u \in \mathrm{~A}_{p, q}(\Omega): \operatorname{det} \mathrm{D} u>0 \text { a.e. }\right\}
$$

then one can define a set-valued image $\mathrm{F}(a, u)$ for every point $a \in \Omega$. Indeed by Proposition 2.1 there is an $\mathrm{L}^{1}$ null set $\mathrm{N}_{a}$ such that for all $r \in\left(0, r_{a}\right) \backslash \mathrm{N}_{a}\left[\right.$ where $\left.r_{a}=\operatorname{dist}(a, \partial \Omega)\right]$ one has $u \in \mathrm{~A}_{p, q}(\partial \mathrm{~B}(a, r))$. Let $\bar{u}$ be the continuous representative of the trace (recall $p>n-1$ ) and let
$\mathrm{E}(u, \mathrm{~B}(a, r))=\left\{y \in \mathbb{R}^{n} \backslash u(\partial \mathbf{B}(a, r)): \operatorname{deg}(u, \partial \mathrm{~B}(a, r), y) \geqq 1\right\} \cup u(\partial \mathrm{~B}(a, r))$. Using (5.1), one verifies that

$$
\mathrm{E}(u, \mathrm{~B}(a, r)) \subset \mathrm{E}(u, \mathrm{~B}(a, s))
$$

if $r, s \in\left(0, r_{a}\right) \backslash \mathrm{N}_{a}, r<s($ see $[\mathrm{Sv88]}$, Lemma 3) and one defines

$$
\begin{gathered}
\mathrm{F}(a, u)=\bigcap_{r \in\left(0, r_{a}\right) \not \mathrm{N}_{a}} \mathrm{E}(u, \mathrm{~B}(a, r)), \\
\mathrm{F}(\mathrm{~A})=\cup\{\mathrm{F}(x): x \in \mathrm{~A}\}, \quad \text { if } \quad \mathrm{A} \subset \Omega .
\end{gathered}
$$

One has the following regularity results which are proved exactly as in [Sv88]. Similar results have recently been obtained by Manfredi [Ma92] using a different techniques. For $p=n$, the result was already proved by Vodopyanov and Goldstein [VG77].

Theorem 5.2 (cf. [Sv88], Theorem 4). - If $u \in \mathrm{~A}_{p, q}^{+}(\Omega)$ with $p>n-1$, $q \geqq \frac{n}{n-1}$, then $u$ has a representative $\tilde{u}$ which is continuous outside a set S of Hausdorff dimension $n-p$. Moreover, for each $\varepsilon>0$, the set $\{x \in \Omega, \lim \sup \operatorname{osc}(\tilde{u}, \mathrm{~B}(x, r))<\varepsilon\}$ is open.

$$
r \rightarrow 0^{+}
$$

Theorem 5.3 (cf. [Sv88], Theorem 6). - Let $u \in \mathrm{~A}_{p, q}^{+}(\Omega)$ with $p>n-1$, $q \geqq \frac{n}{n-1}$ and let F be the set function defined above. Then
(i) $\mathscr{H}^{n-1}(\mathrm{~F}(a))=0$ for each $a \in \Omega$.
(ii) For each measurable set $\mathrm{A} \subset \Omega$, the set $\mathrm{F}(\mathrm{A})$ is measurable and

$$
\mathrm{L}^{n}(\mathrm{~F}(\mathrm{~A})) \leqq \int_{\mathrm{A}} \operatorname{det} \mathrm{D} u d x
$$

In particular $L^{n}(F(S))=0$ where $S$ is the singular set in Theorem 5.2.
Similarly Šverák's results on the existence and regularity of an inverse function can be generalized to the case $q \geqq \frac{n}{n-1}$ (instead of $q \geqq \frac{p}{p-1}$ ). For detailed statements we refer the reader to section 5 of [Sv88], and in particular to Theorems 7 and 8. Also in the results of Tang Qi [TQ88] on
almost everywhere injectivity (which generalize earlier work of Ciarlet and Nečas [CN87]) one may now replace the condition $q \geqq \frac{p}{p-1}$ by $q \geqq \frac{n}{n-1}$.

Proof of Theorem 5.1. - We follow essentially Š̌erák's proof but use Theorem 3.2 to weaken the hypothesis on $q$. Assume first that $f \in \mathrm{C}_{0}^{\infty}\left(\mathbb{R}^{n}\right)$. This is no restriction of generality as long as $\operatorname{deg}\left(\bar{u}, \Omega, y_{0}\right) \neq 0$. Indeed $\mathbb{R}^{n} \backslash \bar{u}(\partial \Omega)$ contains only one unbounded component [since $\bar{u}(\partial \Omega)$ is compact] and the degree vanishes on that component (see [Sc69]). There exists $g \in \mathrm{C}^{\infty}\left(\mathbb{R}^{n} ; \mathbb{R}^{n}\right)$ satisfying

$$
\begin{gathered}
\operatorname{div} g=f \\
|g|(x)+|\mathrm{D} g(x)| \rightarrow 0 \quad \text { as }|x| \rightarrow \infty
\end{gathered}
$$

take e.g. $g_{i}=\mathrm{K}_{i} * f, \mathrm{~K}_{i}(z)=\frac{c_{n} z_{i}}{|z|^{n+2}}$.
By Lemma 2.2 we have

$$
\operatorname{deg}\left(\bar{u}, \partial \Omega, y_{0}\right) \int_{\mathbb{R}^{n}} f d y=\int_{\partial \Omega}(g \circ u) \cdot\left(\Lambda_{n-1} \mathrm{D} \bar{u}\right) \vee d \mathrm{H}_{n-1}
$$

We claim that for all $\psi \in \mathrm{C}_{0}^{\infty}\left(\mathbb{R}^{n}\right)$,

$$
\begin{align*}
& \int_{\partial \Omega} \psi(g \circ u) \cdot\left(\Lambda_{n-1} \mathrm{D} u\right) v d \mathrm{H}_{n-1} \\
& \quad=\int_{\Omega}\left\{\left(\frac{\partial}{\partial x^{j}} \psi\right)(g \circ u)(\operatorname{adj} \mathrm{D} u)_{i}+\psi(f \circ u) \operatorname{det} \mathrm{D} u\right\} d x \tag{5.2}
\end{align*}
$$

Taking into account of Lemma 2.2, the theorem follows by applying (5.2) to a $\psi$ with $\left.\psi\right|_{\bar{\Omega}} \equiv 1$. By a partition of unity it suffices to consider two cases. Either $\psi$ is supported in a neighbourhood of the boundary represented by a Lipschitz chart (cf. the definition of sets with Lipschitz boundary in section 2) or $\psi \in \mathrm{C}_{0}^{\infty}(\Omega)$. The latter case is the content of Theorem 3.2. To deal with the former, we follow Šverák's idea to extend $u$ outside $\Omega$. To obtain the result for Lipschitz boundaries, we first have to "flatten" the boundary.

After changing coordinates it suffices to consider the following situation. Let $x=\left(x^{\prime}, x^{n}\right), \Delta=(-\alpha, \alpha)^{n-1}$, let $a: \Delta \rightarrow \mathbb{R}$ be Lipschitz and consider

$$
\Omega^{\prime}=\left\{x \in \Delta \times \mathbb{R}: x_{n}>a\left(x^{\prime}\right)\right\}, \quad \Gamma^{\prime}=\left\{x \in \Delta \times \mathbb{R}: x_{n}=a\left(x^{\prime}\right)\right\} .
$$

Assume that $u \in \mathrm{~A}_{p, q}\left(\Omega^{\prime}\right)$ and that $\bar{u}=\left.u\right|_{\Gamma^{\prime}}$ belongs to $\mathrm{A}_{p, q}\left(\Gamma^{\prime}\right)$. Let $\psi \in \mathrm{C}_{0}^{\infty}(\Delta \times \mathbb{R})$. We have to show that

$$
\begin{align*}
& \int_{\Gamma^{\prime}} \psi(g \circ \bar{u}) \cdot\left(\Lambda_{n-1} \mathrm{D} \bar{u}\right) v d \mathrm{H}_{n-1} \\
& \quad=\int_{\Omega^{\prime}}\left\{\left(\frac{\partial}{\partial x^{j}} \psi\right)\left(g^{i} \circ u\right)(\operatorname{adj} \mathrm{D} u)_{i}^{j}+\psi(f \circ u) \operatorname{det} \mathrm{D} u\right\} d x \tag{5.3}
\end{align*}
$$

To transform the problem to a region with a flat boundary, consider

$$
\Phi\left(y^{\prime}, y^{n}\right)=\left(y^{\prime}, a\left(y^{\prime}\right)+y^{n}\right)
$$

Note that $\Phi$ is a bi-Lipschitz map of $\Delta \times \mathbb{R}$ to itself. Let

$$
v=u^{\circ} \Phi, \quad \bar{v}=\left.\bar{u} \circ \Phi\right|_{\Delta}, \quad \eta=\psi \circ \Phi
$$

Using the chain rule (here we use the fact that $\Phi$ has a Lipschitz inverse, see Proposition 2.5) and the identity $\operatorname{adj}(A B)=(\operatorname{adj} B)(\operatorname{adj} A)$, one easily verifies that

$$
v \in \mathrm{~A}_{p, q}\left(\Delta \times \mathbb{R}_{+}\right), \quad \bar{v} \in \mathrm{~A}_{p, q}(\Delta)
$$

Moreover,

$$
\operatorname{det} \mathrm{D} v=(\operatorname{det} \mathrm{D} u)^{\circ} \Phi \operatorname{det} \mathrm{D} \Phi
$$

and

$$
\begin{aligned}
(\operatorname{adj} \mathrm{D} v)_{i}^{j}\left(\frac{\partial}{\partial y^{j}} \eta\right) & =(\operatorname{adj} \mathrm{D} \Phi)_{k}^{j}(\operatorname{adj} \mathrm{D} u)_{i}^{k} \circ \Phi\left(\frac{\partial}{\partial x^{l}} \psi\right) \circ \Phi(\mathrm{D} \Phi)_{j}^{l} \\
& =\left[(\operatorname{adj} \mathrm{D} u)_{i}^{l} \frac{\partial}{\partial x^{l}} \psi\right] \circ \Phi \operatorname{det} \mathrm{D} \Phi .
\end{aligned}
$$

Hence by the area formula (see [Fe69], Theorem 3.2.5; [Si83], 8.4 or [EG91], Section 3.3), the right-hand side of (5.3) is equal to

$$
\begin{equation*}
\int_{\Delta \times \mathbb{R}_{+}}\left\{\left(\frac{\partial}{\partial y^{j}} \eta\right)\left(g^{i} \circ v\right)(\operatorname{adj} \mathrm{D} v)_{i}^{j}+\eta(f \circ v) \operatorname{det} \mathrm{D} v\right\} d y \tag{5.4}
\end{equation*}
$$

Let $v$ be the outer unit normal of $\Gamma^{\prime}$. Taking into account that

$$
\begin{aligned}
\left(\Lambda_{n-1} \mathrm{D} \bar{v}\right) e_{n} & \left.=\left[\Lambda_{n-1}\left(\left.\mathrm{D} \bar{u} \circ \Phi \mathrm{D} \Phi\right|_{\Delta}\right)\right] e_{n}\right]=\left(\Lambda_{n-1} \mathrm{D} \bar{u}\right) \circ \Phi\left[\left(\left.\Lambda_{n-1} \mathrm{D} \Phi\right|_{\Delta}\right) e_{n}\right] \\
& =-\left(\Lambda_{n-1} \mathrm{D} \bar{u}\right) \circ \Phi\left(1+|\mathrm{D} a|^{2}\right)^{1 / 2} v
\end{aligned}
$$

and observing that $\left(1+|\mathrm{D} a|^{2}\right)^{1 / 2}$ is the area element of $\Gamma^{\prime}$, one finds, by another application of the area formula,

$$
\begin{equation*}
\int_{\Gamma^{\prime}} \psi(g \circ \bar{u}) \cdot\left(\Lambda_{n-1} \mathrm{D} \bar{u}\right) v d \mathrm{H}_{n-1}=-\int_{\Delta} \eta(g \circ \bar{v}) \cdot \Lambda_{n-1}(\mathrm{D} \bar{v}) e_{n} d x^{\prime} \tag{5.5}
\end{equation*}
$$

It only remains to show that the right-hand side of (5.5) equals (5.4). To this end extend $v$ to $\Delta \times \mathbb{R}$ by letting

$$
v\left(y^{\prime}, y^{n}\right)=\bar{v}\left(y^{\prime}\right) \quad \text { if } \quad y^{n}<0
$$

Clearly $v \in \mathbf{W}_{\text {loc }}^{1, p}(\Delta \times \mathbb{R})$ since $\bar{v} \in \mathbf{W}^{1, p}(\Delta)$. Moreover using (2.3) one has for $y^{n}<0$,

$$
\left.\begin{array}{rlrl}
(\operatorname{adj} \mathrm{D} v)_{i}^{n} & =\left[\left(\Lambda_{n-1} \mathrm{D} \bar{v}\right) e_{n}\right]^{i}  \tag{5.6}\\
(\operatorname{adj} \mathrm{D} v)_{i}^{j} & =0 & \text { if } & j \neq n, \\
\operatorname{det} \mathrm{D} v & =0 .
\end{array}\right\}
$$

Hence $v \in \mathrm{~A}_{p, q}(\Delta \times \mathbb{R})$. Application of Theorem 3.2 gives

$$
\int_{\Delta \times \mathbb{R}}\left\{\left(\frac{\partial}{\partial y^{j}} \tilde{\eta}\right)\left(g^{i} \circ v\right)(\operatorname{adj} \mathrm{D} v)_{i}^{j}+\tilde{\eta}(f \circ v) \operatorname{det} \mathrm{D} v\right\} d x=0
$$

for all $\tilde{\eta} \in C_{0}^{\infty}(\Delta \times \mathbb{R})$. By approximation, the same holds for $\tilde{\eta} \in W_{0}^{1, \infty}(\Delta \times \mathbb{R})$. Now let

$$
\tilde{\eta}\left(y^{\prime}, y^{n}\right)=\left\{\begin{array}{cc}
\eta\left(y^{\prime}, y^{n}\right), & 0 \leqq y_{n} \\
\left(1+y^{n}\right) \eta\left(y^{\prime}, 0\right), & -1 \leqq y_{n}<0 \\
0, & y_{n}<-1
\end{array}\right.
$$

Taking into account (5.6) one deduces that the right-hand side of (5.5) is equal to (5.4). This finishes the proof if $f \in \mathrm{C}_{0}^{\infty}\left(\mathbb{R}^{n}\right)$.

Now assume that $f \in \mathrm{C}^{\infty}\left(\mathbb{R}^{n}\right) \cap \mathrm{L}^{\infty}\left(\mathbb{R}^{n}\right)$ and that $f$ does not have compact support. Then $y_{0}$ lies in the unbounded component of $\mathbb{R}^{n} \backslash \bar{u}(\partial \Omega)$ and hence $\operatorname{deg}\left(\bar{u}, y_{0}, \partial \Omega\right)=0$. It remains to show that the left-hand side of (5.1) vanishes.

Consider cut-off functions $\varphi_{j} \in \mathrm{C}_{0}^{\infty}\left(\mathbb{R}^{n}\right)$ such that $\varphi_{j}(x)=1$ if $|x| \leqq j$ and let $f_{j}=\varphi_{j} f$. As $f_{j} \in \mathrm{C}_{0}^{\infty}\left(\mathbb{R}^{n}\right)$ by the result above

$$
\int_{\Omega}\left(f_{j}^{\circ} u\right)(\operatorname{det} \mathrm{D} u) d x=0 .
$$

Thus

$$
\left|\int_{\Omega}(f \circ u) \operatorname{det} \mathrm{D} u d x\right| \leqq\|f\|_{\infty} \int_{|u| \geqq j}|\operatorname{det} \mathrm{D} u| d x
$$

Since $q \geqq \frac{n}{n-1}$, we have $\operatorname{det} \mathrm{D} u \in \mathrm{~L}^{1}(\Omega)$ by (1.4). Moreover, because $|\{x \in \Omega:|u(x)| \geqq j\}| \rightarrow 0$ as $j \rightarrow \infty$,

$$
\int_{\Omega}(f \circ u) \operatorname{det} \mathrm{D} u d x=0
$$

as claimed.

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